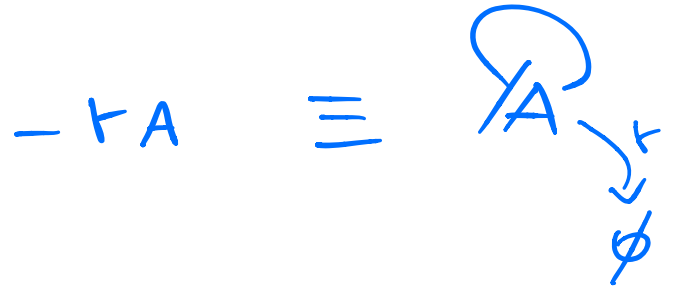


ELL707

23.01.2020

$$\frac{dA}{dt} = \alpha_0 + \frac{\alpha \cdot k^n}{k^n + A^n}$$

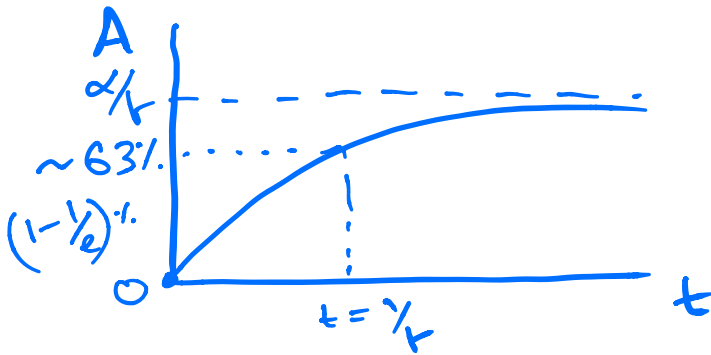


for comparison,

$$\frac{dA}{dt} = \alpha - rA \equiv \alpha \rightarrow \textcircled{A} \xrightarrow{r} \phi$$

Focus on (↓)

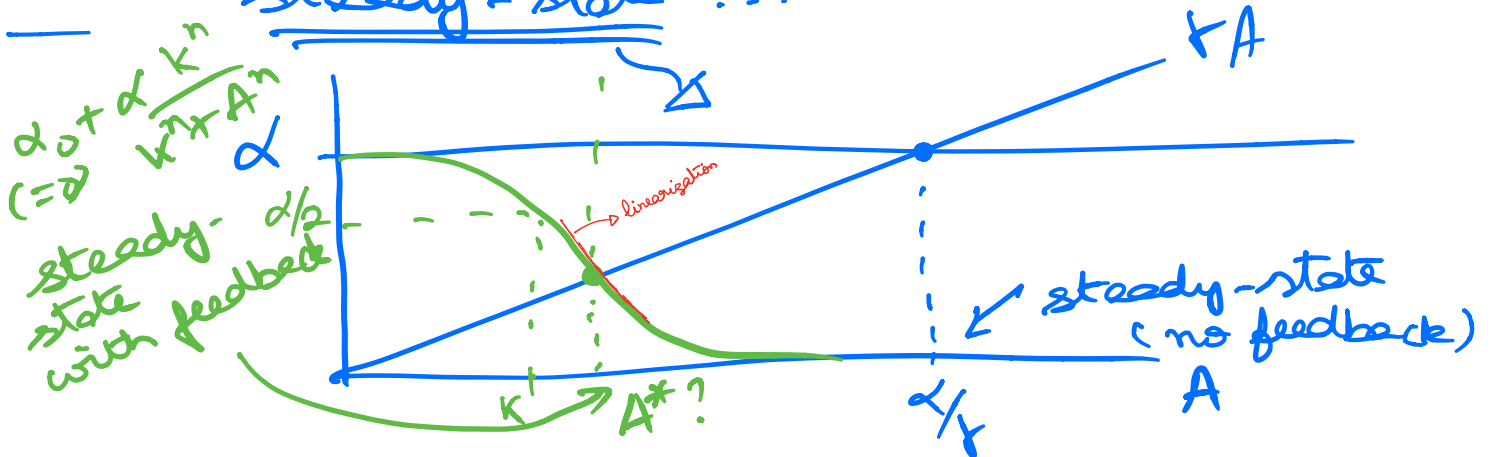
$$\Rightarrow A(t) = \frac{\alpha}{r} (1 - e^{-rt}), \quad A(0) = 0$$



exponential response
time constant: $\frac{1}{r}$

Question: How does adding negative feedback, as in the above model, change the response time?

steady-state ...



What is A^* relative to α/τ ?

$$A^* > \frac{\alpha}{\tau} \quad \text{or} \quad A^* < \frac{\alpha}{\tau}$$

• $A^* < \frac{\alpha}{\tau}$ always.

• If $K \ll \frac{\alpha}{\tau}$, $A^* \ll \frac{\alpha}{\tau}$

• If $K \gg \frac{\alpha}{\tau}$, $A^* \approx \frac{\alpha}{\tau}$

Response time comparison

$$\frac{dA}{dt} = \stackrel{(\alpha_0=0)}{\propto} \frac{K^n}{K^n + A^n} - \tau A$$

How to do?

→ Linearization approach

Linearize the nonlinear term about an operating.

