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# Lecture - 17, 18 (Feb 26, March 11, 2014)

DSB-SC (Double Sideband Suppressed Carrier)

message signal -  $m(t)$ .

DSB-SC signal

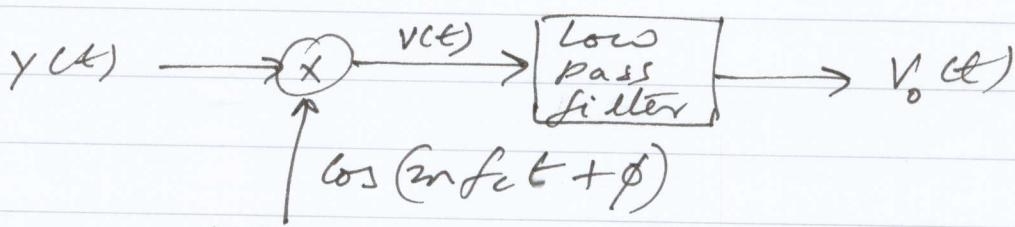
$$s(t) = m(t) \cos(\omega_c t) \cdot (\text{no carrier signal})$$

$$\therefore s(t) = \underline{M(f-f_c)} + M(f+f_c).$$

"Coherent Detection."

Received Signal is

$$y(t) = s(t-\tau) = m(t-\tau) \cos(\omega_c t - \omega_c \tau)$$



local oscillator,  $\phi$ : phase offset of local oscillator.

$$v_{ce}(t) = m(t-\tau) \cos(\omega_c t - \omega_c \tau) \cos(\omega_c t + \phi)$$

$$= \frac{m(t-\tau)}{2} \left[ \cos(\omega_c \tau + \phi) + \cos(\omega_c t + \phi - \omega_c \tau) \right]$$

Assuming  $m(t)$  is band limited to  $[-W, W]$ , and the low pass filter only allows signals in the band  $[-W, W]$  to pass through.

(2)

This filter therefore rejects the signal

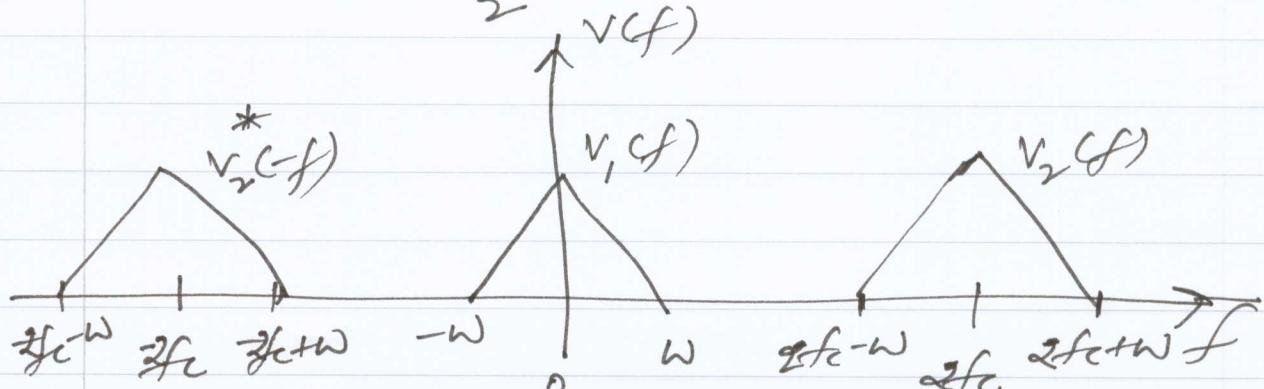
$$\frac{m(t-\tau)}{2} \cos(4\pi f_c t + \phi - m\pi\tau).$$

