

Segmentation: MRFs and Graph Cuts

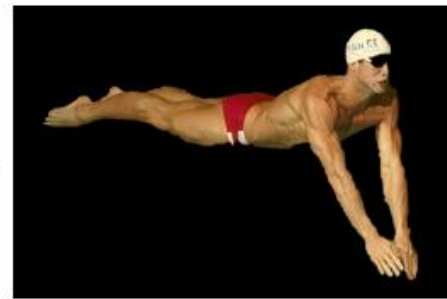
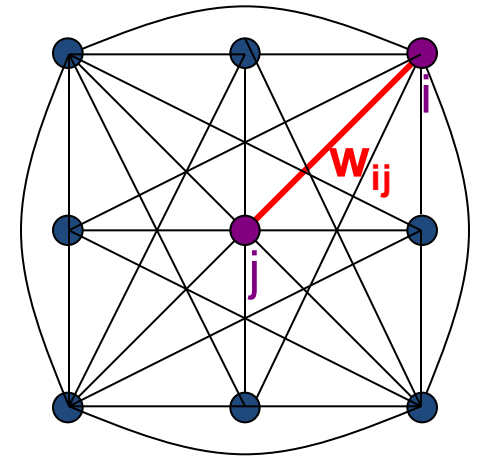
Computer Vision

CS 143, Brown

James Hays

Today's class

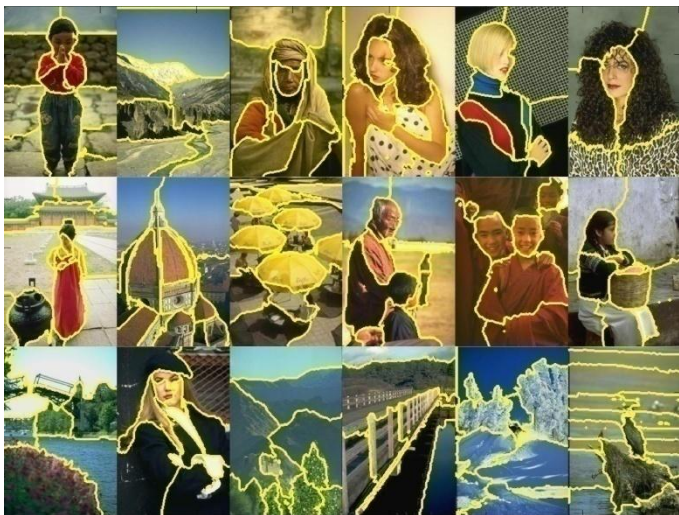
- Segmentation and Grouping
- Inspiration from human perception
 - Gestalt properties
- MRFs
- Segmentation with Graph Cuts



Grouping in vision

- **Goals:**
 - Gather features that belong together
 - Obtain an intermediate representation that compactly describes key image or video parts

Examples of grouping in vision



[Figure by J. Shi]

Determine image regions



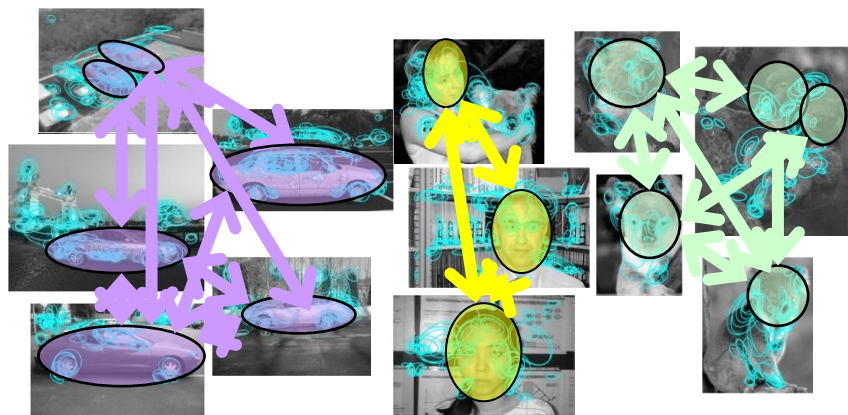
[http://poseidon.csd.auth.gr/LAB_RESEARCH/Latest/imgs/S_peakDepVidIndex_img2.jpg]

