

Practice Problems

Linear algebra.

(1) Consider $P_3 := \left\{ a_0 + a_1x + a_2x^2 + a_3x^3 \right\}$
 $a_0, a_1, a_2, a_3 \in \mathbb{R}$

be a set of polynomials of degree ≤ 3

A particular basis for this space is

$B_3 = \{1, x, x^2, x^3\}$. A derivative

map $\frac{d}{dx} : P_3 \rightarrow P_3$ is a linear map

and can be expressed on B_3 as

$$A = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 3 \\ 0 & 0 & 0 & 0 \end{bmatrix}.$$

Let $B_0 = \{1, x, 2x^2 - 1, 4x^3 - 3x\}$

be a new basis. Express $\frac{d}{dx}$ as a

linear map in this new basis.

Q.2 Consider a ~~matrix~~ linear map

$A: \mathbb{R}^5 \rightarrow \mathbb{R}^5$, let $b \in \mathbb{R}^5$ be a column vector. ^{Suppose it is} ~~It is~~ known that

$$A^5 + A^4 + A^3 + A^2 + A + I = 0.$$

Also the set $\{b, Ab, A^2b, \dots, A^4b\}$ contains linearly independent vectors.

Find matrix A by selecting a suitable basis.

Q.3: Given $A = \left[\begin{array}{ccc|cc} 1 & 101 & \pi & 1 & \pi \\ 1001 & 999 & e & e^2 & \pi^{1.5} \\ 159 & \frac{17\sqrt{5}}{2} & \frac{1-\sqrt{5}}{2} & e^3 & e^\pi \\ \hline 0 & 0 & 0 & -1 & \pi e \\ 0 & 0 & 0 & \sqrt{13} & \sqrt{3} \end{array} \right]$

Find an A -invariant subspace. Write basis for it.

Q.4 Let $A \in \mathbb{R}^{n \times n}$ be a matrix. Show that if λ is an eigenvalue of matrix A , then for any polynomial $p(x)$, $p(\lambda)$ is an eigenvalue of $p(A)$. Moreover if v is eigenvector of A corresponding to eig. val. λ , then

v is also an eigenvector of $p(A)$
corresponding to eigenvalue $p(\lambda)$.

Q. 5 Defⁿ 1: [Monic Polynomial]

~~Q. 5~~ A polynomial $p(\lambda) \in \mathbb{R}[\lambda]$ is called
monic if its leading coefficient is 1.

Defⁿ 2: [Minimal polynomial of A , (m.p. of A)]

The least degree monic polynomial
 $p(\lambda)$ s.t. $p(A) = 0$ is called as
the "minimal polynomial" of A .

Note characteristic polynomial of A

$$\pi(\lambda) = \det(\lambda I - A).$$

In general, $p(\lambda) \neq \pi(\lambda)$.

(i) Show that $p(\lambda)$ divides $\pi(\lambda)$

(ii) Show that $\deg \pi(\lambda) = n$, $\deg p(\lambda) \leq \deg \pi(\lambda)$

(iii) For $A = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 2 & 1 \\ 0 & 0 & 2 \end{bmatrix}$, find the

minimal polynomial and characteristic
polynomial of A .

Q.6. Let $A = \begin{bmatrix} 0 & 1 & 1 & 0 \\ 1 & 0 & 0 & 1 \\ 0 & 1 & -1 & 0 \\ 1 & 0 & 0 & -1 \end{bmatrix}$, $b = \begin{bmatrix} 0 \\ 1 \\ 1 \\ 1 \end{bmatrix}$

Generate vectors $b, Ab, A^2b, A^3b, A^4b, A^5b$

It is clear ~~show~~ that

$$\text{Span}\{b\} \subset \text{Span}\{b, Ab\} \subset \text{Span}\{b, A^2b, A^2b\} \\ \subset \dots \subset \text{Span}\{b, Ab, A^2b, A^3b, \dots, A^5b\}$$

Find ~~minimum~~ minimum k s.t

$$\text{Span}\{b, Ab, \dots, A^k b\} = \text{Span}\{b, Ab, \dots, A^k b, A^{k+1} b\} \\ = \text{Span}\{b, Ab, A^2b, \dots, A^{k+1} b\}.$$

