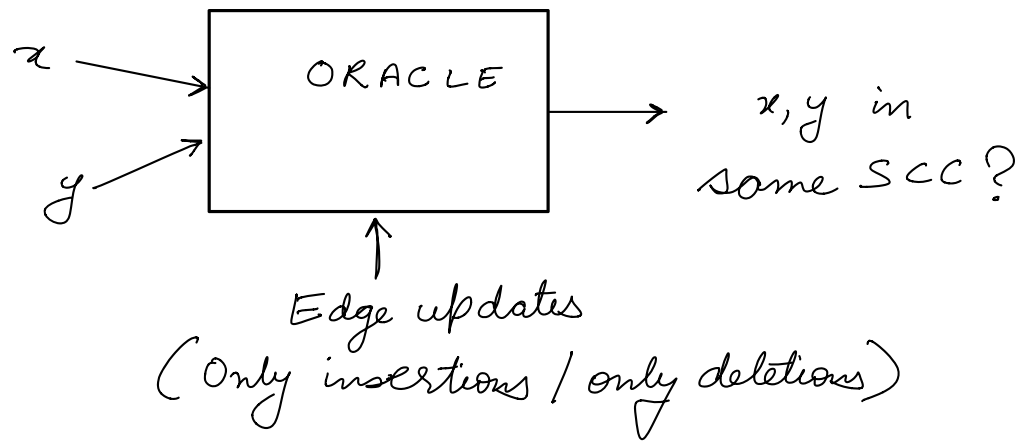


Incremental / Decremental SCC Oracle



Incremental Setting

SSR - $O(m)$ total time

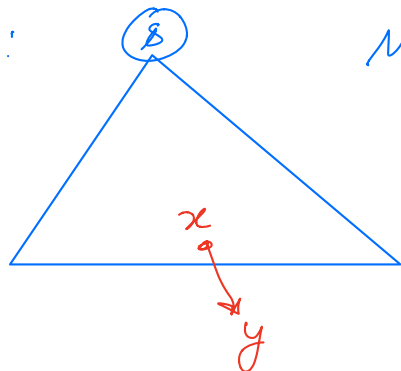
$\therefore$ APR - $O(mn)$ total time

SCC - $O(mn)$ total time

(We just need to maintain SSR from all vertices in G .)

How to solve incremental SSR (Single source reachability) in $O(m)$ total time?

Solⁿ:

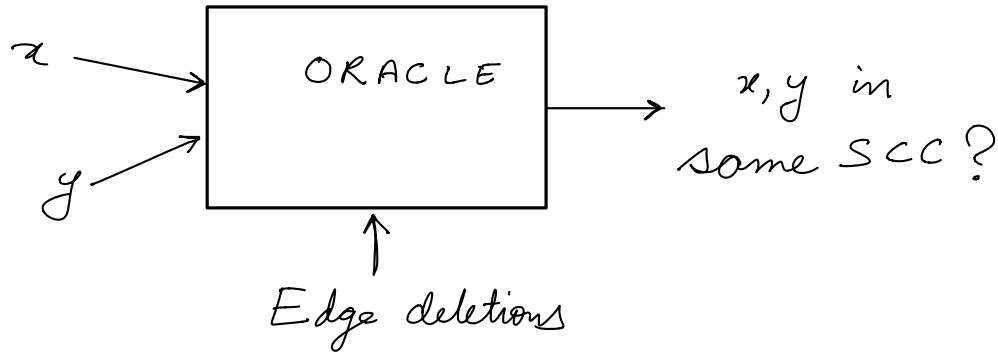


Maintain vertices reachable from s .

On addition of $e = (x, y)$ such that only x was previously reachable, perform a tree-traversal from y over only

those vertices that are first time becoming reachable from s .