Group video frames into shots



[Figure by Wang & Suter]

Figure-ground



[Figure by Grauman & Darrell]

Object-level grouping

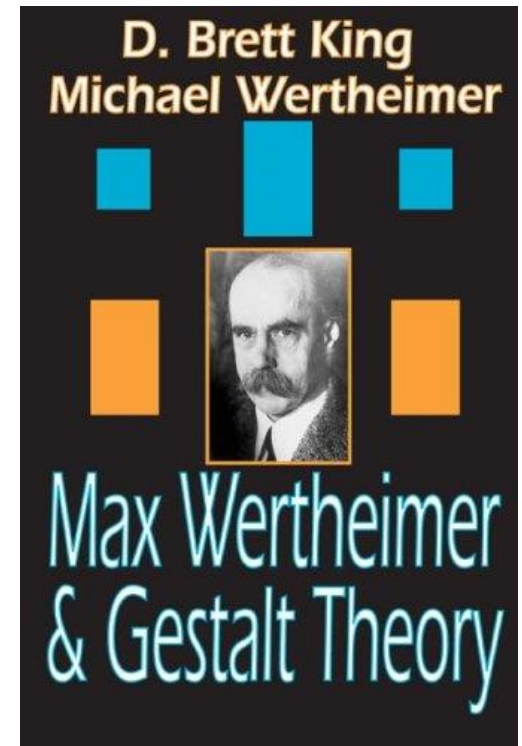
Grouping in vision

- Goals:
 - Gather features that belong together
 - Obtain an intermediate representation that compactly describes key image (video) parts
- Top down vs. bottom up **segmentation**
 - Top down: pixels belong together because they are from the same object
 - Bottom up: pixels belong together because they look similar
- Hard to measure success
 - What is interesting depends on the app.