Detail:

$$v(t) = v_1(t) + v_2(t), \text{ where}$$

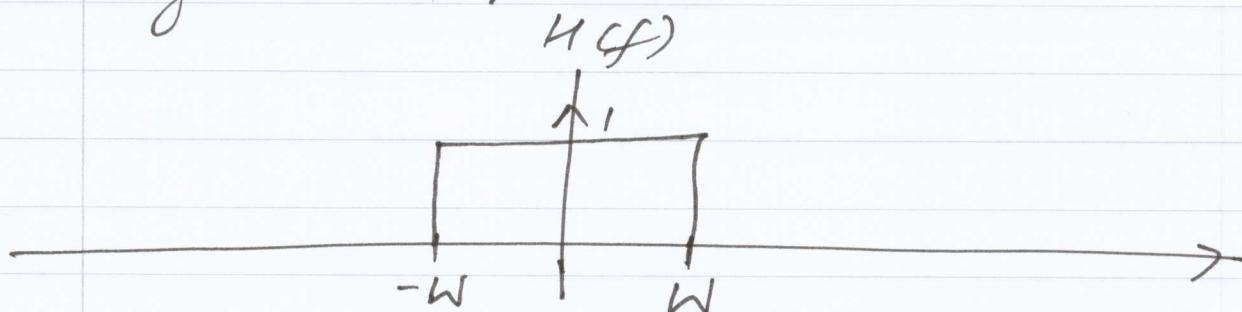
$$v_1(t) = \frac{m(t-\tau)}{2} \cos(2\pi f_c t + \phi) \text{ and}$$

$$v_2(t) = \frac{m(t-\tau)}{2} \cos(4\pi f_c t + \phi - m\pi\tau).$$

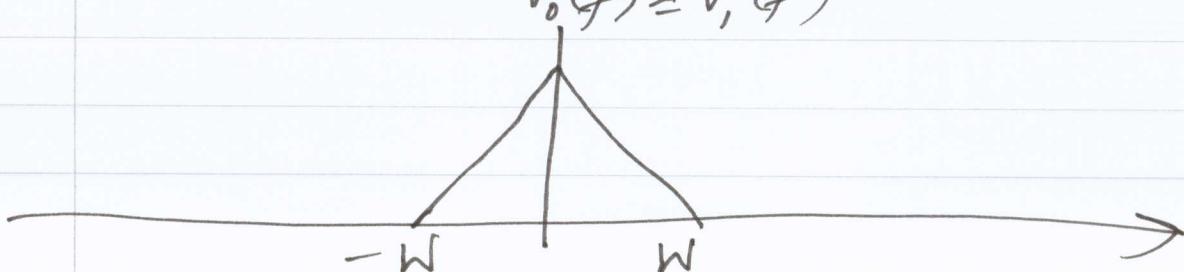


Assuming  $2f_c - w$ , i.e.,  $f_c > w$ ,  $v_2(f)$  and  $v_1(f)$  don't overlap.

using a low pass filter



$$v_o(f) = v_1(f)$$



(3)

$$V_o(t) = \frac{1}{2} m(t-\tau) \cos(2\pi f_c t + \phi)$$

If  $m f_c \tau + \phi = n \pi/2$ ,  $n$  is an odd integer  
then  $V_o(t) = 0$ .

The unknown phase ( $m f_c \tau + \phi$ ) affects the received signal to noise ratio.

This problem happens due to the fact that the phase <sup>offset</sup> of the local oscillator (i.e.  $\phi$ ) does not match the phase offset of receiver carrier  $\cos(m f_c t - m f_c \tau)$

Such a receiver is called non-coherent.

We next discuss a receiver which can resolve this problem of

"non-coherency".