Decremental Setting



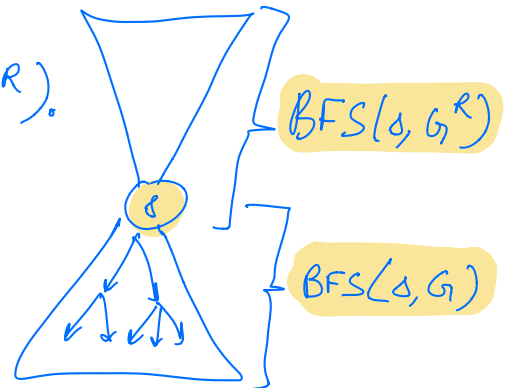
Simpler Problem (Decremental)

Initially : Suppose G is an SCC

Maintain : Whether G remains an SCC or not. (Yes/No)

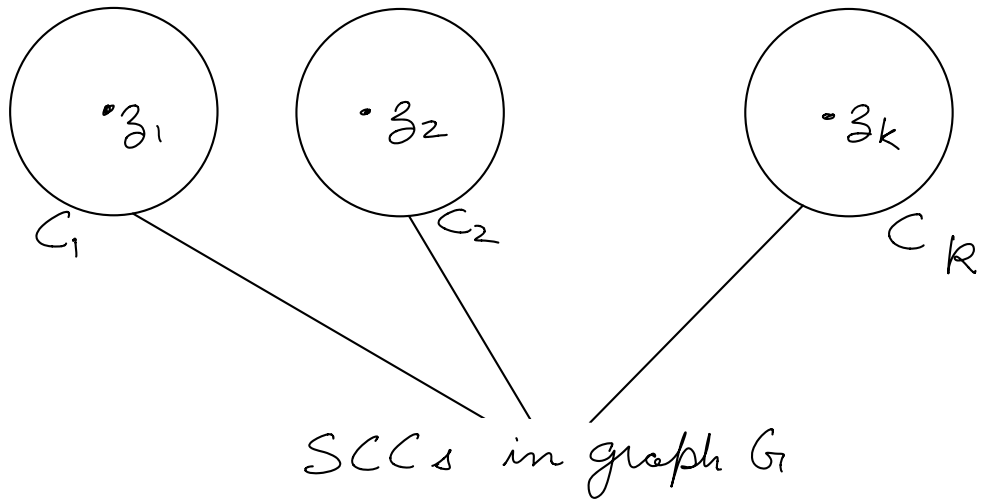
An $O(mn)$ total time algorithm is :

- ① Choose $s \in V(G)$.
- ② Maintain $\text{BFS}(s, G)$ and $\text{BFS}(s, G^R)$.
- ③ Output 'Yes' if both BFS trees have n vertices, and
'No' if either of trees has $\leq n-1$ vertices



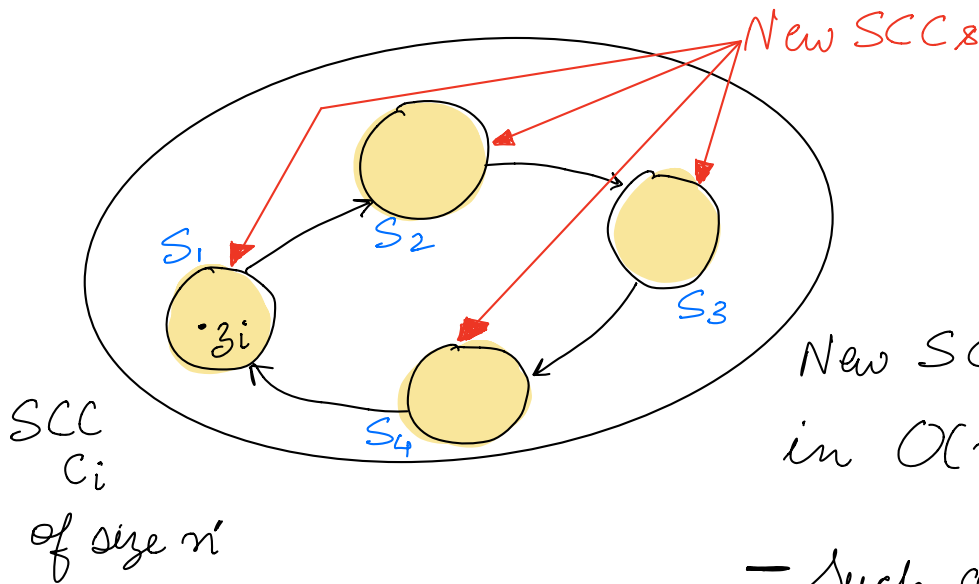
Main Idea:

Initially :



On an edge deletion
 C_i can split:

(maintain $\text{BFS}(z_i, G[C_i])$
and $\text{BFS}(z_i, G^R[C_i])$)



New SCC can be found
in $O(m)$ time after split

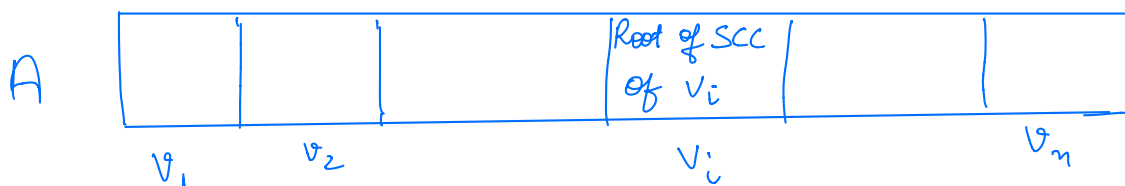
— Such an event occurs at
most $(n-1)$ times

- ④ In exactly one child (new) SCC vertex z_i lies
- ④ At most one child (new) SCC has size $\geq \frac{n'}{2}$
- ④ In the child (new) SCCs that don't contain z_i , we will choose new root and maintain "in" and "out" BFS.

Decremental SCC Algorithm :

Initialization Phase :

- ① Compute the partitioning $\underline{G} = \{C_1, C_2, \dots, C_k\}$ of SCCs
- ② Delete from G edges lying b/w SCCs: $C_1, C_2, \dots, C_k$
- ③ For $i = 1$ to $|\underline{G}|$:
 choose a random vertex z_i in C_i ,
 Set z_i to be root of C_i .
 Initialize and maintain $BFS(z_i, G)$, $BFS(z_i, G^R)$.
- ④ Compute an array A of size n such that
 $A[q] = \text{root of SCC of vertex } v_q, 1 \leq q \leq n.$

