

ELL333 QUIZ 4 MARKS=7 DURATION=20 min

NAME = \_\_\_\_\_, ENTRY NUMBER = \_\_\_\_\_

Q. Consider the system  $\dot{x} = Ax + Bu$ , where

$$A = \begin{bmatrix} \lambda_1 & 0 & 0 \\ 0 & \lambda_2 & 0 \\ 0 & 0 & \lambda_3 \end{bmatrix} \begin{matrix} \lambda_1 \neq \lambda_2 \\ \lambda_1 \neq \lambda_3 \\ \lambda_2 \neq \lambda_3 \end{matrix}, \quad B = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix}. \quad \text{Suppose } u = -Kx. \quad \text{(state feedback)}$$

- a) What is the condition on  $b_1, b_2, b_3$  for the eigenvalues of the system with state feedback to be placed at arbitrarily locations through suitable choice of  $K$ ?
- b) Based on a), give a generalized statement for when  $A$  is a  $n \times n$  diagonal matrix with distinct eigenvalues and  $B$  is an  $n \times 1$  column vector with  $j^{\text{th}}$  element  $b_j, j=1, 2, \dots, n$

A. The condition for the eigenvalues to be placed at arbitrary locations is

$$\text{rank} \begin{bmatrix} B & AB & A^2 B \end{bmatrix} = n$$

$$\Rightarrow \text{rank} \left( \underbrace{\begin{bmatrix} b_1 & \lambda_1 b_1 & \lambda_1^2 b_1 \\ b_2 & \lambda_2 b_2 & \lambda_2^2 b_2 \\ b_3 & \lambda_3 b_3 & \lambda_3^2 b_3 \end{bmatrix}}_{= W_c} \right) = 3 \quad \rightarrow \textcircled{2}$$

$$\Rightarrow \det(W_c) \neq 0$$

$$\det(W_c) = \begin{vmatrix} b_1 & \lambda_1 b_1 & \lambda_1^2 b_1 \\ b_2 & \lambda_2 b_2 & \lambda_2^2 b_2 \\ b_3 & \lambda_3 b_3 & \lambda_3^2 b_3 \end{vmatrix} = \begin{vmatrix} b_1 & \lambda_1 b_1 & \lambda_1^2 b_1 \\ 0 & b_2(\lambda_2 - \lambda_1) & b_2(\lambda_2^2 - \lambda_1^2) \\ 0 & b_3(\lambda_3 - \lambda_1) & b_3(\lambda_3^2 - \lambda_1^2) \end{vmatrix}$$

$$= b_1 b_2 b_3 [(\lambda_2 - \lambda_1)(\lambda_3^2 - \lambda_1^2) - (\lambda_3 - \lambda_1)(\lambda_2^2 - \lambda_1^2)]$$

$$= b_1 b_2 b_3 [(\lambda_2 - \lambda_1)(\lambda_3 - \lambda_1)(\lambda_3 + \lambda_1) - (\lambda_3 - \lambda_1)(\lambda_2 - \lambda_1)(\lambda_2 + \lambda_1)]$$

$$= b_1 b_2 b_3 (\lambda_2 - \lambda_1)(\lambda_3 - \lambda_1)(\lambda_3 - \lambda_2)$$

This is non-zero if none of  $b_1, b_2, b_3$  are zero.  $\textcircled{3}$

For a  $n \times n$  diagonal  $A$  matrix with distinct eigenvalues, the condition for controllability is that none of  $b_1, b_2, \dots, b_n$  are zero  $\rightarrow \textcircled{2}$