VCO (Voltage Controlled Oscillator)

Instantaneous frequency of the oscillator output

$$f_i(t) = f_c + k v(t), \text{ where } v(t) \text{ is the input control voltage to the oscillator.}$$

Instantaneous phase

$$\phi_{vco}(t) = 2\pi \int_0^t f_i(k) dt + \phi_{vco}^{(0)}$$

$$= 2\pi f_c t + 2\pi k \int_0^t v(t) dt + \phi_{vco}^{(0)}$$

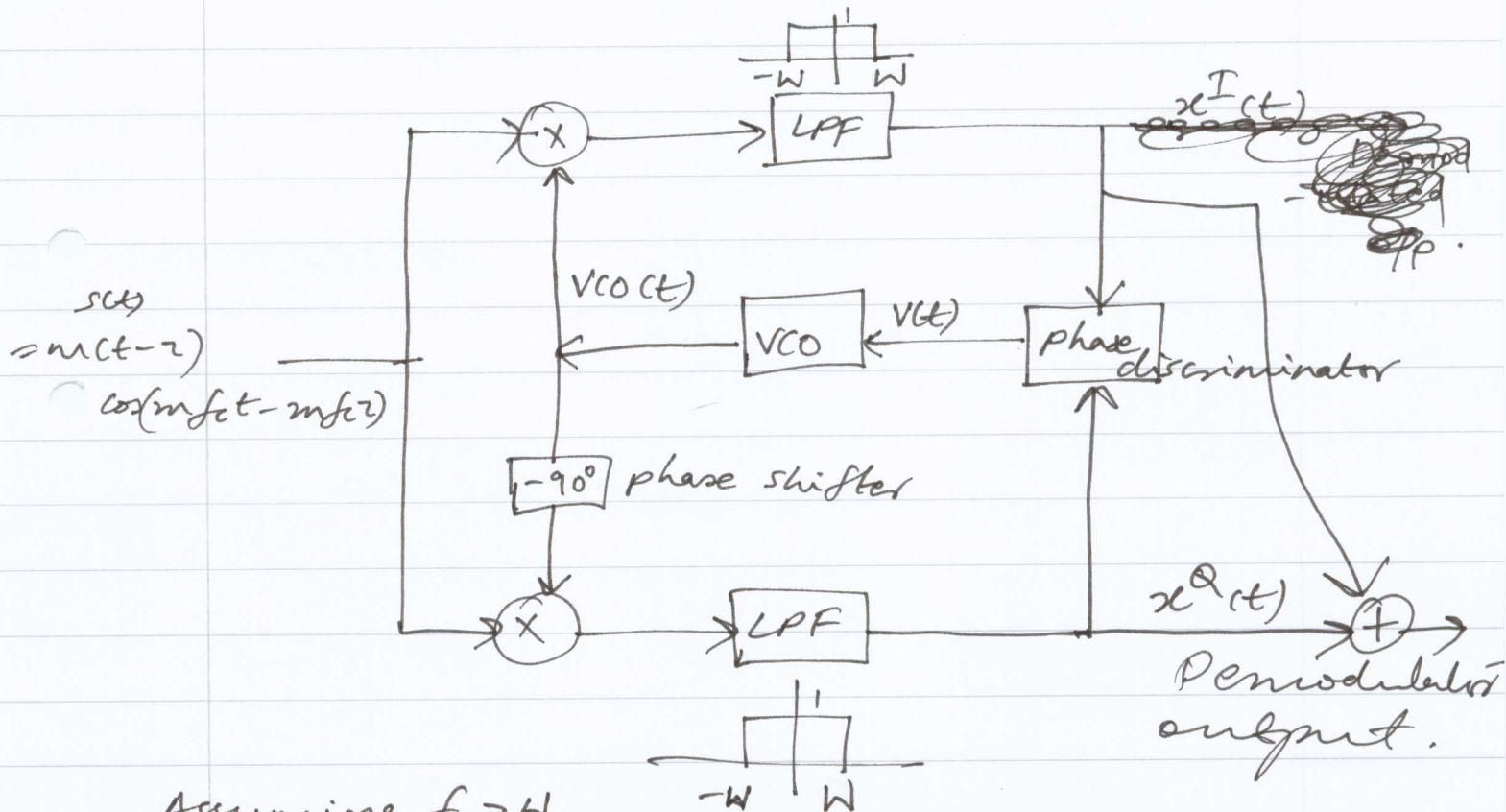
$$\text{VCO}(t) = A_{\text{VCO}} \cos(\phi_{\text{VCO}}(t))$$

$$v_{\text{CO}}(t) = A_{\text{VCO}} \cos(m_f t + \phi_{\text{VCO}}(0) + 2\pi k \int_0^t v_{\text{CO}}(t') dt)$$

(4)

(COSTAS RECEIVER.)

