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ELL301

The Least Squares method is best method for measurement where noise is ^(independent) Gaussian in the sense that the corresponding estimator achieves minimum possible variance.

error \neq mistake

in context of measurement errors are inherent.

↳ Random error

• measurement noise

N readings of a quantity of interest

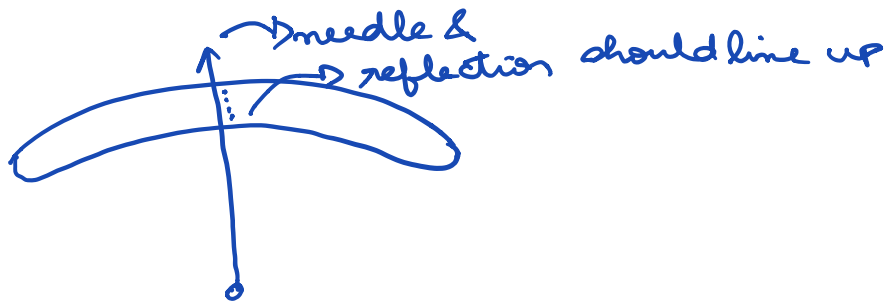
$$y_1, y_2, \dots, y_N$$
$$\text{Mean, } \mu_y = \frac{1}{N} \sum_{i=1}^N y_i$$

$$\text{Standard Deviation } \sigma_y = \sqrt{\frac{1}{N} \sum_{i=1}^N (y_i - \mu_y)^2}$$

The summary of measurement is represented as $\mu_y \pm \sigma_y$ (N readings)

↳ Gross Error / Human Error

↳ Parallax Error



↳ Environmental errors

Temperature affects instrument properties
⇒ this contributes to different readings at different times

↳ Systematic error

→ instrument characteristics drift over time
→ loading effects

Propagation of uncertainty.

$$y = f(x_1, x_2, \dots, x_N)$$

each x_i has a mean value μ_i and a standard deviation σ_i .

What is the mean of y and its standard deviation?

Suppose,

$$y = \frac{1}{N} (x_1 + x_2 + \dots + x_N)$$

$$x_i = \mu_i \pm \sigma_i \Rightarrow y = \mu_y \pm \sigma_y?$$

$$\mu_y, \text{ mean of } y = \frac{1}{N} (h_1 + h_2 + \dots + h_N)$$

σ_y , standard deviation of y ?

$$\sigma_y^2 = \left(\frac{1}{N} \right) (y - \mu_y)^2$$

$$= \frac{1}{N} \left(\frac{1}{N} (x_1 + x_2 + \dots + x_N) - \frac{1}{N} (h_1 + h_2 + \dots + h_N) \right)^2$$

$$= \frac{1}{N} \left[\frac{1}{N} (x_1 - h_1) + \frac{1}{N} (x_2 - h_2) + \dots + \frac{1}{N} (x_N - h_N) \right]^2$$

$$= \frac{1}{N} \left[\left(\frac{1}{N} (x_1 - h_1) \right)^2 + \left(\frac{1}{N} (x_2 - h_2) \right)^2 + \dots + \left(\frac{1}{N} (x_N - h_N) \right)^2 \right.$$

$$+ \frac{1}{N^2} (x_1 - h_1)(x_2 - h_2) + \dots + \frac{1}{N^2} (x_1 - h_1)(x_N - h_N)$$

$$+ \frac{1}{N^2} (x_2 - h_2)(x_1 - h_1) + \dots + \frac{1}{N^2} (x_2 - h_2)(x_N - h_N)$$

+ ...

$$+ \frac{1}{N^2} (x_N - h_N)(x_1 - h_1) + \frac{1}{N^2} (x_N - h_N)(x_2 - h_2) + \dots \left. \right]$$

$$\frac{1}{N} (x_1 - h_1)^2 = \sigma_1^2 \text{ and so on}$$

covariance terms are zero as assume

experiments done independently.

$$\Rightarrow \sigma_y^2 = \left(\frac{1}{N} \right) (\sigma_1^2 + \sigma_2^2 + \dots + \sigma_N^2)$$

↳ should this be there?