

8 Q. Suppose $T_1: V_1 \rightarrow V_2$ and $T_2: V_2 \rightarrow V_3$ are linear transformations. Show that $T_2 \circ T_1: V_1 \rightarrow V_3$ is a linear transformation.

Solution: We have to ~~verify~~ show for $a, b \in F, u, v \in V_1$,

$$(T_2 \circ T_1)(au + bv) = a (T_2 \circ T_1)(u) + b (T_2 \circ T_1)(v)$$

that is,

$$T_2(T_1(au + bv)) = a T_2(T_1(u)) + b T_2(T_1(v)) \quad \text{--- (*)}$$

$$\Leftrightarrow \cancel{T_2(aT_1(u) + bT_1(v))}$$

$$\text{LHS} = T_2(aT_1(u) + bT_1(v)) = a T_2(T_1(u)) + b T_2(T_1(v))$$

(since T_2 is a linear transformation)

$$= \text{RHS.}$$

Thus (*) is verified.

9 Q. Show that if $T: \mathbb{R}^n \rightarrow \mathbb{R}$ is a linear transformation, ~~show that~~ then ~~$T = a_1 p_1 + a_2 p_2 + \dots + a_n p_n$~~ for some $a_1, a_2, \dots, a_n \in \mathbb{R}$ and p_i is the map which maps $(x_1, x_2, \dots, x_n)$ to x_i .

Solution: $T(x_1, x_2, \dots, x_n) = T(x_1 e_1 + x_2 e_2 + \dots + x_n e_n)$ (where

$\{e_1, e_2, \dots, e_n\}$ is the standard basis of $\mathbb{R}^n$).

$$= x_1 T(e_1) + x_2 T(e_2) + \dots + x_n T(e_n) \quad (\because T \text{ is linear})$$

$$= \cancel{T(e_i)}$$

$$T(e_1), T(e_2), \dots, T(e_n) \in \mathbb{R}, \quad \text{Suppose } T(e_i) = b_i.$$

$$\begin{aligned} \text{Then } T(x_1, x_2, \dots, x_n) &= x_1 b_1 + x_2 b_2 + \dots + x_n b_n \\ &= b_1 x_1 + b_2 x_2 + \dots + b_n x_n \\ &= b_1 p_1(x_1, \dots, x_n) + b_2 p_2(x_1, x_2, \dots, x_n) + \dots \\ &\quad \dots + b_n p_n(x_1, x_2, \dots, x_n) \\ &= (b_1 p_1 + b_2 p_2 + \dots + b_n p_n)(x_1, x_2, \dots, x_n) \end{aligned}$$

Thus $T = b_1 p_1 + b_2 p_2 + \dots + b_n p_n$ with $a_1, b_2, \dots, b_n \in \mathbb{R}$.