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Transmission of a W.S.S. through a
random LTI filter.



Let $N(t)$ be a wide sense stationary (W.S.S) random process which is the input to a LTI filter characterized by its impulse response $h(t)$.

$N(t)$ therefore satisfies the following

P-i) $E[N(t_1)] = E[N(t_2)]$ for any t_1, t_2

P-ii) $E[N(t_1) N^*(t_2)] = E[N(t_1 + T) N^*(t_2 + T)]$
for any t_1, t_2, T .

From P-ii) we can define the autocorrelation function of $N(t)$ as

$$R_N(\tau) = E[N(t) N^*(t-\tau)] \quad \text{--- ①}$$

We will show that $W(t)$ is also W.S.S. (2)
 We need to therefore prove that $W(t)$
 also satisfies the W.S.S. properties

P-i) and P-ii).

We firstly have

$$W(t) = \int h(\tau) N(t-\tau) d\tau \quad \text{--- (2)}$$

$$\begin{aligned} \therefore E[W(t)] &= E\left[\int h(\tau) N(t-\tau) d\tau\right] \\ &= \int h(\tau) E[N(t-\tau)] d\tau \quad (\text{since } E[\cdot] \text{ is a linear operator}) \\ &= \int h(\tau) E[N(0)] d\tau \\ &= E[N(0)] \int h(\tau) d\tau \quad (\text{since } N(\cdot) \text{ is W.S.S., mean is constant}) \end{aligned}$$

which is a constant and does not depend upon t .

This proves P-i) for $W(t)$. Next we try to prove P-ii) for $W(t)$.

$$\begin{aligned} E[W(t_1) W^*(t_2)] &= E\left[\int h(\tau_1) N(t_1-\tau_1) d\tau_1 \int h^*(\tau_2) N^*(t_2-\tau_2) d\tau_2\right] \\ &= E\left[\iint h(\tau_1) h^*(\tau_2) N(t_1-\tau_1) N^*(t_2-\tau_2) d\tau_1 d\tau_2\right] \\ &= \iint h(\tau_1) h^*(\tau_2) E[N(t_1-\tau_1) N^*(t_2-\tau_2)] d\tau_1 d\tau_2 \quad \text{--- (3)} \end{aligned}$$

Since $N(t)$ is W.S.S, from P-ii) (3)
we get

$$E [N(t_1 - \tau) N^*(t_2 - \tau)] = R_N(\tau - \tau + t_1 - t_2).$$

\therefore using this in (3) we set

$$E [W(t_1) W^*(t_2)]$$

$$= \iint h(\tau) h^*(\tau_2) R_N(\tau_2 - \tau + t_1 - t_2)$$

$d\tau d\tau_2$
— (4)

which clearly depends only on the
time difference $(t_1 - t_2)$.

We will next study the conditions under
which the output process $W(t)$ has
finite power (i.e., $E |W(t)|^2 < \infty$).

$$E |W(t)|^2 = R_W(0) \quad (\text{using (4) we set})$$

$$= \iint h(\tau) h^*(\tau_2) R_N(\tau_2 - \tau) d\tau d\tau_2$$

$$\leq \iint |h(\tau) h^*(\tau_2) R_N(\tau_2 - \tau)| d\tau d\tau_2$$

$$\leq R_N(0) \iint |h(\tau) h^*(\tau_2)| d\tau d\tau_2$$

where we have used the fact that
for any W.S.S $|R_N(\tau)| \leq R_N(0)$.

$$\begin{aligned} \therefore E |W(t)|^2 &\leq R_W(0) \iint |h(z_1)| |h(z_2)| dz_1 dz_2 \\ &= R_W(0) \left[\int |h(z)| dz \right]^2. \end{aligned} \quad (4)$$

From ~~we~~ here, we can conclude that-

$$E |W(t)|^2 < \infty \quad \text{if} \quad R_W(0) = E |W(t)|^2 < \infty$$

and $\int |h(z)| dz < \infty$, i.e., if the input has finite power and the LTI filter is stable.

Properties of P.S.D.

a) $S_N(f) \geq 0$ for all f .

(from definition, $S_N(f)$ is the power in a narrow band $[f - \frac{\Delta f}{2}, f + \frac{\Delta f}{2}]$ ~~centered~~ centered at f , and since power is non-negative)

b) If $W(t)$ is real, then

$$S_N(f) = S_N(-f).$$

Ex: $X(t) = A \cos(2\pi f_c t + \theta)$, $\theta \sim \text{unif}[-\pi, \pi]$.

$$S_X(f) = \frac{A^2}{4} [\delta(f - f_c) + \delta(f + f_c)].$$