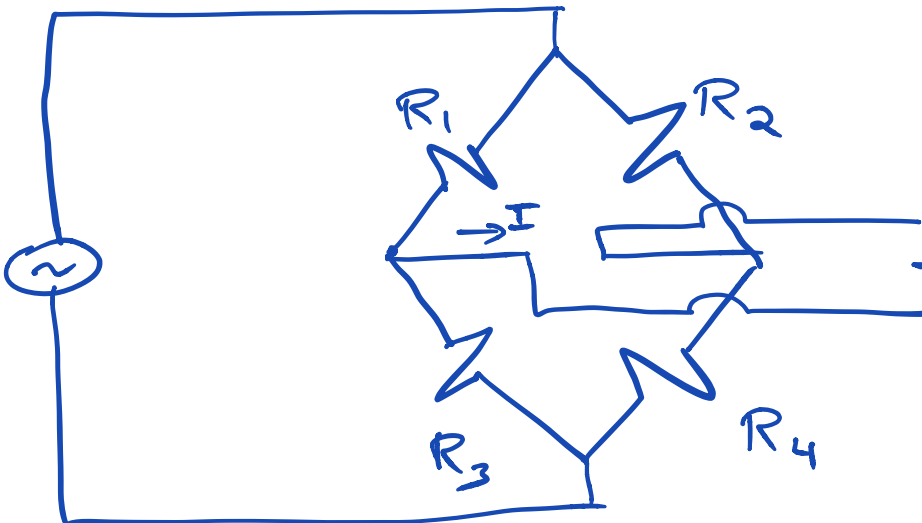
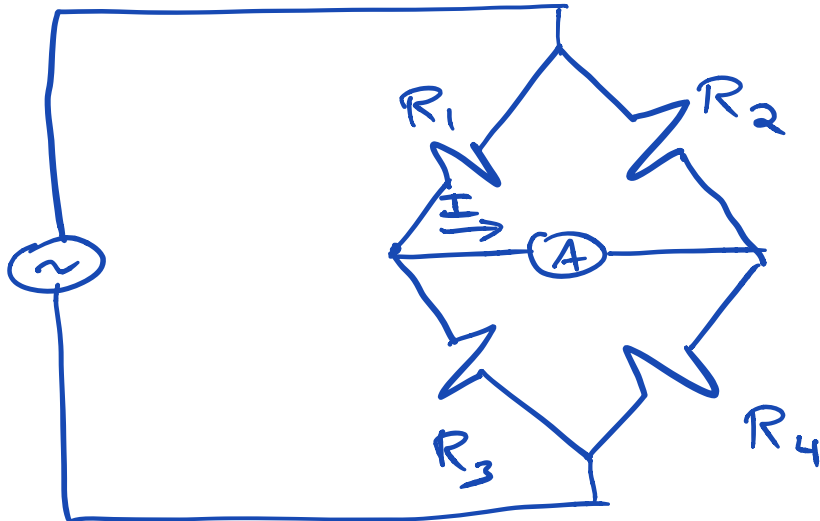
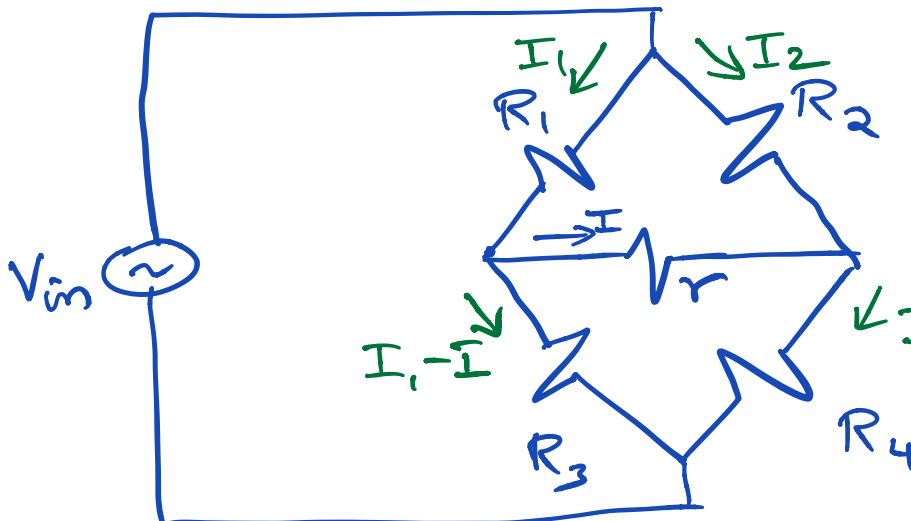


