

Lecture

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We have seen that the joint-probability density function of samples from a Gaussian process depend only upon the mean values and the covariance matrix.

i.e., for any n and any t_1, \dots, t_n

the joint p.d.f. of $(x(t_1), \dots, x(t_n))$ is given by

$$f(x(t_1), x(t_2), \dots, x(t_n)) = \frac{1}{(2\pi)^{n/2} \sqrt{|K|}} e^{-\frac{(\underline{x} - \underline{\mu}_x)^T K^{-1} (\underline{x} - \underline{\mu}_x)}{2}}$$

where $\underline{x} \triangleq \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}$, $\underline{\mu}_x \triangleq \begin{bmatrix} E(x(t_1)) \\ E(x(t_2)) \\ \vdots \\ E(x(t_n)) \end{bmatrix}$,

and the covariance matrix

$$K \triangleq E[(\underline{X} - \underline{\mu}_x)(\underline{X} - \underline{\mu}_x)^T], \quad |K| \text{ is the determinant of } K.$$

$\underline{X} = \begin{bmatrix} X(t_1) \\ X(t_2) \\ \vdots \\ X(t_n) \end{bmatrix}$. Note that \underline{X} and \underline{x} are different: \underline{X} is the vector of random variable $X(t_1), \dots, X(t_n)$ whereas \underline{x} is the vector of values (x_1, \dots, x_n) where we like to evaluate the p.d.f.

Property 3
↓ Gaussian random processes

(2)

If a Gaussian random process $X(t)$ is W.S.S. (wide sense stationary) then it is strictly stationary.

Proof: To show strict stationarity we will have to show that

for any finite integer $n \geq 1$ and time instances t_1, t_2, \dots, t_n , and any T

$$f_{X(t_1), X(t_2), \dots, X(t_n)}(x_1, x_2, \dots, x_n) = f_{X(t_1+T), X(t_2+T), \dots, X(t_n+T)}(x_1, x_2, \dots, x_n)$$

we

can assume that $X(t)$ is W.S.S., i.e., for any two time instances t_1 and t_2

$$E(X(t_1)) = E(X(t_2)) \triangleq \mu \quad (2.4)$$

and

$$E(X(t_1)X(t_2)) = E(X(t_2 - t_1)X(0)) \triangleq R(t_2 - t_1) \quad (2.5)$$

(only time difference only)

From (2.4) and (2.5) it is easy to see that

$$E[(X(t_1) - E(X(t_1)))(X(t_2) - E(X(t_2)))] \quad (2.6)$$

also depends only on the time difference $(t_2 - t_1)$

We firstly note that for a W.S.S process $x(t)$

$$\underline{\mu}_1 \triangleq \begin{bmatrix} E(x(t_1)) \\ \vdots \\ E(x(t_n)) \end{bmatrix} \text{ and}$$

$$\underline{\mu}_2 \triangleq \begin{bmatrix} E(x(t_1+T)) \\ \vdots \\ E(x(t_n+T)) \end{bmatrix} \text{ are equal,}$$

and in fact $\underline{\mu}_1 = \underline{\mu}_2 = E(x(t)) \begin{bmatrix} 1 \\ \vdots \\ 1 \end{bmatrix}$ — (3)
where $\mu \triangleq E(x(t))$

this follows from (2.9).

The $(i,j)^{th}$ entry of the covariance matrix of $(x(t_1), \dots, x(t_n))$ is

$$\begin{aligned} K_{(i,j)}^{(1)} &\triangleq E[(x(t_i) - E(x(t_i))) (x(t_j) - E(x(t_j)))] \\ &= E[x(t_i)x(t_j)] - E(x(t_i))E(x(t_j)) \\ &= R(t_j - t_i) - [E(x(t))]^2 \\ &= R(t_j - t_i) - \mu^2. \end{aligned} \text{ — (4.a)}$$

similarly the $(i,j)^{th}$ entry of the covariance matrix of $(x(t_1+T), x(t_2+T), \dots, x(t_n+T))$

$$\begin{aligned} K_{(i,j)}^{(2)} &\triangleq E[(x(t_i+T) - E(x(t_i+T))) (x(t_j+T) - E(x(t_j+T)))] \\ &= R((t_j+T) - (t_i+T)) - \mu^2 \\ &= R(t_j - t_i) - \mu^2 \end{aligned} \text{ — (4.b)}$$

From (4.9) and (4.5) it follows ⁽⁴⁾ that the matrices $K^{(1)}$ and $K^{(2)}$ are equal.