A COHERENT RECEIVER.



Assuming  $f_c > \omega$ , we get

$$x^I(t) = \frac{A_{\text{VCO}}}{2} m(t-\tau) \cos \phi_e(t) \quad \text{and}$$

$$x^Q(t) = \frac{A_{\text{VCO}}}{2} m(t-\tau) \sin \phi_e(t)$$

where

$$\phi_e(t) \triangleq 2\pi f_c t + \phi_{\text{VCO}}(0) + 2\pi k \int_0^t v_{\text{CO}}(t') dt$$

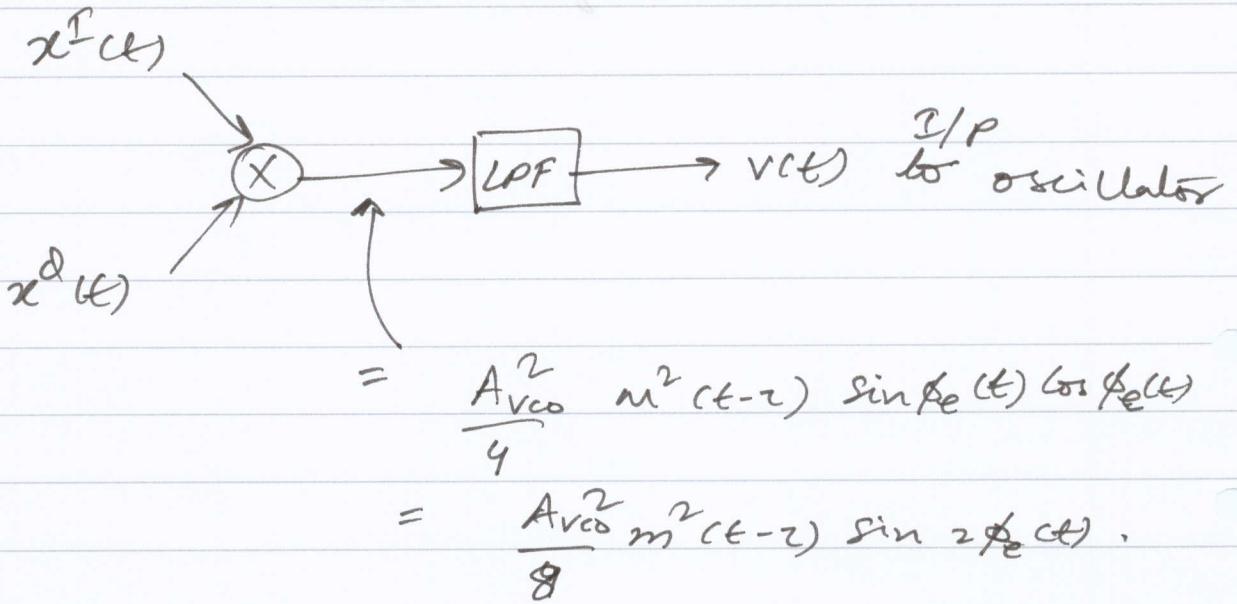
$$\therefore \frac{d\phi_e(t)}{dt} = 2\pi k v_{\text{CO}}(t).$$

