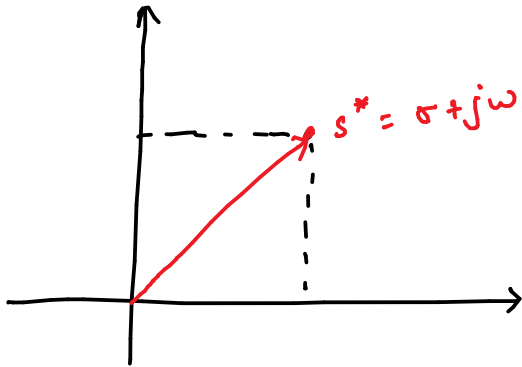


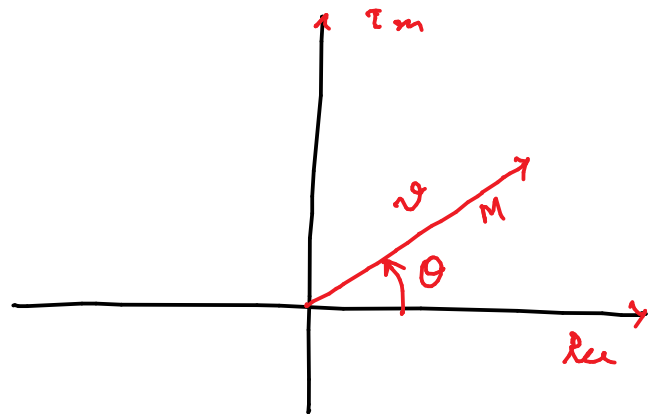
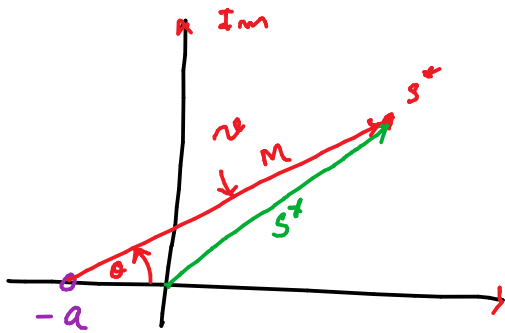
Lecture - 21

$$F(s) = s + a$$

$$s^* = \sigma + j\omega$$

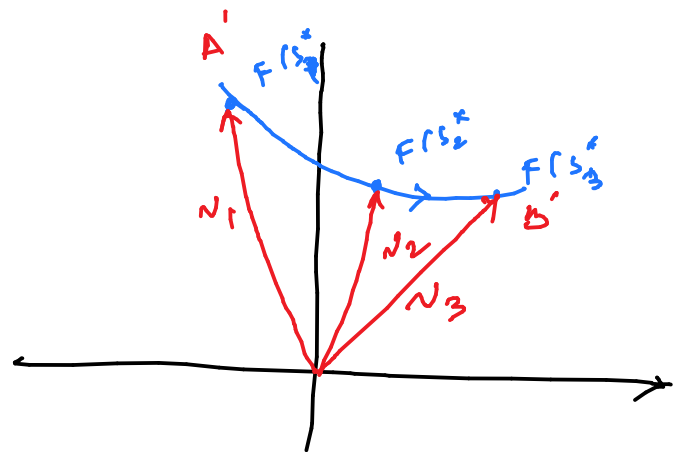
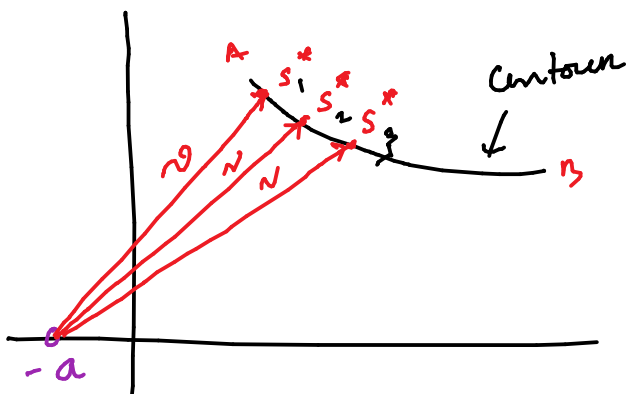