Also the mean vector μ_1 and μ_2 are equal (from (3)).

Since the p.d.f. only depends on the mean vector and the covariance matrix it follows that the p.d.f. of $(X(t_1), \dots, X(t_n))$ and $(X(t_1+T), \dots, X(t_n+T))$ are the same.

Property 4

$X(t_1)$ and $X(t_2)$ have a covariance of 0, i.e.

$$E \left[(X(t_1) - E(X(t_1))) (X(t_2) - E(X(t_2))) \right] = 0,$$

then $X(t_1)$ and $X(t_2)$ are statistically independent.

Before proving property ④ we will ⑤
 discuss the following property of
 jointly Gaussian random variables.

FACT If two jointly Gaussian random
 variables X and Y have zero
~~covariance~~ covariance, i.e.,

$$E[(X - E(X))(Y - E(Y))] = 0, \text{ then}$$

X & Y are statistically independent.

i.e., $f_{X,Y}(x,y) = f_X(x)f_Y(y)$.

Proof of fact
FACT. The joint p.d.f of (X, Y) is
 given by

$$f_{X,Y}(x,y) = \frac{1}{(\sqrt{2\pi})^2 |K|} e^{-\frac{1}{2} \begin{bmatrix} (x-E(X)) & (y-E(Y)) \end{bmatrix} K^{-1} \begin{bmatrix} x-E(X) \\ y-E(Y) \end{bmatrix}}$$

where $K \triangleq \begin{bmatrix} E[(X-E(X))^2] & E[(X-E(X))(Y-E(Y))] \\ E[(X-E(X))(Y-E(Y))] & E[(Y-E(Y))^2] \end{bmatrix}$

since ~~the~~ the covariance between

X & Y is zero, i.e.,

$$E[(X-E(X))(Y-E(Y))] = 0, \text{ it follows that}$$

K is diagonal i.e.,

$$K = \begin{bmatrix} E[(X-E(X))^2] & 0 \\ 0 & E[(Y-E(Y))^2] \end{bmatrix} \quad \textcircled{6}$$

hence $|K| = E[(X-E(X))^2] E[(Y-E(Y))^2]$.

$$f_{X,Y}(x,y) = \frac{1}{(2\pi)^2 \sqrt{\sigma_X^2 \sigma_Y^2}} e^{-\frac{g(x,y)}{2}}$$

where $\sigma_X^2 \triangleq E[(X-E(X))^2]$ and

$$\sigma_Y^2 \triangleq E[(Y-E(Y))^2],$$

$$g(x,y) \triangleq [x-E(X) \quad y-E(Y)] K^{-1} \begin{bmatrix} x-E(X) \\ y-E(Y) \end{bmatrix}$$

$$= [x-E(X) \quad y-E(Y)] \begin{bmatrix} \sigma_X^2 & 0 \\ 0 & \sigma_Y^2 \end{bmatrix}^{-1} \begin{bmatrix} x-E(X) \\ y-E(Y) \end{bmatrix}$$

$$= \frac{(x-E(X))^2}{\sigma_X^2} + \frac{(y-E(Y))^2}{\sigma_Y^2}$$

$$f_{X,Y}(x,y) = \frac{1}{(2\pi) \sqrt{\sigma_X^2} \sqrt{\sigma_Y^2}} e^{-\left\{ \frac{(x-E(X))^2}{2\sigma_X^2} + \frac{(y-E(Y))^2}{2\sigma_Y^2} \right\}}$$

$$= \frac{1}{\sqrt{2\pi}\sigma_X} e^{-\frac{(x-E(X))^2}{2\sigma_X^2}} \cdot \frac{1}{\sqrt{2\pi}\sigma_Y} e^{-\frac{(y-E(Y))^2}{2\sigma_Y^2}}$$

$$= f_X(x) f_Y(y).$$

Property 4 now follows from
the above fact by using
the substitution

$$X \triangleq X(t_1), Y \triangleq X(t_2)$$

and the fact that $X(t_1), X(t_2)$
are jointly Gaussian.