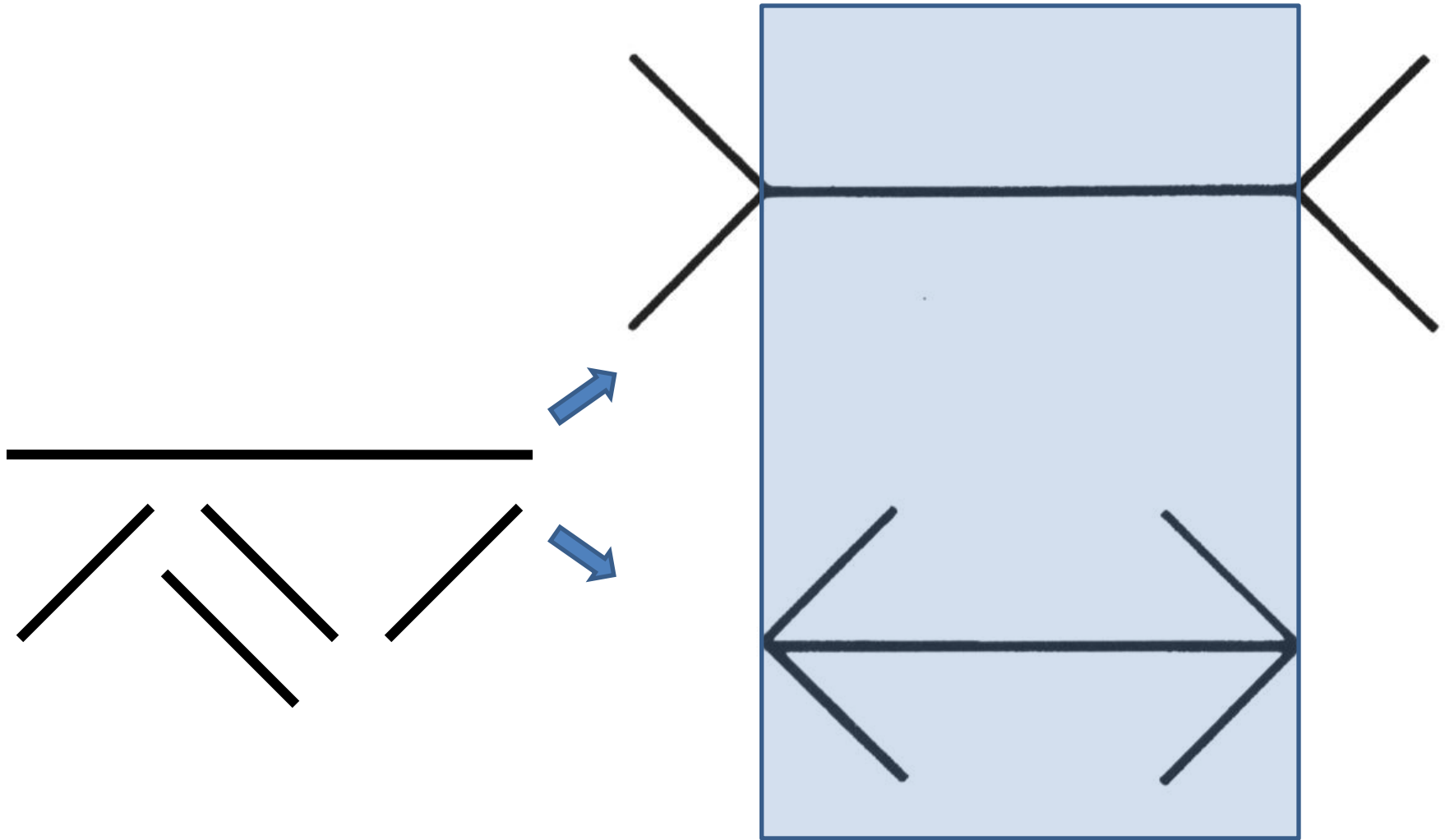
What things should be grouped?
What cues indicate groups?

Gestalt psychology or Gestaltism

- German: *Gestalt* - "form" or "whole"
- Berlin School, early 20th century
 - Kurt Koffka, Max Wertheimer, and Wolfgang Köhler
- Gestalt: whole or group
 - Whole is greater than sum of its parts
 - Relationships among parts can yield new properties/features
- Psychologists identified series of factors that predispose set of elements to be grouped (by human visual system)