~~Let k be the min~~

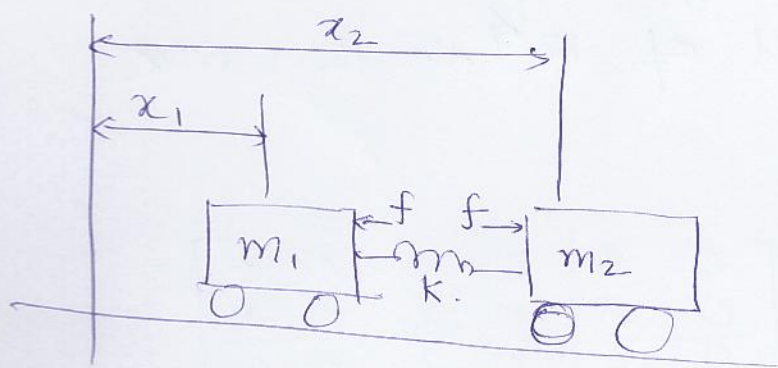
Show that this implies that

$b, Ab, A^2b, \dots, A^{k+1}b$ are linearly dependent.

Find linear dependence ^{relation} among them.

Reachable space.

Q. 1



$$\begin{aligned} m_1 \ddot{x}_1 + k(x_1 - x_2) + f &= 0 \\ m_2 \ddot{x}_2 + k(x_2 - x_1) + f &= 0 \end{aligned}$$

Example from
Control system design
B. Friedland Chapter 5
many more such
examples!

$$x = \begin{bmatrix} x_1 \\ \dot{x}_1 \\ x_2 \\ \dot{x}_2 \end{bmatrix}, \quad u = f$$

$$\dot{x} = \begin{bmatrix} \dot{x}_1 \\ \ddot{x}_1 \\ \dot{x}_2 \\ \ddot{x}_2 \end{bmatrix} = \begin{bmatrix} 0 & 1 & 0 & 0 \\ -k/m_1 & 0 & k/m_1 & 0 \\ 0 & 0 & 0 & 1 \\ k/m_2 & 0 & -k/m_2 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ \dot{x}_1 \\ x_2 \\ \dot{x}_2 \end{bmatrix} + \begin{bmatrix} 0 \\ -1/m_1 \\ 0 \\ -1/m_2 \end{bmatrix} u$$

$$A = \begin{bmatrix} 0 & 1 & 0 & 0 \\ -k/m_1 & 0 & k/m_1 & 0 \\ 0 & 0 & 0 & 1 \\ k/m_2 & 0 & -k/m_2 & 0 \end{bmatrix}, \quad B = \begin{bmatrix} 0 \\ -1/m_1 \\ 0 \\ -1/m_2 \end{bmatrix}$$

- (i) Find Reachable Space \mathcal{W}
- (ii) Check if $\mathcal{W} = \mathbb{R}^n$
- (iii) If $\mathcal{W} \subsetneq \mathbb{R}^n$ (i.e. strict subset) then use similarity Transform. decompose (A, B) into controllable \triangleright uncontrollable part

parts.

(iv) Explain physically why Reachable space is not all of \mathbb{R}^4 . in this case

Matrix Exponential.

Q.2 Let $A = \left[\begin{array}{cc|cccc} 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ \hline 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 \end{array} \right]$

Find e^{At} .

Q.3 Let $A = \left[\begin{array}{c|c} A_{11} & 0 \\ \hline 0 & A_{22} \end{array} \right]$

Show that $e^{At} = \left[\begin{array}{c|c} e^{A_{11}t} & 0 \\ \hline 0 & e^{A_{22}t} \end{array} \right]$

Q.4 Let A, B be such that $AB = BA$.

Show that $e^{A+B} = e^A e^B$

Q.5 $A = \left[\begin{array}{cc|cc} 2 & -3 & 1 & 0 \\ 3 & 2 & 0 & 1 \\ \hline 0 & 0 & 2 & -3 \\ 0 & 0 & 3 & 2 \end{array} \right]$, Compute e^{At} .