

Q.2.61.b) Consider current  $i(t)$  flowing through the circuit.

Applying KVL we get,

$$x(t) = Ri(t) + \frac{1}{C} \int i dt.$$

Differentiating both sides with respect to  $t$ ,

$$\frac{dx(t)}{dt} = R \frac{di(t)}{dt} + \frac{1}{C} i(t) \quad \text{--- (1)}$$

Natural response of the system is obtained by setting  $x(t)=0$  i.e. no input given to the system,

$$\therefore \frac{dx(t)}{dt} = 0$$

$$\Rightarrow R \frac{di(t)}{dt} + \frac{1}{C} i(t) = 0$$

$$\Rightarrow R \frac{di(t)}{dt} = -\frac{1}{C} i(t)$$

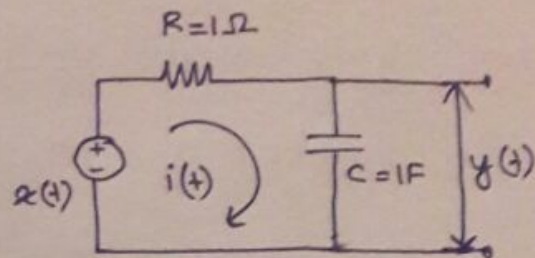
$$\Rightarrow \frac{di(t)}{dt} = -\frac{1}{RC} i(t) \quad \text{--- (2)}$$

Integrating both sides,

$$\Rightarrow i(t) = e^{-1/RC \cdot t}$$

$$\therefore k e^{-at} = e^{-1/RC \cdot t}$$

$$\therefore k=1 \text{ and } a = \frac{1}{RC} = \frac{1}{1 \cdot 1} \quad [ \because R=1\Omega, C=1F ] \Rightarrow a=1.$$



$$\text{Q.17i)} \quad y[n] = \text{Real} \{ x[n] \}$$

$$\text{Suppose } y = a + jw \quad \therefore \text{Real}[y] = a$$

$$\text{For input } x_1[n], \text{ output } y_1[n] = \text{Real} \{ x_1[n] \}$$

$$\text{For input } x_2[n], \text{ output } y_2[n] = \text{Real} \{ x_2[n] \}$$

For input  $x_1[n] + x_2[n]$ ,

$$y[n] = \text{Real} \{ x_1[n] + x_2[n] \}$$

$$= \text{Real} \{ x_1[n] \} + \text{Real} \{ x_2[n] \}$$

$$= y_1[n] + y_2[n]$$

$\therefore$  The system is additive.

For input  $kx[n]$ , the output

$$y_k[n] = \text{Real} \{ kx[n] \} = k \text{Real} \{ x[n] \} = ky[n]$$

$\therefore$  The system is homogeneous.



$$\text{Q.17ii)} \quad y(t) = \frac{1}{x(t)} \left[ \frac{dx(t)}{dt} \right]^2$$

$$\text{For input } x_1(t), \text{ the output } y_1(t) = \frac{1}{x_1(t)} \left[ \frac{dx_1(t)}{dt} \right]^2$$

$$\text{For input } x_2(t), \text{ the output } y_2(t) = \frac{1}{x_2(t)} \left[ \frac{dx_2(t)}{dt} \right]^2$$

For input  $x_1(t) + x_2(t)$ , the output,

$$y(t) = \frac{1}{x_1(t) + x_2(t)} \left[ \frac{d}{dt} (x_1(t) + x_2(t)) \right]^2$$

$$\neq y_1(t) + y_2(t)$$

$\therefore$  The system is not additive.