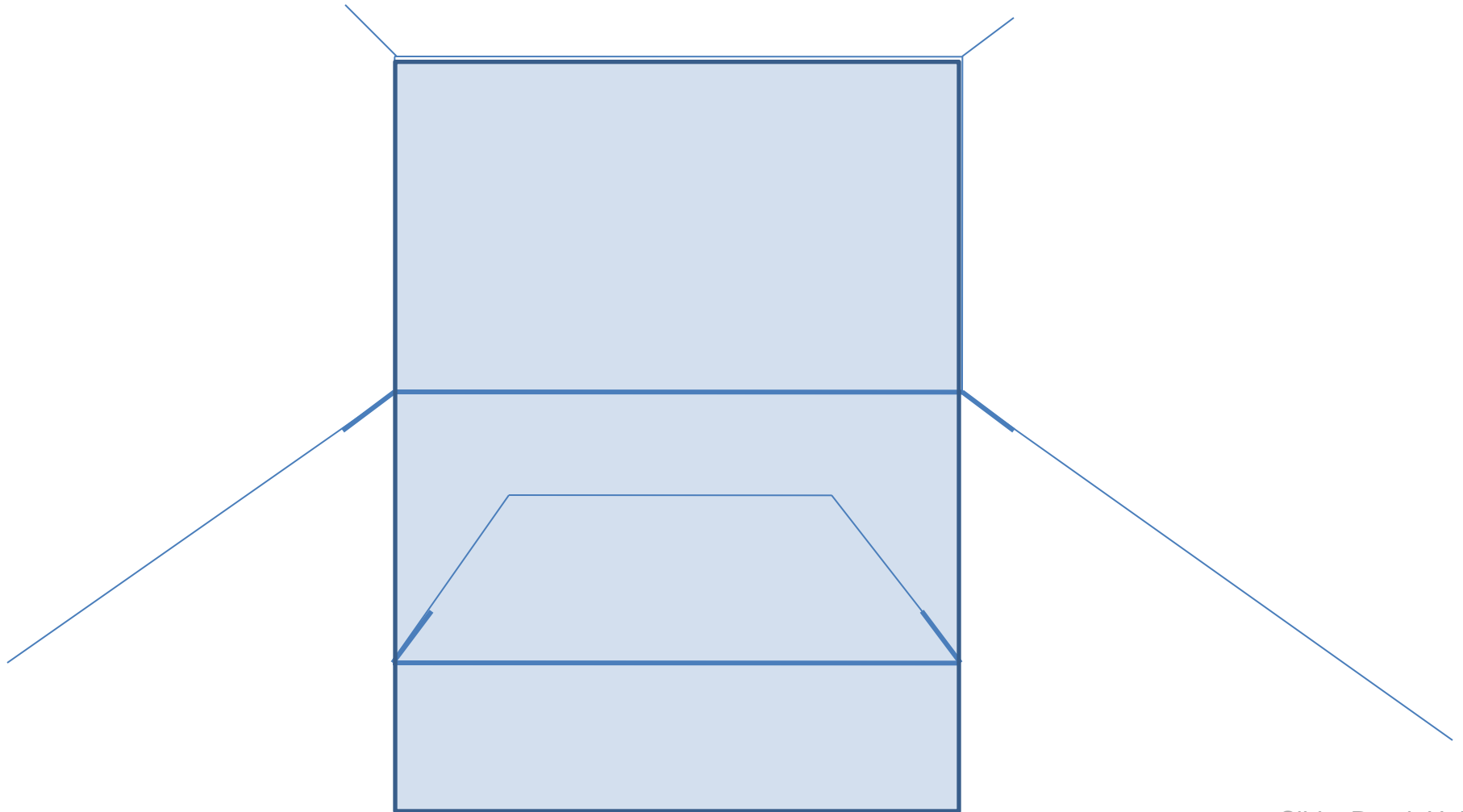


Gestaltism

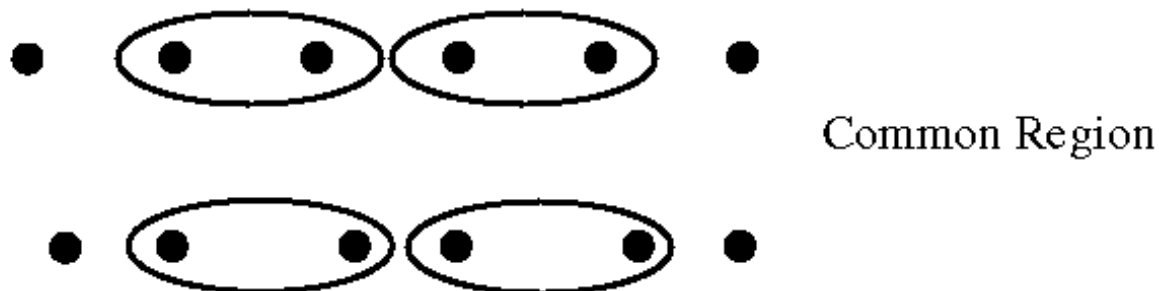
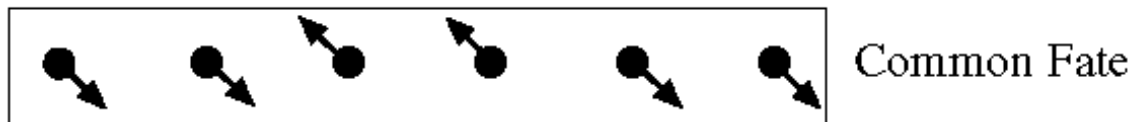
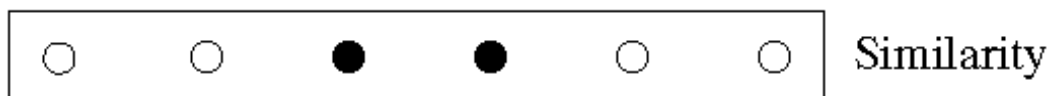
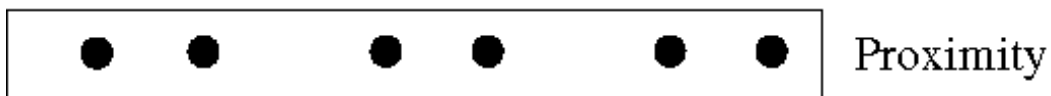
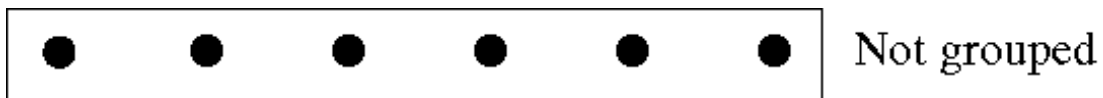


