

MULTIVARIABLE CONTROL

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DYNAMICS > MATRIX EXPONENTIAL

Example: $\ddot{x} = u$, $x(0), \dot{x}(0)$

'Double Integrator'

For $u=0$, $\ddot{x}=0$, $x(0)$, $\dot{x}(0)$

So what is the solution?

$$\frac{d}{dt} \dot{x} = 0 \xrightarrow{\text{INTEGRATE}} \dot{x}(t) = \text{a constant, whose value is } \dot{x}(0) \text{ by initial condition}$$

Now, $\frac{dx}{dt} = \dot{x}(0)$

$$\xrightarrow{\text{INTEGRATE}} x(t) = \dot{x}(0)t + \text{another constant, whose value is } x(0)$$

$\Rightarrow x(t) = \dot{x}(0)t + x(0)$ ← solution from direct integration
This is one way to find solution.

Another way is to convert into a state-space representation and use matrix exponential.

STATE SPACE of $\ddot{x} = u$ $\rightarrow x_1 = x, x_2 = \dot{x}$

$$\left[\begin{array}{c} \frac{d}{dt} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \end{array} \right] = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} 0 \\ 1 \end{bmatrix} u$$

↳ Solution of homogeneous part. using matrix exponential is $e^{At} \begin{bmatrix} x(0) \\ \dot{x}(0) \end{bmatrix}$, $A = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}$

What is e^{At} ?

$$e^{At} = I + At + A^2 \frac{t^2}{2!} + \dots + A^k \frac{t^k}{k!} + \dots$$

$$A = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, A^2 = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

$$e^{At} = I + At = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} + \begin{bmatrix} 0 & t \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} 1 & t \\ 0 & 1 \end{bmatrix}$$

$$\text{solution} = e^{At} \begin{bmatrix} x(0) \\ \dot{x}(0) \end{bmatrix} = \begin{bmatrix} 1 & t \\ 0 & 1 \end{bmatrix} \begin{bmatrix} x(0) \\ \dot{x}(0) \end{bmatrix} \\ = \begin{bmatrix} x(0) + \dot{x}(0) \cdot t \\ \dot{x}(0) \end{bmatrix}$$

$$\Rightarrow \underline{x_1(t) = x(0) + \dot{x}(0)t}$$

→ matches the solution obtained from direct integration.

$$\text{Consider } A = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}.$$

This has two eigenvalues, both are '0'

What are the corresponding eigenvectors?

$$\hookrightarrow \text{eigenvector is } \begin{bmatrix} 1 \\ 0 \end{bmatrix} \quad A - \lambda I = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}$$

Recall definition: $\vec{v} (\neq 0)$ is an eigenvector of $n \times n$ matrix A with eigenvalue λ if $A\vec{v} = \lambda\vec{v}$

$$\text{Consider } A = \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix}$$

eigenvalues :

$$\begin{bmatrix} 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

eigenvectors:

Two eigenvectors, with repeated eigenvalues

What about $A = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$

eigenvalues: '1', '1'

eigenvectors: $\begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix}$

$$Av = 1v$$

$$(A - 1I)v = 0$$

$$A - 1I$$

$$\Rightarrow A = I, A = I$$

$$\begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

Going back to red example,

$$A = \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix}$$

eigenvalues : 1, 0

eigenvectors: $\begin{bmatrix} 1 \\ -1 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \end{bmatrix}$

How to diagonalize this?

$$A = \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix}$$

Co-ordinate
transformation
 T
 2×2

diagonal
 $\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$

T is related to eigenvectors

$$T = ?$$