

ELL333

MULTIVARIABLE CONTROL

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Scalar Case

$$\dot{x} = a x, \quad x(0) \Rightarrow x(t) = x(0) e^{at}$$

General Case

$$\dot{x} = A x, \quad x(0) \Rightarrow x(t) = ?$$

\swarrow matrix
 \nwarrow vector

defined matrix exponential

$$e^{At} = I + At + \frac{A^2 t^2}{2!} + \dots + \frac{A^k t^k}{k!} + \dots$$

$$\dot{x} = A x, \quad x(0) = \begin{bmatrix} x_1(0) \\ x_2(0) \\ \vdots \\ x_n(0) \end{bmatrix}_{n \times 1}, \quad e^{At} = \begin{bmatrix} & & & \\ & & & \\ & & & \\ & & & \end{bmatrix}_{n \times n}$$

How to combine to get solution?

$$x(t) = \underbrace{\alpha}_{n \times 1} e^{At} \quad \leftarrow \text{careful about dimensions}$$

\uparrow
 $n \times 1$

$x(0)$

$$\underbrace{x(0)^T}_{1 \times n} e^{At}$$

$$e^{At} x(0) \rightarrow \text{solution?}$$

Claim: Solution of $\dot{x} = Ax, x(0)$ is $x(t) = e^{At} x(0)$

How to check if this is solution?

at $t=0$, $x(t) = e^{At} x(0) = \underbrace{e^{A \cdot 0}}_{\textcircled{I} + A \cdot 0 + \frac{A \cdot 0^2}{2!} + \dots} x(0) = x(0)$

does it satisfy $\dot{x} = Ax$
 $\dot{x} = \frac{d}{dt} x = \left[\frac{d}{dt} e^{At} \right] x(0)$

$$e^{At} = I + tA + \frac{t^2}{2!} A^2 + \dots + \frac{t^R}{R!} A^R + \dots$$

$$\frac{d}{dt} e^{At} = 0 + A + tA^2 + \dots + \frac{t^{R-1}}{(R-1)!} A^R + \dots$$

$$= A \left[I + tA + \dots + \frac{t^{R-1}}{(R-1)!} A^{R-1} + \dots \right]$$

$$= A e^{At}$$

$$\dot{x} = A \left[e^{At} x(0) \right] \rightarrow x(t)$$

This is the 'existence' part. Solution exists!
 What about 'uniqueness'?

Try Suppose two solutions $x_1, x_2, x_1 \neq x_2$

$x_1(t) = e^{At} x_1(0)$ and $x_2(t) = e^{At} x_2(0)$
 $\dot{x}_1 = Ax_1$ and $\dot{x}_2 = Ax_2$

define $y = x_1 - x_2, y(0) = 0$

$$\dot{y} = \dot{x}_1 - \dot{x}_2 = Ax_1 - Ax_2 = A(x_1 - x_2) = Ay$$

$$\Rightarrow \dot{y} = Ay \Rightarrow y(t) = e^{At} \cdot y(0) = 0$$

$$\Rightarrow x_1(t) = x_2(t) \rightarrow \text{solution is unique.}$$

$$\dot{y} = Ay, y(0) = 0.$$

What is the equilibrium point of the system $\dot{y} = Ay$?

$\Rightarrow y = 0$ or any $y \in \text{nullspace}(A)$

\hookrightarrow one way of showing $y(t) = 0$

$\Rightarrow x_1(t) = x_2(t)$

Solution of $\dot{x} = Ax, x(0)$ is
 $x(t) = e^{At} x(0)$.

How to compute e^{At} ?

For what matrices is e^{At} easy to compute?

Diagonal matrices

$$\begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix}, \begin{bmatrix} \lambda_1 & 0 & 0 & \dots & 0 \\ 0 & \lambda_2 & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \dots & \lambda_n \end{bmatrix}$$

What is $e^{(\downarrow)t}$ = $\begin{bmatrix} e^{\lambda_1 t} & 0 \\ 0 & e^{\lambda_2 t} \end{bmatrix}$

$$A = \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix}, A^2 = \begin{bmatrix} \lambda_1^2 & 0 \\ 0 & \lambda_2^2 \end{bmatrix}, \dots, A^k = \begin{bmatrix} \lambda_1^k & 0 \\ 0 & \lambda_2^k \end{bmatrix}$$

$$e^{At} = I + At + \frac{A^2 t^2}{2!} + \dots + \frac{A^k t^k}{k!} + \dots$$

$$= \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} + \begin{bmatrix} \lambda_1 t & 0 \\ 0 & \lambda_2 t \end{bmatrix} + \begin{bmatrix} \lambda_1^2 t^2 / 2! & 0 \\ 0 & \lambda_2^2 t^2 / 2! \end{bmatrix} + \dots + \begin{bmatrix} \lambda_1^k t^k / k! & 0 \\ 0 & \lambda_2^k t^k / k! \end{bmatrix} + \dots$$

$$= \begin{bmatrix} 1 + \lambda_1 t + \frac{\lambda_1^2 t^2}{2!} + \dots + \frac{\lambda_1^{k+1} t^{k+1}}{(k+1)!} + \dots & 0 \\ 0 & 1 + \lambda_2 t + \frac{\lambda_2^2 t^2}{2!} + \dots + \frac{\lambda_2^{k+1} t^{k+1}}{(k+1)!} + \dots \end{bmatrix}$$

$$= \begin{bmatrix} e^{\lambda_1 t} & 0 \\ 0 & e^{\lambda_2 t} \end{bmatrix}$$

$$A = \begin{bmatrix} 0 & \omega \\ -\omega & 0 \end{bmatrix}$$

$$e^{At} = ?$$

$$A = \begin{bmatrix} \lambda & 1 \\ 0 & \lambda \end{bmatrix}$$

\leadsto Jordan Canonical Form.

$$e^{At} = ?$$