The Muller-Lyer illusion

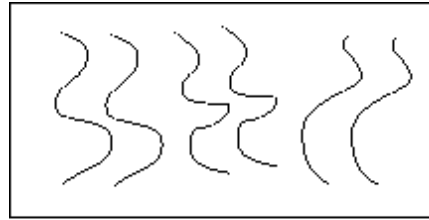
We perceive the interpretation, not the senses



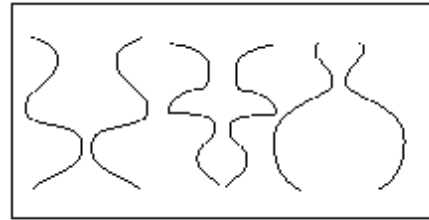
Principles of perceptual organization



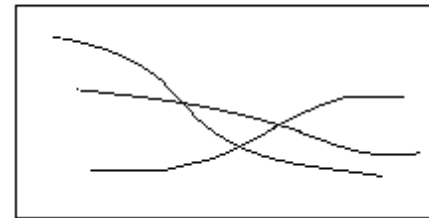
Principles of perceptual organization



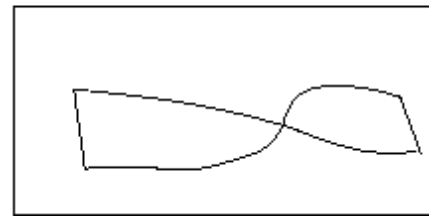
Parallelism



Symmetry



Continuity

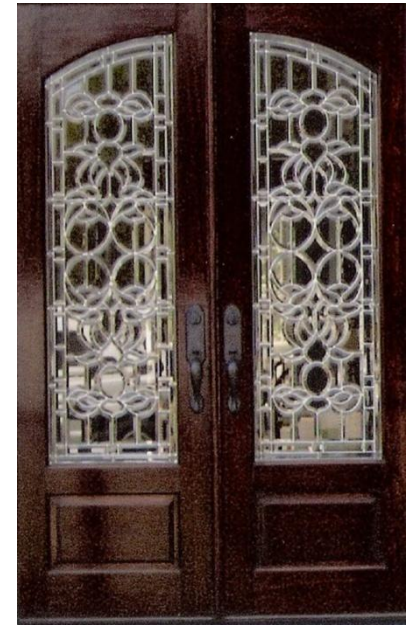
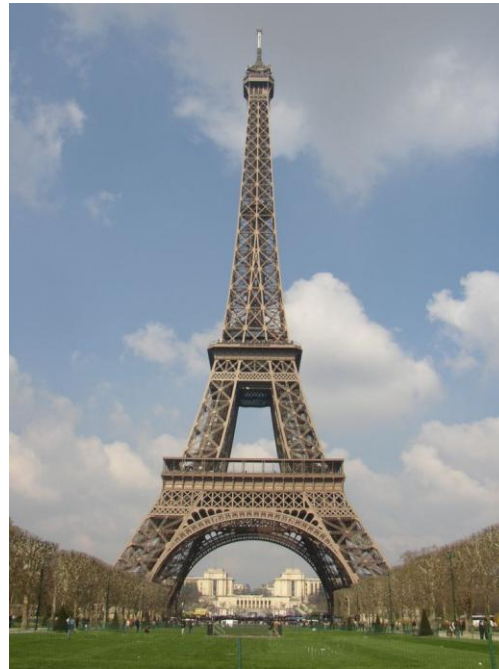