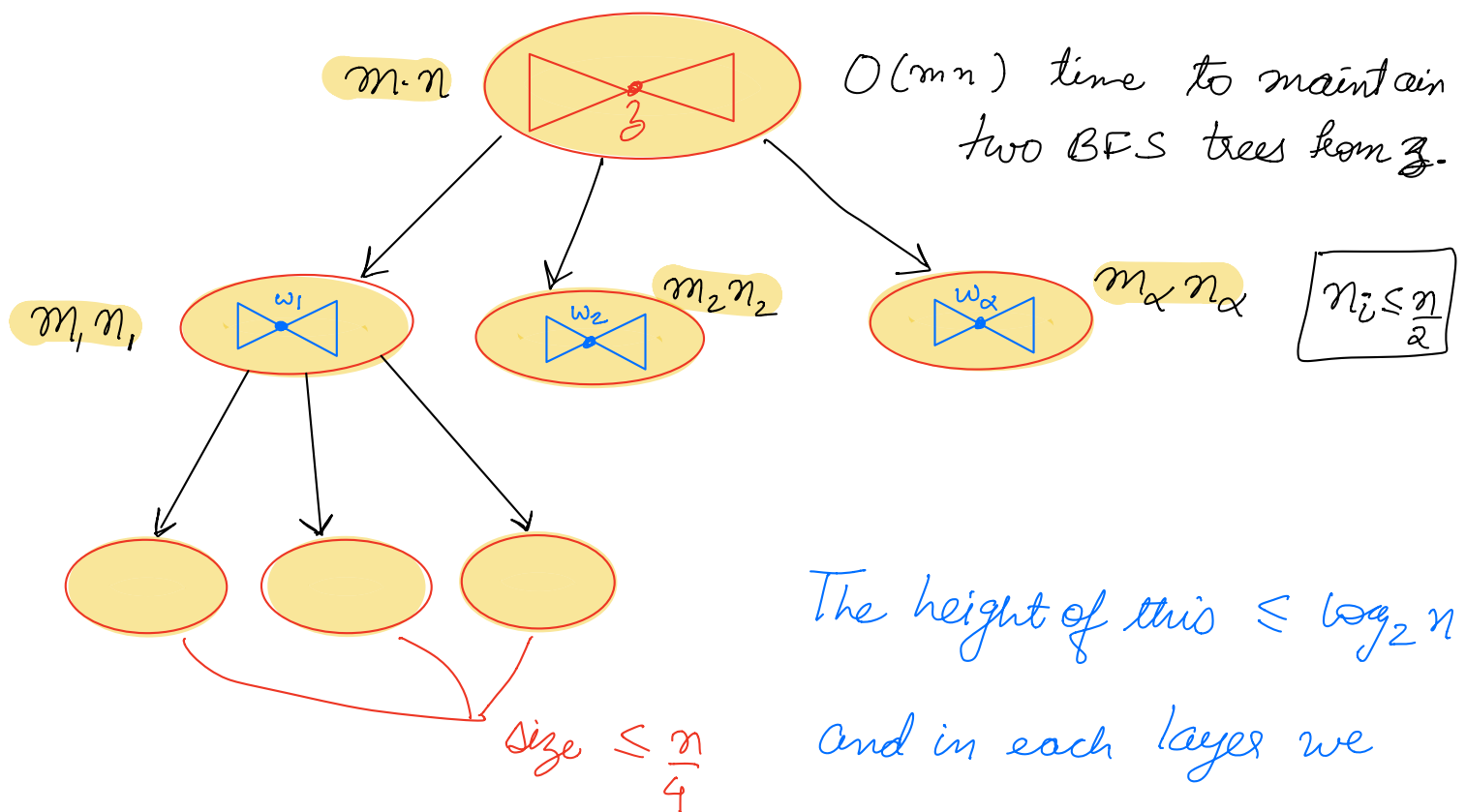


Deletion Subroutine ($e = (u, v)$)

- ① If $A[v] \neq A[u] \Rightarrow \text{Return.}$
- ② Let $z = A[v]$ be root of SCC of v .
- ③ $C_0 = \text{Vertices in BFS}(z, G)$ } Total time of this step
 $= O(n) \times m.$
 $(C_0 \text{ is old SCC of } z \text{ as we don't keep inter SCC edges.})$
- ④ Delete edge (u, v) from $\text{BFS}(z, G)$, $\text{BFS}(z, G^R)$
- ⑤ If size of tree $\text{BFS}(z, G)$ or $\text{BFS}(z, G^R)$ decreases:
 - $\rightarrow$ Compute new (child) SCCs $S_1 \dots S_\alpha$ } Total time of this step
 $= O(m) \times n.$
 - $\rightarrow$ Remove all edges lying b/w $S_1 S_2 \dots S_\alpha$
 and update $\text{BFS}(z, G)$ and $\text{BFS}(z, G^R)$
 - $\rightarrow$ For $i=1$ to α :
 - If $z \notin S_i$:
 - $\rightarrow$ Choose a random root $w_i \in S_i$
 - $\rightarrow \forall$ vertices in S_i update entry in A to root w_i
 - $\rightarrow$ Compute & decrementally maintain
 $\text{BFS}(w_i, G)$ and $\text{BFS}(w_i, G^R).$

Before analyzing above algorithm we will analyze some special cases.

SPECIAL CASE 1: Whenever an SCC splits the new components have size at most half of original SCC.

