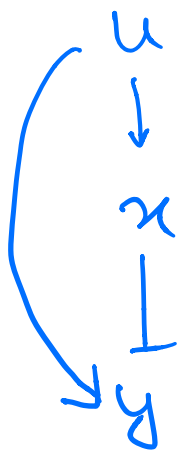


ELL 707

27.02.2020

Example 1:



$$\frac{dx}{dt} = \alpha_x u - r_x x$$

$$\frac{dy}{dt} = \alpha_y u \frac{k}{x} - r_y y$$

exact solution?

• steady-state

$$x^* = \frac{\alpha_x}{r_x} u$$

$$y^* = \frac{\alpha_y}{\alpha_x} \cdot \frac{r_x}{r_y} \cdot k \quad \checkmark \quad \begin{array}{l} \text{no } u \\ \text{here} \end{array}$$

y^* is independent of exact value of u ($\neq 0$)

• stability

Linearize around (x^*, y^*)

$$x = x^* + \Delta x, \quad y = y^* + \Delta y$$

$$\Rightarrow \frac{d\Delta x}{dt} = \alpha_x u - r_x (x^* + \Delta x)$$

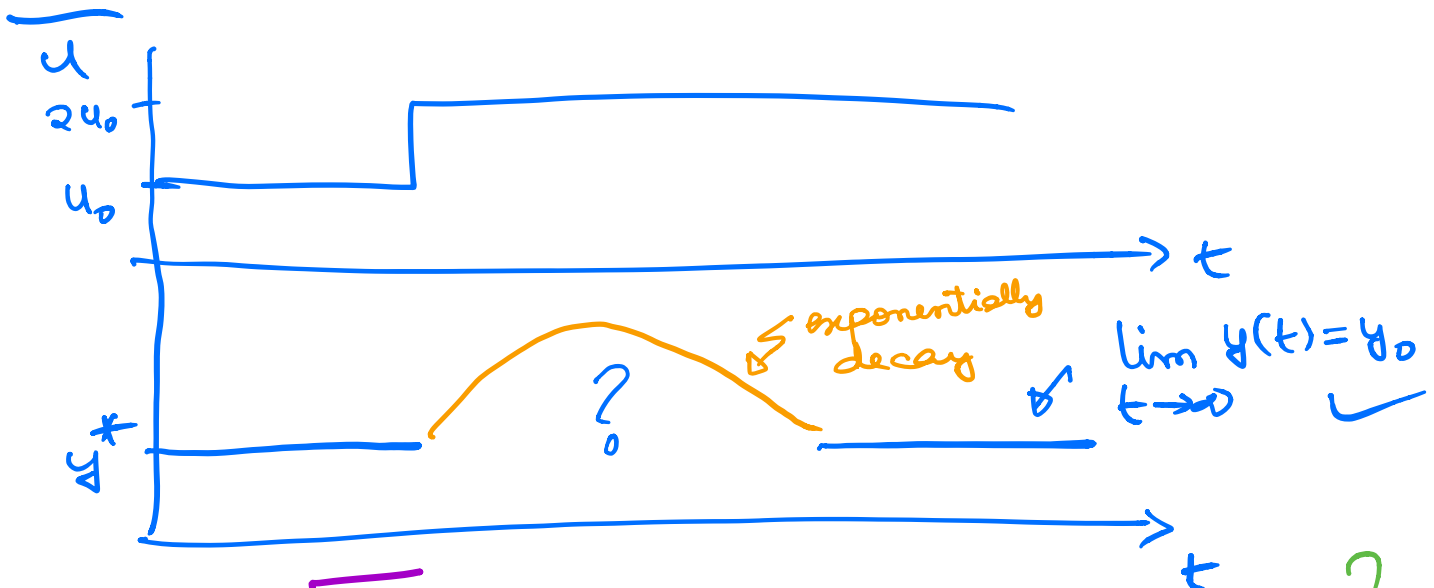
$$\& \frac{d\Delta y}{dt} = \alpha_y u \cdot \frac{k}{x^* + \Delta x} - r_y (y^* + \Delta y)$$

$$\Rightarrow \frac{d\Delta x}{dt} = -r_x \Delta x$$

$$\begin{aligned} \& \frac{d\Delta y}{dt} &= \alpha_y u \frac{k}{x^*} - \alpha_y u \frac{k}{(x^*)^2} \Delta x \\ &\quad - r_y y^* - r_y \Delta y \\ &= -\alpha_y u \frac{k}{(x^*)^2} \Delta x - r_y \Delta y \end{aligned}$$

$$\Rightarrow \frac{d}{dt} \begin{bmatrix} \Delta x \\ \Delta y \end{bmatrix} = \begin{bmatrix} -r_x & 0 \\ -\alpha_y u \frac{k}{(x^*)^2} & -r_y \end{bmatrix} \begin{bmatrix} \Delta x \\ \Delta y \end{bmatrix}$$

Stable because $\text{eig}(\downarrow) = -r_x, -r_y < 0$

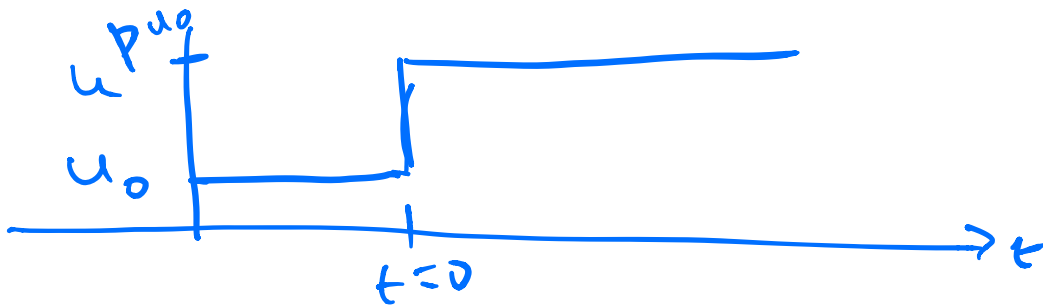


? because $\frac{u}{x}$ can be anything?