Closure

Similarity



Symmetry



Common fate

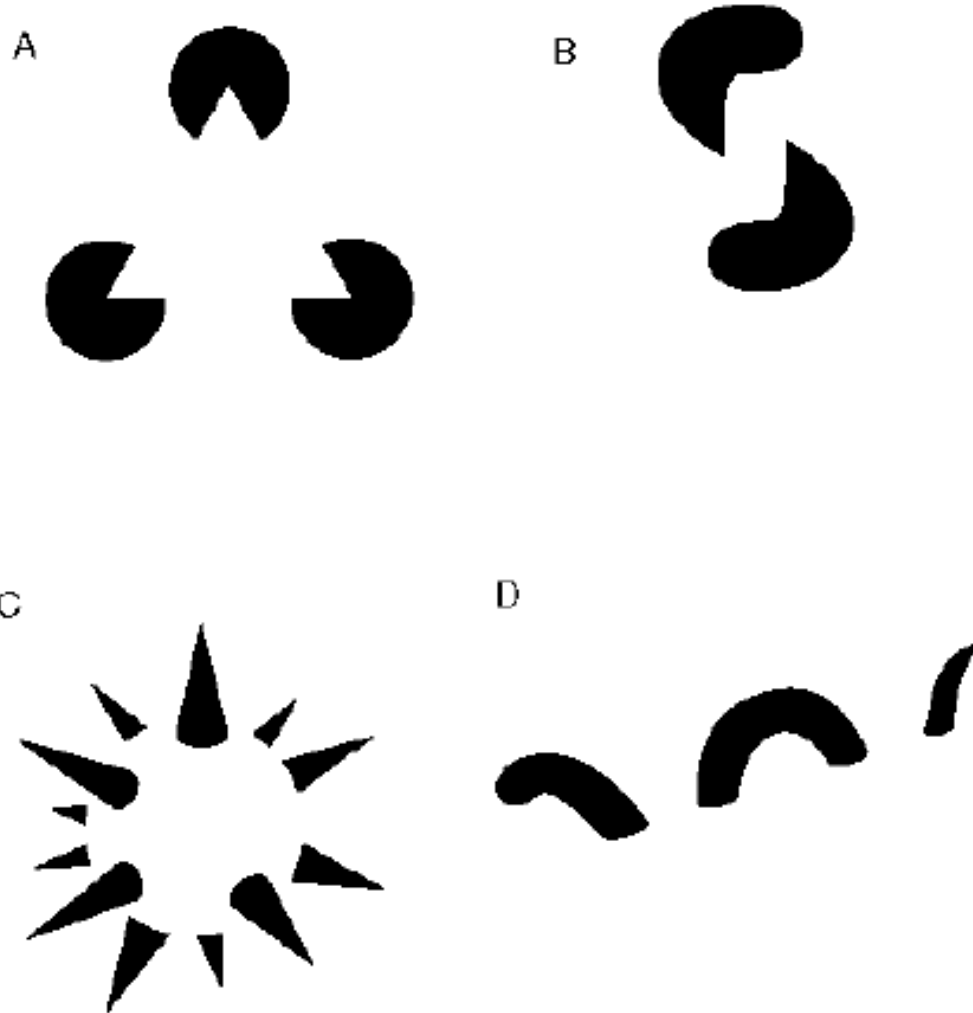