For input  $kx(t)$ , the output

$$y_k(t) = \frac{1}{kx(t)} \left[ \frac{d(kx(t))}{dt} \right]^2$$

$$= k \cdot \frac{1}{x(t)} \left[ \frac{dx(t)}{dt} \right]^2$$

$$= ky(t)$$

$\therefore$  The system is homogeneous.

$$\text{Q.17.iii)} \quad y[n] = \frac{x[n] x[n-2]}{x[n-1]} \quad x[n-1] \neq 0$$

$$= 0 \quad x[n-1] = 0$$

For input  $x_1[n]$ , output  $y_1[n] = \frac{x_1[n] x_1[n-2]}{x_1[n-1]}$

For input  $x_2[n]$ , output  $y_2[n] = \frac{x_2[n] x_2[n-2]}{x_2[n-1]}$

For input  $x_1[n] + x_2[n]$ , output

$$y[n] = \frac{(x_1[n] + x_2[n]) (x_1[n-2] + x_2[n-2])}{(x_1[n-1] + x_2[n-1])}$$

$$\neq y_1[n] + y_2[n]$$

$\therefore$  The system is not additive.

For input  $kx[n]$ , the output

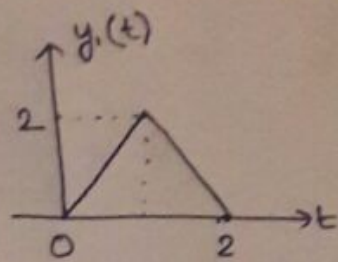
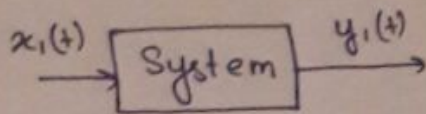
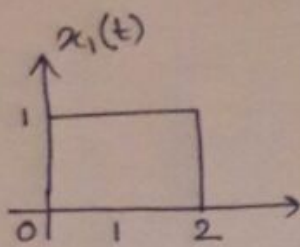
$$y_k[n] = \frac{kx[n] \cdot kx[n-2]}{kx[n-1]}$$

$$= k \cdot \left[ \frac{x[n] x[n-2]}{x[n-1]} \right]$$

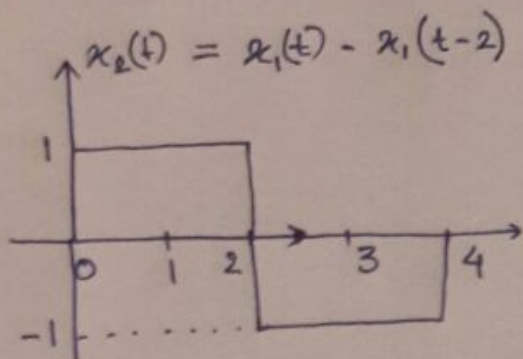
$$= ky[n]$$

$\therefore$  The system is homogeneous.

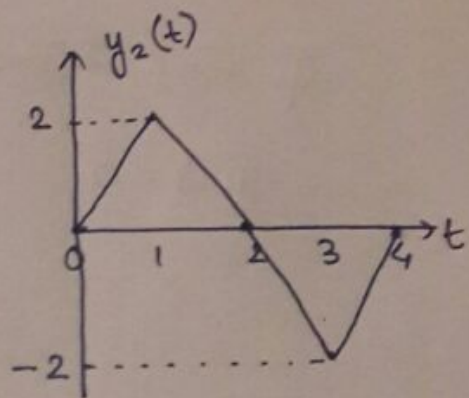
Q.20.a)



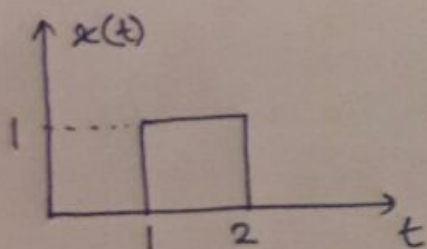
Input



System



b) If input  $x(t) = u(t)$  then  $y(t) = e^{-t}u(t) + u(-1-t)$



$$\therefore x(t) = u(t-1) - u(t-2)$$

For input  $x(t) = u(t-1) - u(t-2)$

$$\begin{aligned} \text{output } y(t) &= e^{-t}[u(t-1) - u(t-2)] + [u(-1-(t-1)) - u(-1-(t-2))] \\ &= e^{-t}[u(t-1) - u(t-2)] + [u(-t) - u(-t+1)] \end{aligned}$$

