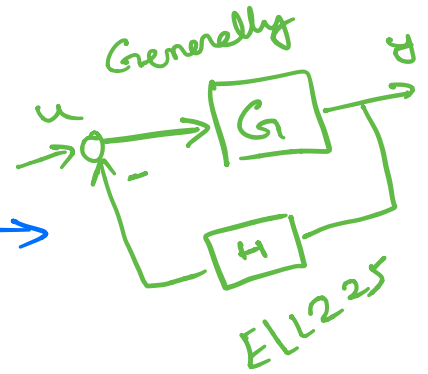
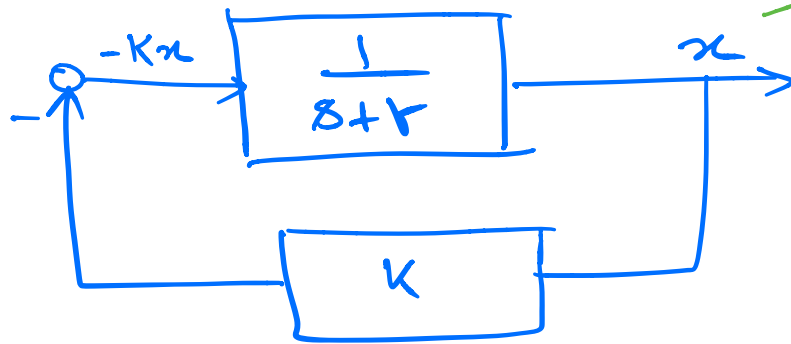


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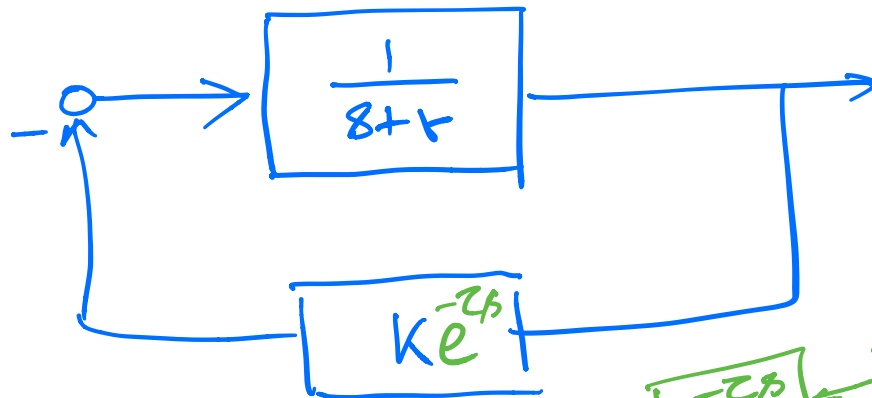


What is corresponding differential equation?

$$\left(\frac{d}{dt} + r\right)x = -Kx$$

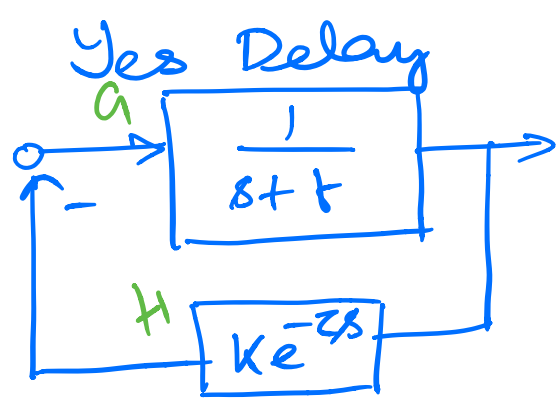
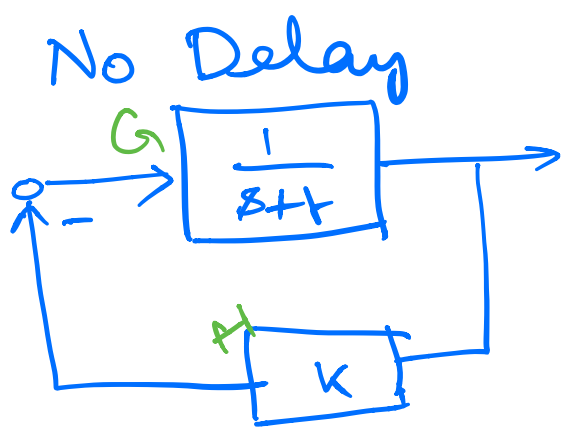
$$\frac{dx}{dt} + rx = -Kx$$

Aim: Add delay to above negative feedback loop and analyze behaviour



$$y(t) = x(t-z) \left[ e^{-zs} \right] \leftarrow x(t)$$

Linear or Nonlinear? Check using superposition



- Stable?
- overall (Transfer function) block may be represented as

$$\frac{1}{s+t+k} \quad \begin{cases} k > 0 \\ t > 0 \end{cases}$$

- corresponding differential equation
- $$\equiv \frac{dx}{dt} = -(t+k)x$$

- $\Rightarrow$  Stable as poles are in LHP (left half of complex plane)