Replace $A = A^* + \Delta A$ in ()

$$\text{LHS} \quad \frac{dA}{dt} = \frac{d}{dt} (A^* + \Delta A) = \frac{d}{dt} \Delta A$$

$$\text{RHS} \quad \frac{\alpha K^n}{K^n + A^n} - \tau A = \frac{\alpha K^n}{K^n + (A^* + \Delta A)^n} - \tau (A^* + \Delta A)$$

≈ Taylor Series of first term upto first order

$$\frac{\alpha k^n}{k^n + (A^*)^n} + \frac{d}{dA} \left(\frac{\alpha k^n}{k^n + A^n} \right) \Big|_{A=A^*} (\Delta A) - \tau A^* - \tau \Delta A$$

$$= \left(\frac{\alpha k^n}{k^n + (A^*)^n} - \tau A^* \right) + \frac{-\alpha k^n \cdot n (A^*)^{n-1}}{(k^n + (A^*)^n)^2} \cdot \Delta A - \tau \Delta A$$

$\hookrightarrow \Delta = 0$ because A^* is a steady-state

$$= - \left(\tau + \frac{\alpha k^n \cdot n (A^*)^{n-1}}{(k^n + (A^*)^n)^2} \right) \Delta A$$

linearization of the negative feedback model at $A = A^*$ is

$$\frac{d}{dt} \Delta A = - \left(\tau + (\text{sth +ve}) \right) \Delta A$$

Repeat $A = \frac{\alpha}{\tau} + \Delta A$ for $\frac{dA}{dt} = \alpha - \tau A$

$$\frac{d}{dt} \Delta A = -\tau \Delta A$$

→ Compare the time constants of those.

Which is faster?

As $(\text{sth +ve}) > 0$, negative feedback is locally faster than no feedback.

How much faster?

This depends on parameters.

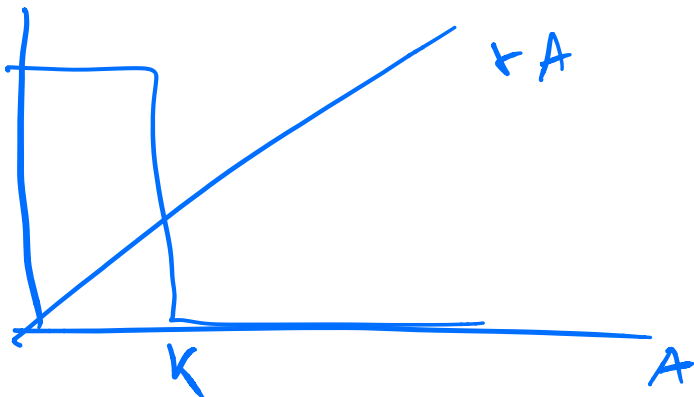
If $K \gg \frac{\alpha}{\Gamma} > A^*$
 then structure = $\frac{\alpha K^n \cdot n (A^*)^{n-1}}{(K^n + (A^*)^n)^2}$
 $\approx \frac{\alpha K^n \cdot n (A^*)^{n-1}}{K^n \cdot K^n}$

$\ll \tau$ in above limit $= \left\{ \frac{n\alpha}{K} \cdot \left(\frac{A^*}{K}\right)^{n-1} \right\} \approx 0, n > 1$
 $\left(\frac{\alpha}{K}\right)$ if $n = 1$

Small K limit

$$\frac{dA}{dt} = \alpha \frac{K^n}{K^n + A^n} - \Gamma A$$

$$\approx \alpha \cdot \frac{K^n}{A^n}$$



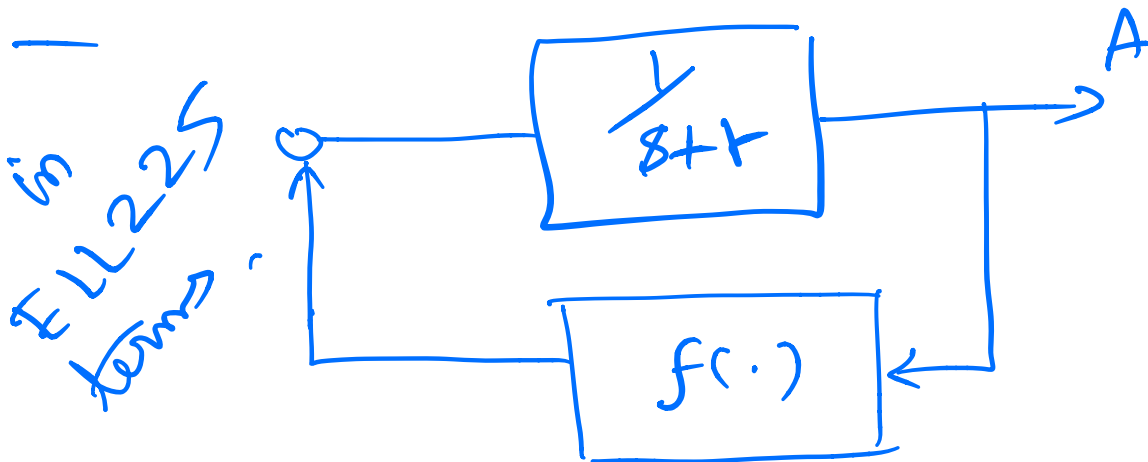
Say $k = A^*$

$$\text{sth tue} = \frac{\alpha n k^n (A^*)^{n-1}}{(k^n + (A^*)^n)^2}$$

$$\approx \frac{n \cdot \alpha \cdot k^n \cdot k^{n-1}}{(2k^n)^2}$$

$$= \frac{n \cdot \alpha}{2k}$$

$$\frac{dA}{dt} = \frac{\alpha k^n}{k^n + A^n} - \tau A$$



$$f(A) = \frac{\alpha k^n}{k^n + A^n}$$

≡ linearized around $A = A^*$