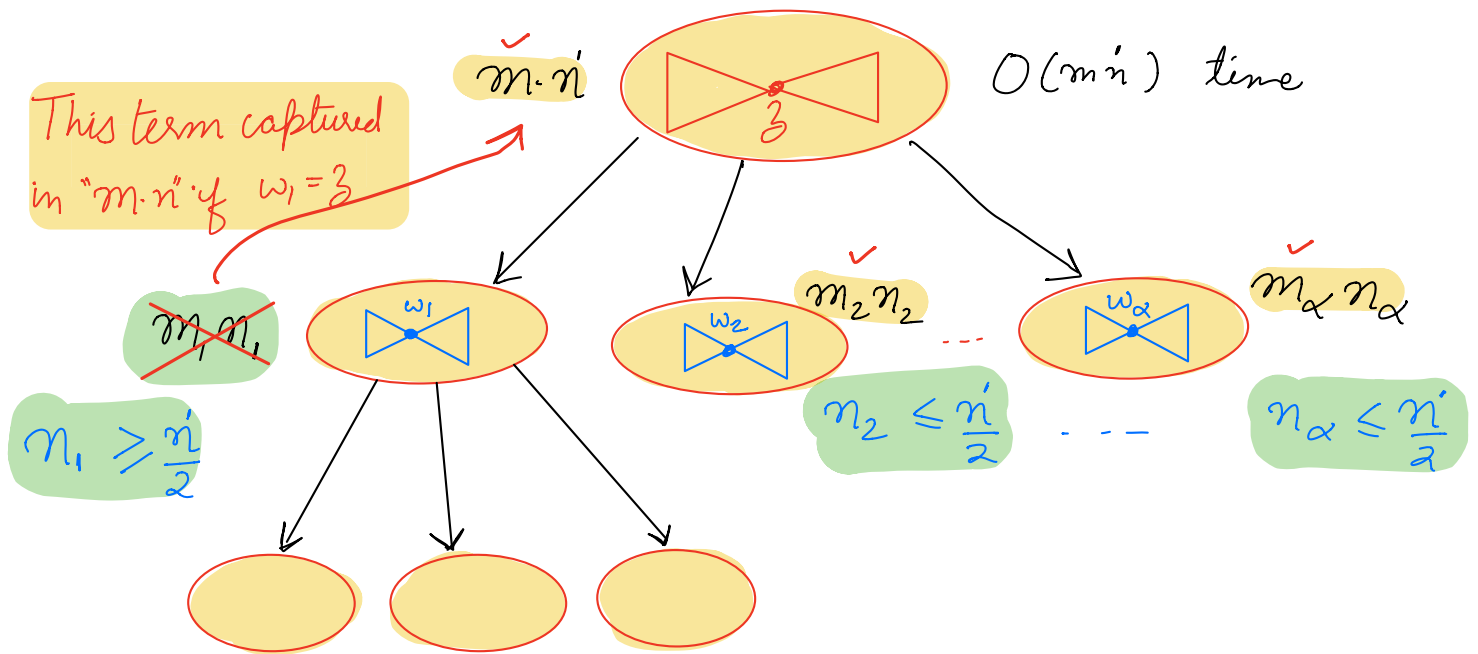


The height of this $\leq \log_2 n$
 and in each layer we
 spent in total $O(mn)$ time

$\Rightarrow$ Total time spent = $O(mn \log n)$.

can we eliminate this?

SPECIAL CASE 2: Whenever an SCC splits the root of original SCC goes into largest component.