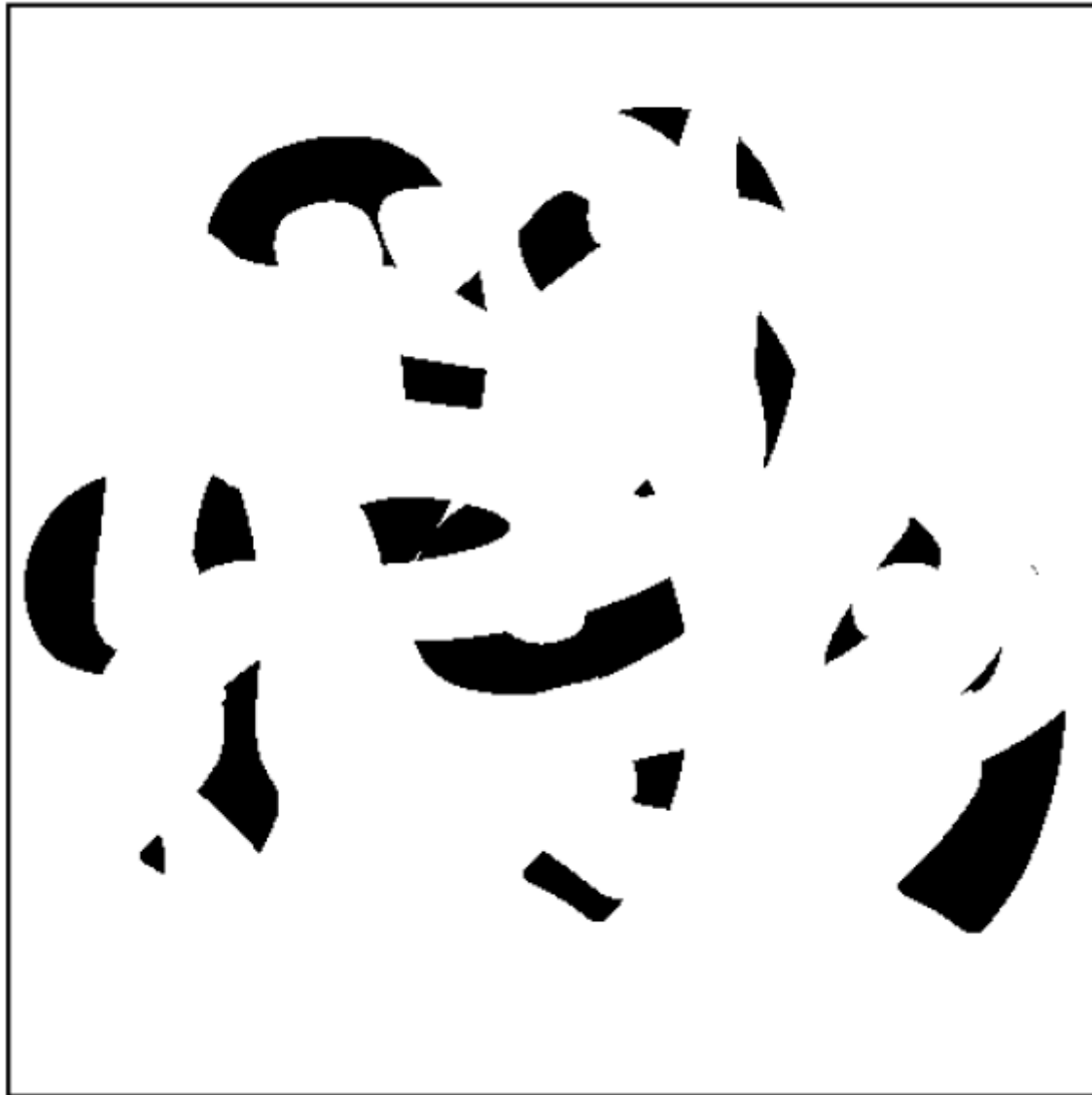
Image credit: Arthus-Bertrand (via F. Durand)

