

ELL 333

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How to get state from output? (so that in can be used for $u = -Kx$)

$$\begin{cases} \dot{x} = Ax + Bu \\ y = Cx + Du \end{cases}$$

ignoring why?

$$x(t) = e^{At} x_0 + \int_0^t e^{A(t-z)} B u(z) dz$$

$$y(t) = C e^{At} x_0 + C \int_0^t e^{A(t-z)} B u(z) dz + D u(t)$$

✓ output we can measure
 we know system parameters
 don't know
 input we give
 we know system parameters

We ignore B & D terms when we want to estimate x from y , because?

$$y(t) - C \int_0^t e^{A(t-z)} B u(z) dz - D u(t) = C e^{At} x_0$$

only unknown
if we get x_0
then $x(t) = e^{At} x_0$
when $u=0$

known effectively,
so we take input $u=0$ (or $B=D=0$)
so that those terms not there

◦◦ We simplify to the question of determining x_0 from y using the equation

$$y = C e^{At} x_0$$

Observability

The system $\dot{x} = Ax, y = Cx$ is observable if it is possible to find any initial state x_0 ($x(t=0)$) from observations of output $y(t)$ over finite duration $[0, T]$. $0 \leq t \leq T$

Nullspace or Kernel

Suppose $U: \mathbb{R}^m \rightarrow \mathbb{R}^n$,

then

$$\text{Ker}(U) = \left\{ x \in \mathbb{R}^m \text{ such that } Ux = 0 \right\}$$

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$$y = C e^{At} x_0$$

Can we reduce observing x_0 from y in terms of $\text{Ker} \{ C e^{At} \}$?

$$C e^{At} : \mathbb{R}^n \rightarrow \mathbb{R}^p$$

(state) (output)

Suppose there was $v (\neq 0)$ in $\text{Ker}(C e^{At})$, then can we get x_0 from y ?

$$v \in \text{Ker}(C e^{At}) \Rightarrow C e^{At} v = 0$$

must have
been some
 x_0 here

$$y(t) = C e^{At} x_0$$

If $v (\neq 0) \in \text{Ker}(C e^{At})$,

$$C e^{At} (x_0 + v) = C e^{At} x_0 + \underbrace{C e^{At} v}_{= 0}$$

Why I am discussing this before going to theorems showing observability $\Leftrightarrow \text{rank} \left\{ \begin{bmatrix} C \\ CA \\ \vdots \\ CA^{n-1} \end{bmatrix} \right\} = n$

convolution $u \xrightarrow{\quad} x \xrightarrow{C e^{At}} y$

Theorem: $\text{Ker}(C e^{At}) = \text{Ker}(C) \cap \text{Ker}(CA) \cap \text{Ker}(CA^2) \cap \dots \cap \text{Ker}(CA^{n-1})$

Proof:

$$\text{Ker}(C e^{At}) \subseteq \text{Ker}(C) \cap \text{Ker}(CA) \dots \cap \text{Ker}(CA^{n-1})$$

Suppose $v \in \text{Ker}\{C e^{At}\}$

$$\Rightarrow C e^{At} v = 0 \quad \xrightarrow{t=0} \quad C v = 0 \Rightarrow v \in \text{Ker}(C)$$

Differentiate w.r.t t

$$\Rightarrow C A e^{At} v = 0 \quad \rightarrow \quad C A v = 0 \Rightarrow v \in \text{Ker}(CA)$$

Differentiate w.r.t t

$$\Rightarrow C A^2 e^{At} v = 0 \quad \rightarrow \quad C A^2 v = 0 \Rightarrow v \in \text{Ker}(CA^2)$$

$$\therefore v \in \text{Ker}(C) \cap \text{Ker}(CA) \dots \cap \text{Ker}(CA^{n-1})$$

$$\text{Ker}(C) \cap \text{Ker}(CA) \dots \text{Ker}(CA^{n-1}) \subseteq \text{Ker}(C e^{At})$$

Suppose $x \in \text{Ker}(C) \cap \text{Ker}(CA) \dots \text{Ker}(CA^{n-1})$

$$\Rightarrow C x = 0, CA x = 0, \dots, CA^{n-1} x = 0$$

How to show $C e^{At} x = 0$?

$$e^{At} = f_0(t) I + f_1(t) A + \frac{f_2(t)}{2!} A^2 + \dots + \frac{f_{n-1}(t)}{(n-1)!} A^{n-1}$$

(because of Cayley-Hamilton Thm and matrix exponential)

$$\therefore C e^{At} = f_0(t) \cdot C + f_1(t) \cdot CA + \dots + \frac{f_{n-1}(t)}{(n-1)!} CA^{n-1}$$

$$\Rightarrow C e^{At} x = 0$$

$$\Rightarrow x \in \text{Ker}(C e^{At})$$

$$\therefore \text{Ker}(C e^{At}) = \text{Ker}(C) \cap \text{Ker}(CA) \cap \dots \cap \text{Ker}(CA^{n-1})$$

$\text{Ker} \begin{bmatrix} C \\ CA \\ \vdots \\ CA^{n-1} \end{bmatrix}_{n \times n}$

$C: \mathbb{R}^n \rightarrow \mathbb{R}^p$
 $CA: \mathbb{R}^n \rightarrow \mathbb{R}^p$
 $CA^{n-1}: \mathbb{R}^n \rightarrow \mathbb{R}^p$

$$\begin{bmatrix} C \\ CA \\ \vdots \\ CA^{n-1} \end{bmatrix}_{n \times n} x_{n \times 1} = \begin{bmatrix} Cx \\ CAx \\ \vdots \\ CA^{n-1}x \end{bmatrix}_{n \times 1}$$