

10.04.2019

Least Squares.

Data : x_1, x_2, \dots, x_N
 y_1, y_2, \dots, y_N

Model : $y = Kx + \eta$

Method : Minimize cost $\sum_{i=1}^N (y_i - Kx_i)^2$ as a function of K .
 (Least Square)

what is inside this?
 unmodelled, ignored dynamics,
 disturbances, errors ...

$$\Rightarrow \hat{K} = \frac{\sum_{i=1}^N y_i x_i}{\sum_{i=1}^N x_i^2}$$

\hat{K} is estimator of K

$$\begin{aligned} E(\hat{K}) &= E \left\{ \frac{\sum_{i=1}^N y_i x_i}{\sum_{i=1}^N x_i^2} \right\} \quad \text{based on model} \\ &= \frac{1}{\sum_{i=1}^N x_i^2} E \left\{ \sum_{i=1}^N (Kx_i + \eta_i) x_i \right\} \\ &= \frac{1}{\sum_{i=1}^N x_i^2} E \left\{ \sum_{i=1}^N (Kx_i^2 + \eta_i x_i) \right\} \\ &= \frac{1}{\sum_{i=1}^N x_i^2} \left[E \left\{ \sum_{i=1}^N Kx_i^2 \right\} + E \left\{ \sum_{i=1}^N \eta_i x_i \right\} \right] \\ &= K + \frac{1}{\sum_{i=1}^N x_i^2} \sum_{i=1}^N x_i E\{\eta_i\} \\ &= K, \text{ if } E\{\eta_i\} = 0, \text{ noise is zero mean} \end{aligned}$$

$\therefore \hat{K}$ is unbiased estimator if noise is zero mean.

$$E\{(\hat{K} - K)^2\} = ?$$

$$\frac{\text{variance of noise}}{\sum_{i=1}^N x_i^2}$$

assuming $E\{n_i\} = 0$

and n_i, n_j are independent

$$\sim \frac{\text{variance of noise}}{N \cdot \text{variance of } x}$$

increase N , lowers variance power

Is this the smallest variance that can be achieved?

Is there another method that can give an estimate of K with lower variance than this?

Cramer-Rao Bound

For an unbiased estimator $\hat{\theta}$ of θ

$$E\{(\hat{\theta} - \theta)^2\} \geq \frac{-1}{E\left\{\frac{\partial^2 \log L(y|\theta)}{\partial \theta^2}\right\}}$$

likelihood
log-likelihood

- This gives the lower bound to variance of the unbiased estimator $\hat{\theta}$
- We want to calculate this bound for a zero-mean Gaussian distribution
- and show that this is the same as that obtained from Least Squares method

Hence, least squares is the best method for above model

$$n \sim \frac{1}{\sqrt{2\pi\sigma_n^2}} e^{-\frac{n^2}{2\sigma_n^2}}$$

$$L(y|K) = \left(\frac{1}{\sqrt{2\pi\sigma_n^2}}\right)^N \cdot e^{-\frac{\sum_{i=1}^N (y_i - Kx_i)^2}{2\sigma_n^2}}$$

\downarrow
 $\sum y_1, y_2, \dots, y_N$

$$\frac{\partial^2}{\partial K^2} \log L(y|K)$$

$$\log L(y|K) = \log(\downarrow) - \frac{1}{2\sigma_n^2} \sum_{i=1}^N (y_i - Kx_i)^2$$

$$\frac{\partial}{\partial K} \log L(y|K) = \left(\frac{-1}{2\sigma_n^2}\right) \sum_{i=1}^N (-2x_i)(y_i - Kx_i)$$

$$\frac{\partial^2}{\partial K^2} \log L(y|K) = \left(\frac{-1}{2\sigma_n^2}\right) \sum_{i=1}^N 2x_i^2$$

Lowest variance possible : $\frac{-1}{\frac{1}{\sigma_n^2} \sum_{i=1}^N x_i^2} = \frac{\sigma_n^2}{\sum_{i=1}^N x_i^2}$,

which is the same as obtained with the least squares method for zero mean, independent noise