Wheatstone Bridge



in sensor uses

→ TB amplifier



r is the input resistance of the amplifier part

Suppose, one of the arms, say R_1 , is a sensor and due to sensing the physical variable, its value changes $R_1 \rightarrow R_1 + \Delta R$, then how much does the current I change?

$$-V_{in} + I_1 R_1 + (I_1 - I) R_3 = 0$$

$$\Rightarrow I_1 = \frac{V_{in}}{R_1 + R_3} + I \cdot \frac{R_3}{R_1 + R_3} \quad \text{--- (1)}$$

$$\text{Similarly } -V_{in} + I_2 R_2 + (I_2 + I) R_4 = 0$$

$$\Rightarrow I_2 = \frac{V_{in}}{R_2 + R_4} - I \cdot \frac{R_4}{R_2 + R_4} \quad \text{--- (2)}$$

$$\text{Similarly } -V_{in} + I_1 R_1 + I r + (I_2 + I) R_4 = 0$$

Replace I_1 from (1) & I_2 from (2),

$$\begin{aligned} \Rightarrow -V_{in} + V_{in} \cdot \frac{R_1}{R_1 + R_3} + I \frac{R_1 R_3}{R_1 + R_3} \\ + I (r + R_4) \\ + V_{in} \frac{R_4}{R_2 + R_4} - I \frac{R_4^2}{R_2 + R_4} = 0 \end{aligned}$$

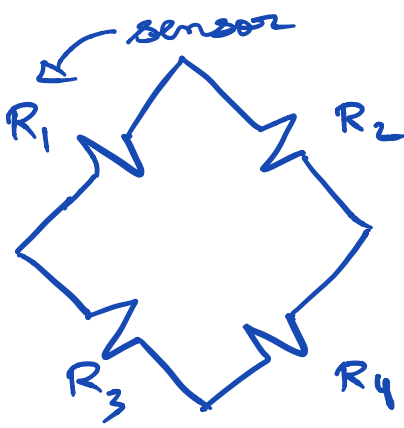
$$\Rightarrow V_{in} \left[-1 + \frac{R_1}{R_1+R_3} + \frac{R_4}{R_2+R_4} \right] + I \left[\frac{R_1 R_3}{R_1+R_3} + r + R_4 - \frac{R_4^2}{R_2+R_4} \right] = 0$$

$$\Rightarrow V_{in} \left[\frac{-R_3}{R_1+R_3} + \frac{R_4}{R_2+R_4} \right] + I \left[\frac{R_1 R_3}{R_1+R_3} + r + \frac{R_2 R_4}{R_2+R_4} \right] = 0$$

$$\Rightarrow I = \frac{V_{in} \left[\frac{R_3}{R_1+R_3} - \frac{R_4}{R_2+R_4} \right]}{\left[r + \frac{R_1 R_3}{R_1+R_3} + \frac{R_2 R_4}{R_2+R_4} \right]}$$

$$\Rightarrow I = V_{in} \frac{R_3(R_2+R_4) - R_4(R_1+R_3)}{r(R_1+R_3)(R_2+R_4) + R_1 R_3(R_2+R_4) + R_2 R_4(R_1+R_3)}$$

$$\Rightarrow I = V_{in} \frac{R_2 R_3 - R_1 R_4}{r(R_1+R_3)(R_2+R_4) + R_1 R_3(R_2+R_4) + R_2 R_4(R_1+R_3)}$$



Initially, $R_1 = R_2 = R_3 = R_4 = R$.