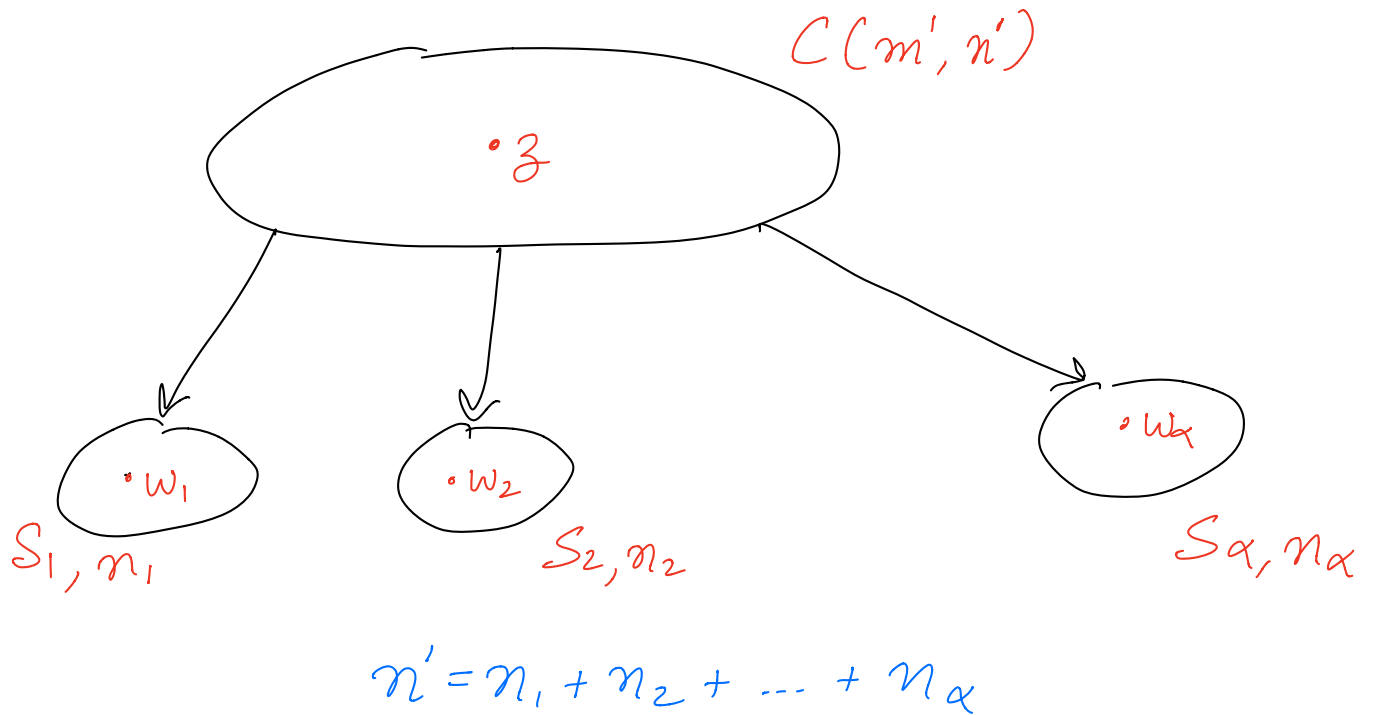
Note: With probability half (at least) z is passed to component having size $\geq \frac{n'}{2}$.

—X—

We next perform analysis of algorithm

Analysis :

- * Cost of maintaining BFS trees in different component is main bottle neck.



Expected cost of maintaining S_i

$$= \underbrace{\left(1 - \frac{n_i}{n'}\right)}_{\text{Prob}(z \notin S_i)} * n_i n_i \leq \left(\frac{n' - n_i}{n'}\right) (n_i)(n)$$

So, each edge of S_i gets cost $= \left(\frac{n' - n_i}{n'} \right) \cdot n$

In general, suppose edge e lies in t components in total:

$$\begin{array}{ccccccc}
 C_1 & \longrightarrow & C_2 & \longrightarrow & C_3 & \longrightarrow & \dots \longrightarrow C_t \\
 (n_1) & & (n_2) & & (n_3) & & (n_t) \\
 & & \downarrow & & \downarrow & & \downarrow \\
 & & \left(\frac{n_1 - n_2}{n_1} \right) \cdot n & & \left(\frac{n_2 - n_3}{n_2} \right) \cdot n & & \left(\frac{n_{t-1} - n_t}{n_{t-1}} \right) \cdot n
 \end{array}$$

Total expected cost over e $= \left(\left(\frac{n_1 - n_2}{n_1} \right) + \dots + \left(\frac{n_{t-1} - n_t}{n_{t-1}} \right) \right) \cdot n$

$$\frac{n_1 - n_2}{n_1} \leq \underbrace{\frac{1}{n_1} + \frac{1}{n_1 - 1} + \frac{1}{n_1 - 2} + \dots + \frac{1}{n_2 + 1}}_{(n_1 - n_2) \text{ terms}}$$

$$\frac{n_2 - n_3}{n_2} \leq \frac{1}{n_2} + \frac{1}{n_2 - 1} + \frac{1}{n_2 - 2} + \dots + \frac{1}{n_3 + 1}$$

$(n_2 - n_3)$ terms

$$\text{Total expected cost over } c \leq \left(\frac{1}{n_1} + \frac{1}{n_1+1} + \dots + 1 \right) \cdot n = O(n \log n)$$

$$\text{Thus, expected time complexity of algorithm} = O(mn \log(n)).$$