$$\begin{aligned} \mathcal{V} &= F(s^*) \\ &= |F(s^*)| \angle F(s^*) \\ &\quad m \quad \theta \end{aligned}$$



s-plane

F(s)-plane



$$F(s) = s + a$$

s-plane

F(s)-plane

$$F(s) = \frac{(s+z_1)(s+z_2) \dots (s+z_m)}{(s+p_1)(s+p_2) \dots (s+p_n)}$$

$$r_{z_i} = |s^* + z_i|$$

$$\theta_{z_i} = \angle s^* + z_i$$

$$r_{p_i} = |s^* + p_i|$$

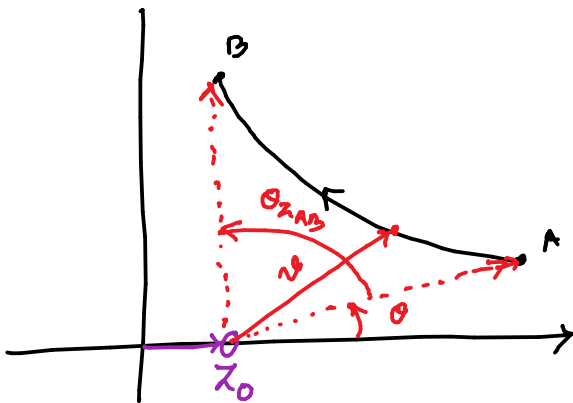
$$\theta_{p_i} = \angle s^* + p_i$$

$$v = F(s^*) = M \angle \theta$$

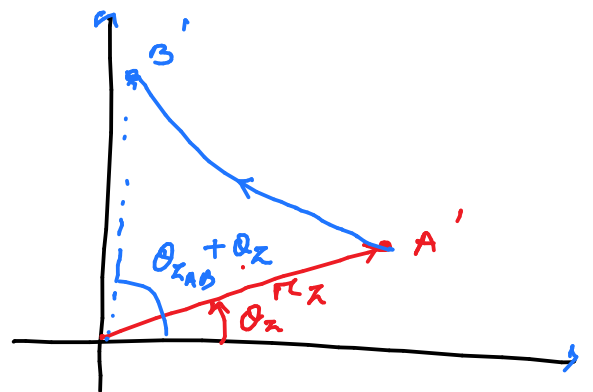
$$M = \frac{r_{z_1} r_{z_2} \dots r_{z_m}}{r_{p_1} r_{p_2} \dots r_{p_n}}$$

$$\theta = \sum \theta_{z_i} - \sum \theta_{p_i}$$

$$\rightarrow F(s) = s - z_1$$



s-plane



F(s)-plane

At point A:

$$M = r_z$$

$$\theta = \theta_z$$

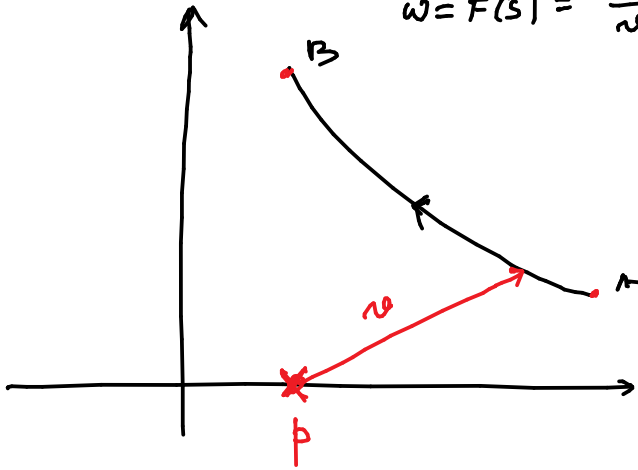
Moving from point A → B

$$M = r_z \text{ (decreases) } \& \text{ then increases}$$

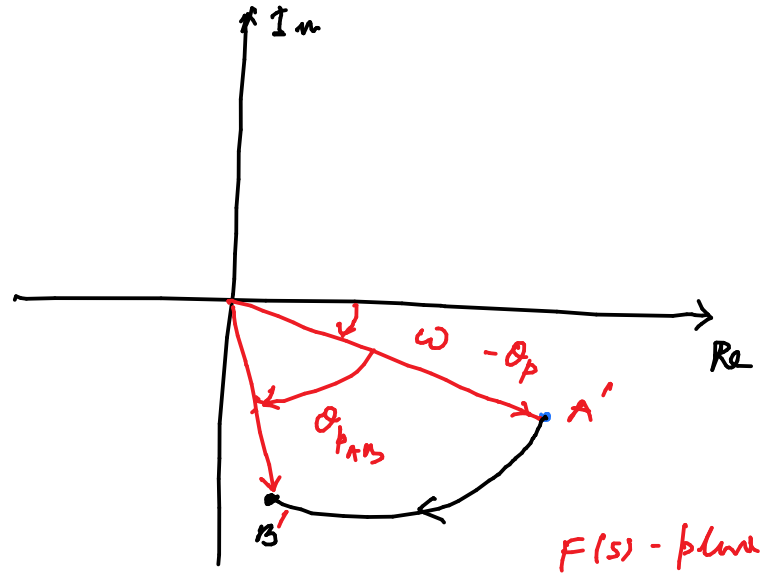
$$\theta = \theta_{z \rightarrow B} \text{ (in counter clockwise direct)}$$

