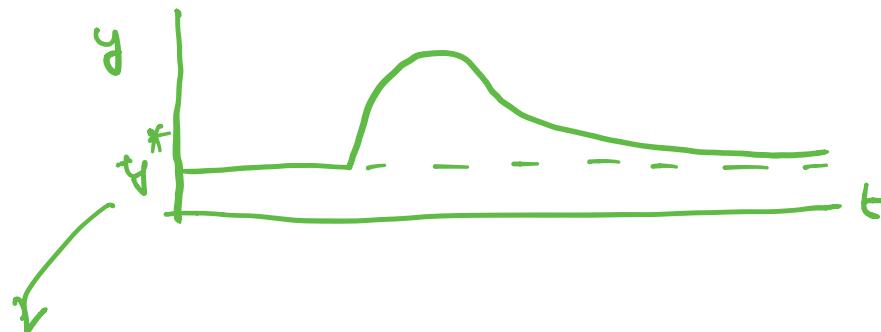
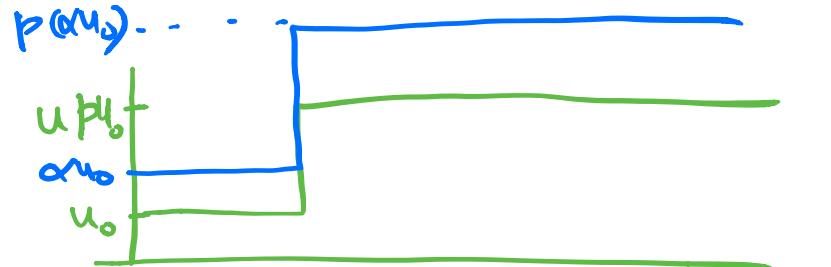
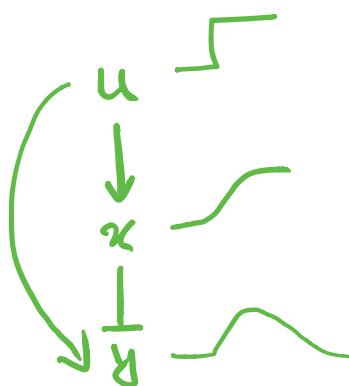


04.03.2020  
ELL707



$$y(t) = \frac{\alpha_y}{\alpha_x} K + \frac{\alpha_y}{\alpha_x} K \frac{p-1}{p} e^{-rt} \ln(1 - p + pe^{-rt})$$

[for some degradation,  $\tau_x = \tau = \tau_y$ ]

This exhibits a fold-change property in the sense that the transient response depends only on 'p' and not the absolute value 'u'.

### Definition of Fold-Change Detection

Consider a system with input 'u' and output 'y'. System is initially at rest  $y(0) = y_0$ .

Fold change detection means that the response  $y(t)$  is exactly the same for two inputs  $u_1(t)$  and  $u_2(t)$  that are related by a fold-change  $u_2(t) = \alpha u_1(t)$ ,  $\alpha > 0$  is constant.

$$u_1(t) \longrightarrow y_1(t)$$

$$u_2(t) \longrightarrow y_2(t)$$

If  $u_2(t) = \alpha u_1(t) \Rightarrow y_1(t) = y_2(t)$ .

---

Theorem: Consider a system

$$\begin{aligned}\dot{x} &= f(x, y, u) && \text{u - input} \\ \dot{y} &= g(x, y, u) && \text{y - output}\end{aligned}$$

A sufficient condition for this to have the Fold. Change Detection property is

- it has a stable steady-state
- this steady-state doesn't depend on input (homeostasis/exact adaptation)
- for  $\alpha > 0$  (homogeneity)

$$f(\alpha x, y, \alpha u) = \alpha f(x, y, u)$$

$$g(\alpha x, y, \alpha u) = g(x, y, u)$$

We want to prove that

Proof:  $u_1(t) \longrightarrow y_1(t)$

$$u_2(t) \longrightarrow y_2(t)$$

$$\text{If } \alpha u_1(t) = u_2(t) \Rightarrow y_1(t) = y_2(t)$$

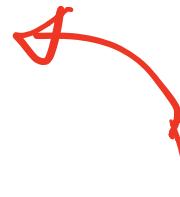
(for any  $\alpha > 0$ )

$$\text{Condition a) + b)} \Rightarrow y_{1,ss} = y_{2,ss}$$

$\underline{u_1}$ 

$$\frac{dx_1}{dt} = f(x_1, y_1, u_1)$$

$$\frac{dy_1}{dt} = g(x_1, y_1, u_1)$$

 $\underline{u_2}$ 

$$\frac{dx_2}{dt} = f(x_2, y_2, u_2)$$

$$\frac{dy_2}{dt} = g(x_2, y_2, u_2)$$

 $\Rightarrow$ 

$$\frac{dx_2}{dt} = f(x_2, y_2, \alpha u_1) \quad \text{if } u_2(t) = \alpha u_1(t)$$

$$\frac{dy_2}{dt} = g(x_2, y_2, \alpha u_1)$$

Normalize  $x_2$ :  $x_2' = \frac{x_2}{\alpha}$

$$\Rightarrow \frac{dx_2'}{dt} = \frac{1}{\alpha} \frac{dx_2}{dt} = \frac{1}{\alpha} f(\alpha x_2', y_2, \alpha u_1) \\ = \frac{1}{\alpha} \cdot \alpha f(x_2', y_2, u_1)$$

$$\frac{dy_2}{dt} = g(\alpha x_2', y_2, \alpha u_1) \\ = g(x_2', y_2, u_1)$$

 $\Rightarrow$ 

$$\frac{dx_2'}{dt} = f(x_2', y_2, u_1) \quad \left. \right\} \text{same as}$$

$$\frac{dy_2}{dt} = g(x_2', y_2, u_1)$$

Equations are same. If initial conditions are same then  $y_1(t) = y_2(t)$

$y_1(0) = y_2(0)$  since independent of input.

$$x_1(0) \stackrel{?}{=} x_2'(0) = \frac{x_2(0)}{\alpha} \rightarrow \text{will check.}$$

Initially

$$f(x_1(0), y_1(0), 0) = 0 = g(x_1(0), y_1(0), 0)$$

$$f(x_2'(0), y_2(0), 0) = 0 = g(x_2'(0), y_2(0), 0)$$

## Quiz 6.

1. Consider the system

$$\frac{dx}{dt} = u - x$$

input :  $u$

$$\frac{dy}{dt} = 2u - x - y$$

output :  $y$

internal variable :  $x$

- a) Find steady-state output.
- b) Is steady-state output independent of  $u$ ?
- c) Is it stable?
- d) Does this system exhibit Fold Change Detection?