- Stable? (should be stable)

$$\frac{1}{s+t+k e^{-z s}}$$

- Check stability using Nyquist Plot

## Nyquist Plots / Bode Plots

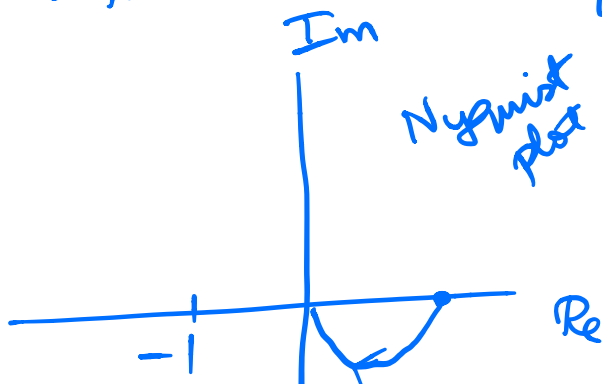
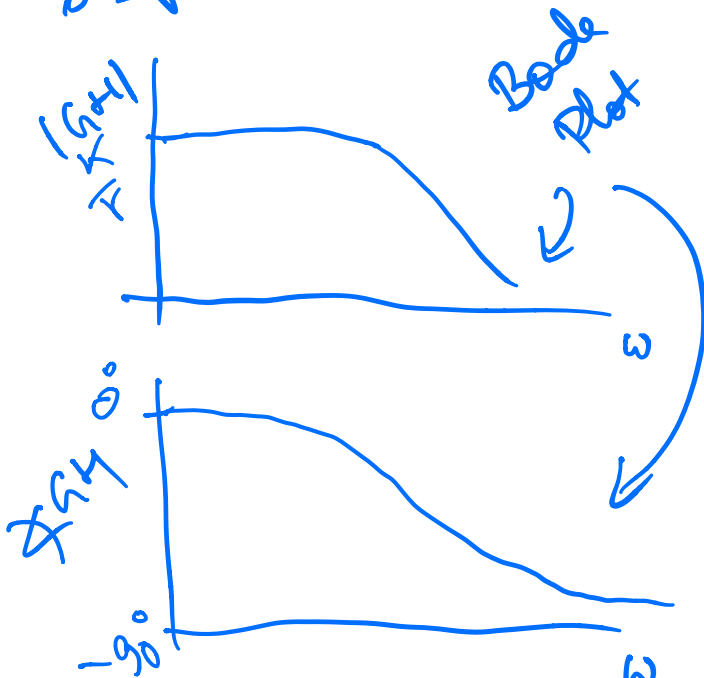
$$\frac{G}{1+GH}$$

Want to check if  $GH = -1$  and for what value of  $s$  this happens.

No delays,

$$GH = \frac{K}{s + \tau}$$

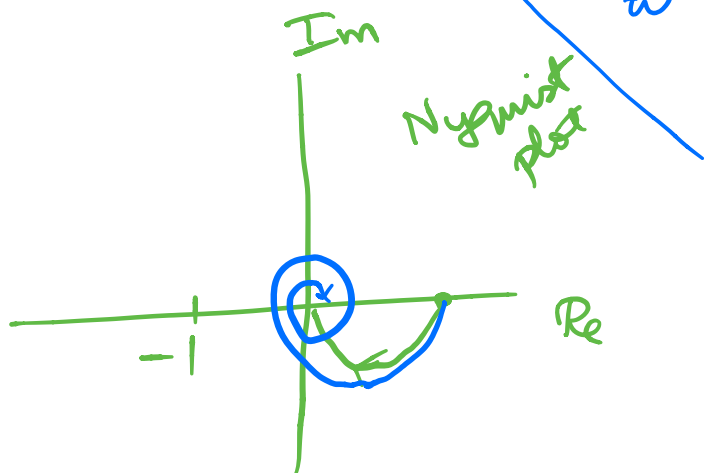
$$s = j\omega$$



Never hits -1

Yes delays

$$GH = \frac{K e^{-z\tau}}{s + \tau}$$



Could hit -1 for some values of  $K, z, \tau$ .

- large  $z, K$  may allow curve to hit '-1'

- may become unstable.

I want to say: These points of instability are those that correspond to purely imaginary roots of  $s + 1 + Ke^{-Ts} = 0$

$$\frac{d^2 x}{dt^2} + \omega^2 x = 0 \quad \equiv \quad \rightarrow \boxed{\frac{1}{s^2 + \omega^2}} \rightarrow$$

$$(s^2 + \omega^2) X(s) = ( ) x(0) + ( ) \dot{x}(0)$$