$$F(s) = \frac{1}{s-p}$$

$$w = F(s) = \frac{1}{s}$$



$$w = s-p \quad s-p \text{ line}$$



$F(s)$ -plane

At point A

$$M = \frac{1}{r_p}$$

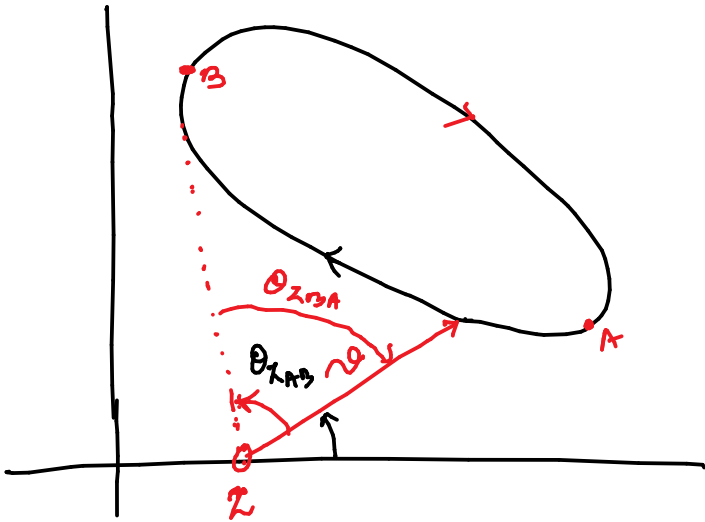
$$\theta = -(\theta_p) \\ = -\theta_p$$

Same for $A \rightarrow B$

$$M = \frac{1}{r_p}$$

$$\theta = -(\theta_{PAB}) \\ = -\theta_{PAB}$$

$$F(s) = s - z$$



s -plane

At point A

$$M = r_z$$

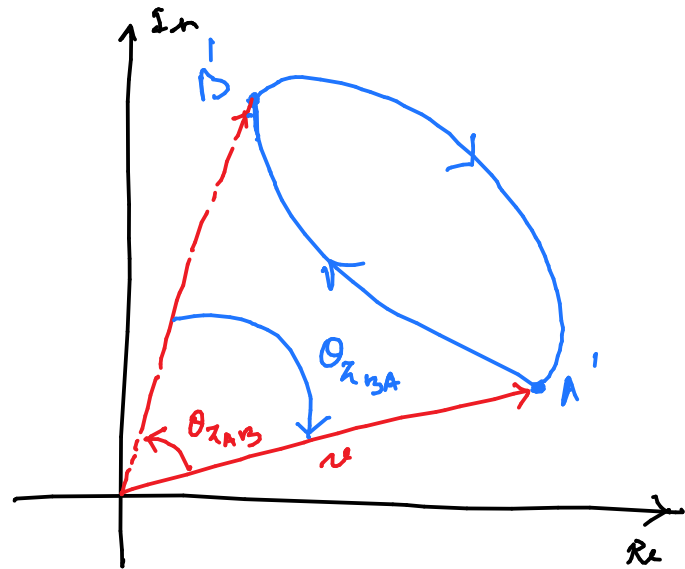
$$\theta = \theta_z$$

Moving from B to A

$$M = r_z$$

$$\theta = (-\theta_z) \text{ since clockwise rotation}$$

$$= -\theta_z$$



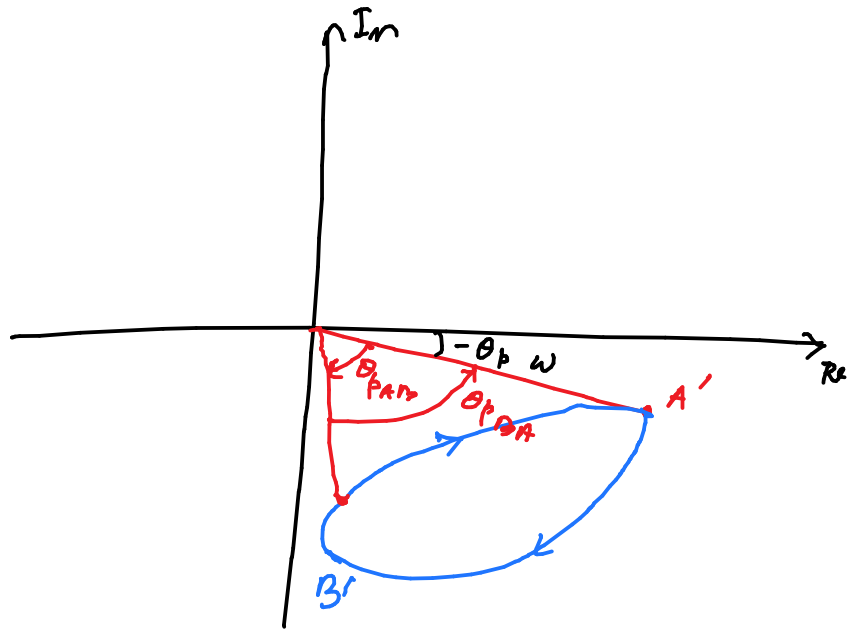
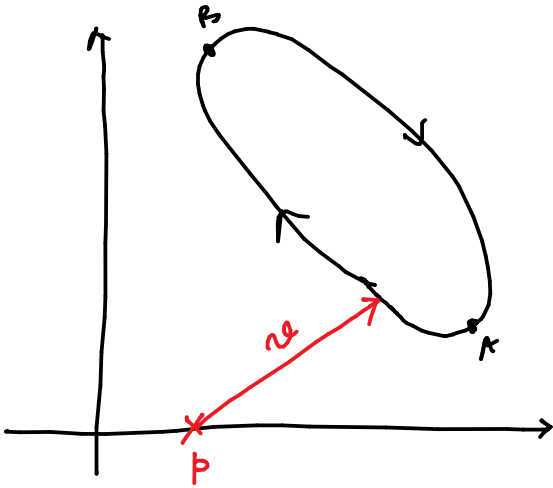
$F(s)$ -plane