We would ideally like the demodulated op

$$(x^Q(t) + x^I(t)) = \frac{A_{\text{VCO}}}{2} m(t-\tau),$$

~~demodulated~~

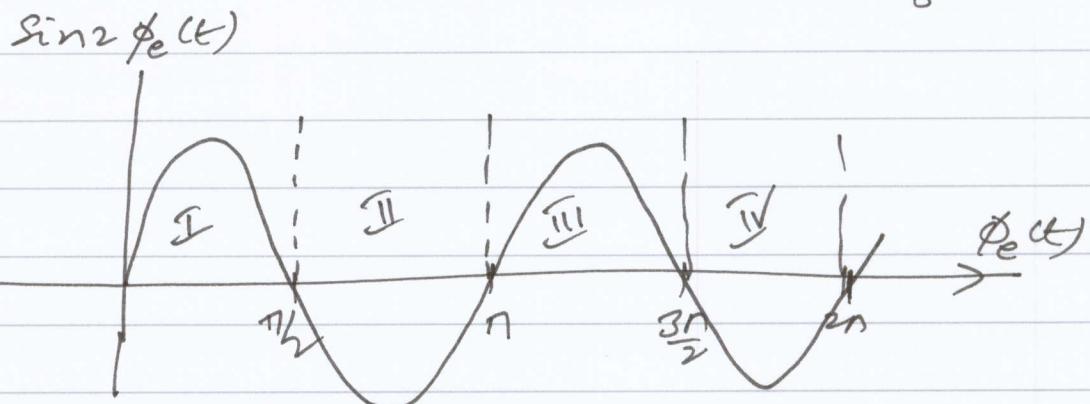
## Phase discriminator



$$v(t) = \frac{A_{vco}^2 c}{8} \sin 2\phi_e(t) \quad \text{where } c > 0$$

is the p.c.

component of  $m^2(t-2)$ .



As  $t \rightarrow \infty$ , what are the possible values for  $\phi_e(t)$ .

since  $\frac{d\phi_e(t)}{dt} = 2\pi k v(t)$ ,

equilibrium point (after which  $\phi_e(t)$  and  $v(t)$  do not change)

are clearly  $\phi_e(t) = 0, \pi, \pi, 3\pi/2 \pmod{2\pi}$

(b)

this is because for each of these

values of  $\phi_e(t)$ ,  $\sin 2\phi_e(t) = 0$  and

therefore

$$\frac{d\phi_e(t)}{dt} = \omega_0 v(t)$$

$$= 2\pi k \cdot \frac{A v_{co}^2}{8} c \sin 2\phi_e(t)$$

$$= 0, \text{ i.e., } \phi_e(t)$$

stabilizes.  
does not change.

But which of these four locations  
is a stable equilibrium point?

If  $\phi_e(t)$  is in region I (see the figure)

then  $\sin 2\phi_e(t) > 0$ , i.e.,  $v(t) > 0$  and

therefore the oscillator phase increases  
resulting in  $\frac{d\phi_e(t)}{dt} > 0$  (since  $\frac{d\phi_e(t)}{dt} = \omega_0 v(t)$ )

$\therefore \phi_e(t)$  increases till it exceeds  $\pi/2$

(i.e. it enters region II). In region II,

$\sin 2\phi_e(t) < 0 \Rightarrow v(t) < 0 \Rightarrow \frac{d\phi_e(t)}{dt} < 0$ ,

and therefore  $\phi_e(t)$  reverts back to  $\pi/2$ .

It can shown (by similar arguments)  
that  $\phi_e(t) = \pi/2$  and  $\phi_e(t) = 3\pi/2$  are  
the two stable equilibrium  
points.

(1) (7)

For both  $\phi_e(t) = \frac{\pi}{2}$  and  $\phi_e(t) = \frac{3\pi}{2}$ ,

$$x^I(t) = \frac{A_{VCO} m(t-\tau)}{2} \cos \phi_e(t) = 0, \text{ and}$$

$$\begin{aligned} x^Q(t) &= \frac{A_{VCO} m(t-\tau)}{2} \sin \phi_e(t) \\ &= \pm \frac{A_{VCO} m(t-\tau)}{2} \end{aligned}$$

therefore the demodulator output  
has a sign ambiguity.