For more rigorous explanation, lets try to solve?

$$\frac{dx}{dt} = \alpha_x u - r_x x$$

$$\frac{dy}{dt} = \alpha_y u \frac{K}{x} - r_y y$$



$$x(0) = \frac{\alpha_x u_0}{r_x}, \quad y(0) = \frac{\alpha_y}{\alpha_x} \cdot \frac{r_x}{r_y} \cdot K$$

$$\begin{aligned} x(t) &= x(0) e^{-r_x t} + \frac{\alpha_x}{r_x} p u_0 (1 - e^{-r_x t}) \\ &= \frac{\alpha_x}{r_x} u_0 e^{-r_x t} + \frac{\alpha_x}{r_x} p u_0 (1 - e^{-r_x t}) \end{aligned}$$

$$\frac{dy}{dt} = \alpha_y p u_0 \frac{K}{x(t)} - r_y y$$

$$\frac{dy}{dt} = \frac{\alpha_y \cdot p u_0 \cdot K}{\frac{\alpha_x}{r_x} u_0 e^{-r_x t} + \frac{\alpha_x}{r_x} p u_0 (1 - e^{-r_x t})} - r_y y$$

$\frac{dy}{dt} + r_y y$ + move $r_y y$ to other side

$$\frac{d}{dt} e^{r_y t} \cdot y = \frac{\alpha_y p u_0 k e^{r_y t}}{\frac{\alpha_x u_0}{r_x} [p + (1-p)e^{-r_x t}]}$$

$$d e^{r_y t} y = \left[\frac{\alpha_y \cdot r_x \cdot p \cdot k}{\alpha_x} \right] \cdot \frac{e^{r_y t} dt}{p + (1-p)e^{-r_x t}}$$

↓
c

other way: homogeneous soln. + particular soln.

Ritvik will try

$$d e^{r_y t} y = c \frac{e^{(r_y + r_x) t} dt}{1 - p + p e^{r_x t}}$$

For $r_y = r_x = r$

$$\Rightarrow d e^{rt} y = c \frac{e^{rt} dt}{1 - p + p e^{rt}}$$

$$z = 1 - p + p e^{rt}$$

$$\Rightarrow dz = p e^{rt} \cdot r dt$$

$$\Rightarrow e^{rt} dt = \frac{dz}{p r}$$

$$\& e^{rt} = \frac{z - 1 + p}{p}$$

$$\Rightarrow d e^{rt} y = c \cdot \left(\frac{z - 1 + p}{p} \right) \cdot \frac{1}{z}$$

$$\Rightarrow d e^{rt} y = \frac{c}{p^2 r} \left[\frac{z - 1 + p}{z} \right] dz \rightarrow \left[1 + \frac{p-1}{z} \right]$$

Integriere $t: 0 \rightarrow t$

$$y: y(0) \rightarrow y$$
$$= \frac{dy}{dx} \cdot t$$

$$z: 1 \rightarrow 1 - p + p e^{rt}$$

$$e^{rt} y - y(0) = \frac{c}{p^2 t} \left[z \Big|_1^{1-p+pe^{rt}} + (p-1) \ln z \Big|_1^{1-p+pe^{rt}} \right]$$

$$\Rightarrow e^{rt} y - y(0) = \frac{c}{p^2 t} \left[p(e^{rt} - 1) + (p-1) \ln(1 - p + p e^{rt}) \right]$$

$$\Rightarrow e^{rt} y = y(0) + \frac{c}{p t} (e^{rt} - 1) + \frac{c}{p^2 t} (p-1) \ln(1 - p + p e^{rt})$$

$$\Rightarrow y(t) = y(0) e^{-rt} + \frac{c}{p t} (1 - e^{-rt}) + \frac{c}{t} \frac{p-1}{p} e^{-rt} \ln(1 - p + p e^{rt})$$

$$\Rightarrow y(t) = \frac{dy}{dx} \cdot K e^{-rt} + \frac{dy}{dx} \cdot k (1 - e^{-rt})$$

$$+ \frac{dy}{dx} \cdot k \cdot \frac{p-1}{p} e^{-rt} \ln(1 - p + p e^{rt})$$

$\frac{dy}{dx} \cdot t_x \cdot p \cdot k$
 $\downarrow c$

$$\Rightarrow y(t) = \underbrace{\frac{\alpha_y}{\alpha_n} \cdot K + \frac{\alpha_y}{\alpha_n} \cdot K \cdot \frac{p-1}{p} e^{-t/\tau} \ln(1 - p + p e^{t/\tau})}_{\text{transient response}}$$

\uparrow
 y^*

as $t \rightarrow \infty$, dominated by exponential decay

for $t \sim 0^+$, ?

$e^{-t/\tau}$: decreases

$\ln(1 + p(e^{t/\tau} - 1))$: increases