Moving from A to B

$$M = r_z \text{ (decreases \& increases)}$$

$$\theta = \theta_z \text{ (in counter clockwise rot')}$$

$$F(s) = \frac{1}{s-p} \quad \omega = \frac{1}{\nu}$$



At point A

$$M = \frac{1}{r_p}$$

$$\theta = -(\theta_p)$$

Moving from B → A

$$M = \frac{1}{r_p}$$

$$\theta = 0 - (-\theta_{pBA})$$

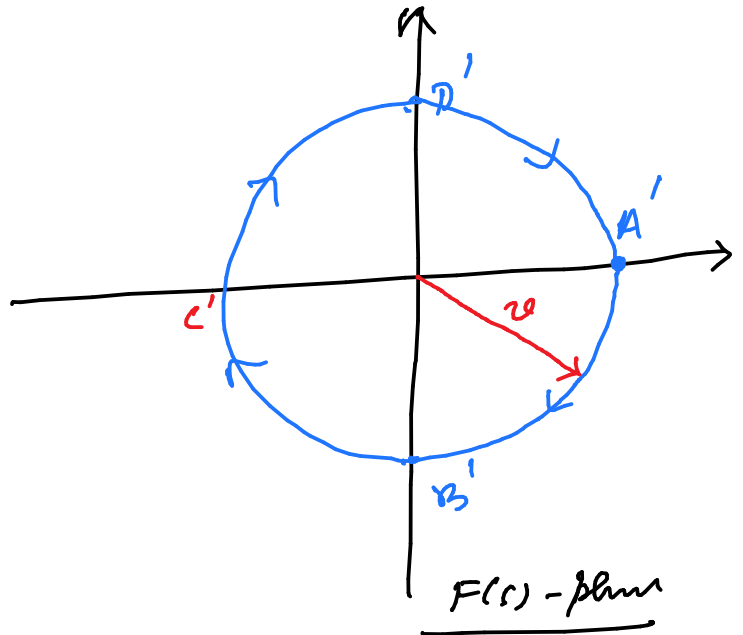
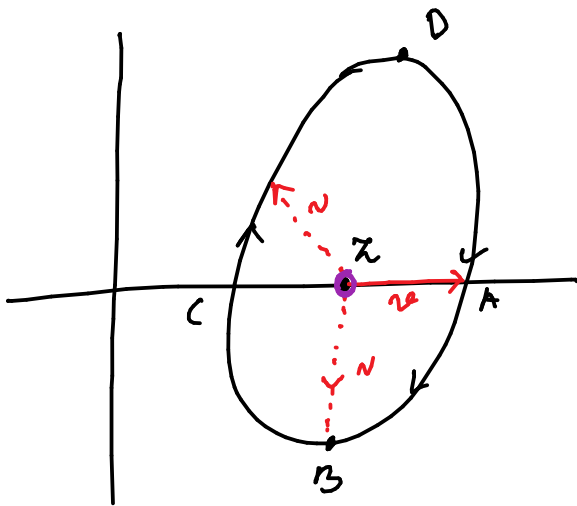
$$= \theta_{pBA}$$

Moving from A → B

$$M = \frac{1}{r_p}$$

$$\theta = -\theta_{pAB}$$

$$F(s) = s - z$$



Point A

$$M = r_z$$

$$\theta = \theta_z = 0$$

Moving from A \rightarrow B

$$M = r_z$$

$$\theta = \theta_z = -90^\circ$$

(90° in clockwise directⁿ)

Moving from B \rightarrow D

$$M = r_z$$

$$\theta = \theta_z$$

$$= -180^\circ \text{ (clockwise rotⁿ of } r)$$



r will rotate 180° in clockwise directⁿ in F(s)-plane

Moving from D \rightarrow A

$$M = r_z$$

$$\theta = \theta_z$$

$$= -90^\circ \text{ (in clockwise rotⁿ of } r)$$



r will rotate 90° in clockwise in F(s)-plane.

* One has to keep track of the vector r

in s-plane, in which direction (clockwise or counter clockwise) it is rotating, while traversing on the given contour.

The directⁿ of r or w in F(s)-plane needs to be determined based on that.