$\Rightarrow I = 0$, as $R_2 R_3 = R_1 R_4$

Due to sensing,

$R_1 = R \rightarrow R_1 = R + \Delta R$

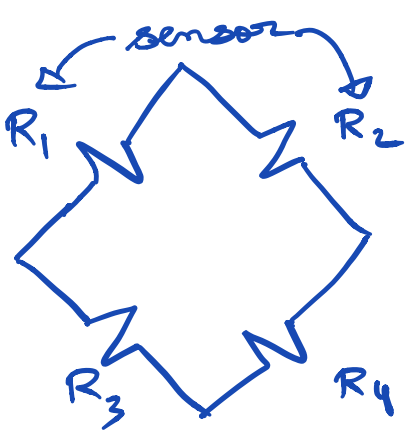
$\Delta R \ll R$

then, what is the change in current, ΔI ?

$$\Delta I = V_{in} \frac{R_2 R_3 - (R + \Delta R) R_4}{r(R + \Delta R + R_3)(R_2 + R_4) + (R + \Delta R) R_3 (R_2 + R_4) + R_2 R_4 (R + \Delta R + R_3)}$$

$$= V_{in} \frac{-R_4 \Delta R}{r(R + \Delta R + R_3)(R_2 + R_4) + (R + \Delta R) R_3 (R_2 + R_4) + R_2 R_4 (R + \Delta R + R_3)}$$

$$\approx V_{in} \frac{-R_4 \Delta R}{r(R + R_3)(R_2 + R_4) + (R) R_3 (R_2 + R_4) + R_2 R_4 (R + R_3)}$$



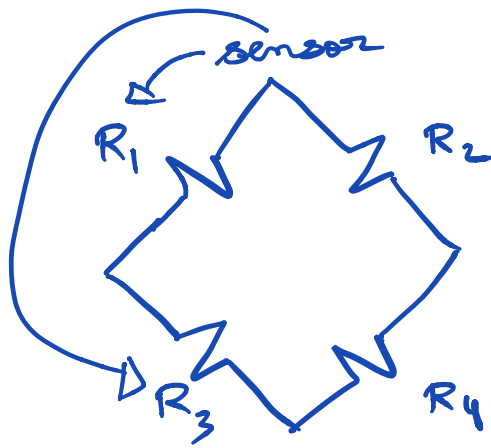
$$R_1: R \rightarrow R + \Delta R$$

$$R_2: R \rightarrow R + \Delta R$$

$$\Delta I ?$$

$$= 0$$

$$\begin{aligned} \left[\begin{aligned} &R_2 R_3 - R_1 R_4 \\ &= (R + \Delta R) R_3 \\ &\quad - (R + \Delta R) R_4 \\ &= 0 \end{aligned} \right] \end{aligned}$$



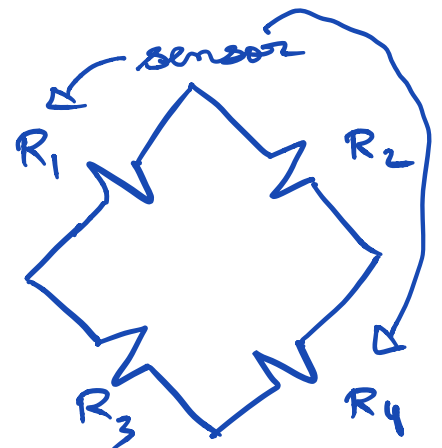
$$R_1: R \rightarrow R + \Delta R$$

$$R_3: R \rightarrow R + \Delta R$$

$$\Delta I ?$$

$$= 0$$

$$\begin{aligned} \left[\begin{aligned} &R_2 R_3 - R_1 R_4 \\ &= (R + \Delta R) R_2 \\ &\quad - (R + \Delta R) R_4 \\ &= 0 \end{aligned} \right] \end{aligned}$$



$$R_1: R \rightarrow R + \Delta R$$

$$R_4: R \rightarrow R + \Delta R$$

$$\Delta I ?$$

$$= \text{add up?}$$

$$\begin{aligned} \left[\begin{aligned} &R_2 R_3 - R_1 R_4 \\ &= R_2 R_3 - (R + \Delta R)^2 \\ &= R_2 R_3 - R^2 \\ &\quad - 2\Delta R \cdot R - (\Delta R)^2 \\ &\approx -2\Delta R \cdot R \end{aligned} \right] \end{aligned}$$

Advantage:

Makes the bridge intrinsically robust to disturbances which may cause $\Delta R \neq 0$

Advantage:

Increases the gain of the bridge