Proximity



Grouping by invisible completion







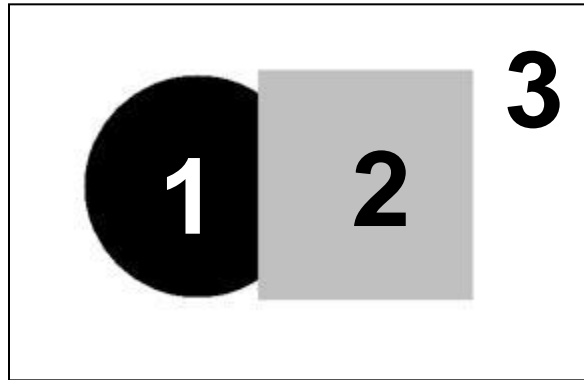
Emergence



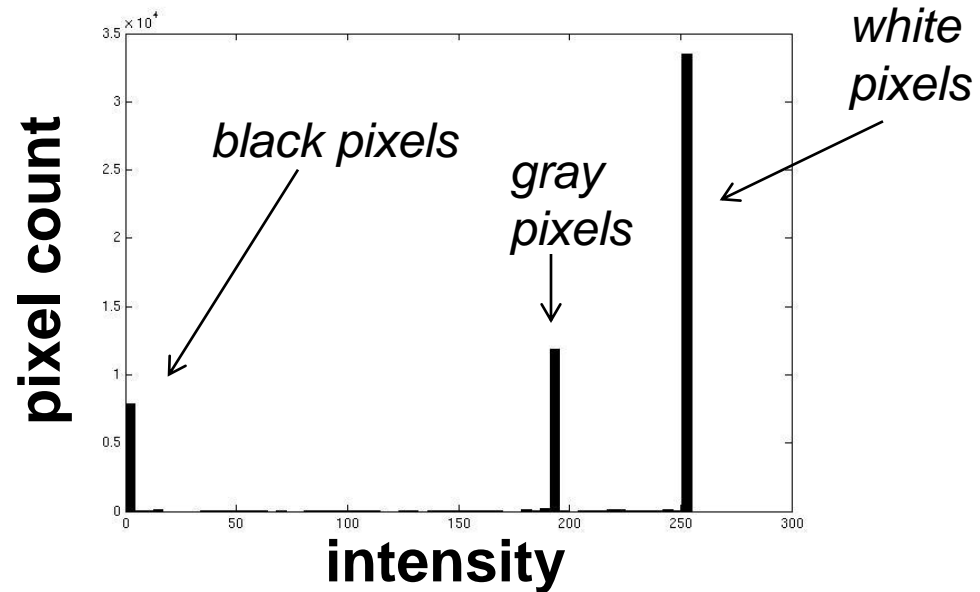
Gestalt cues

- Good intuition and basic principles for grouping
- Basis for many ideas in segmentation and occlusion reasoning
- Some (e.g., symmetry) are difficult to implement in practice

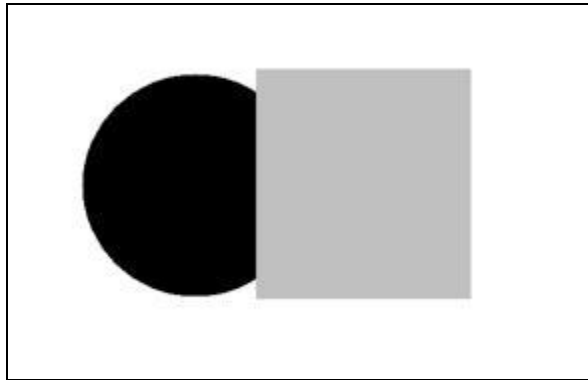
Image segmentation: toy example



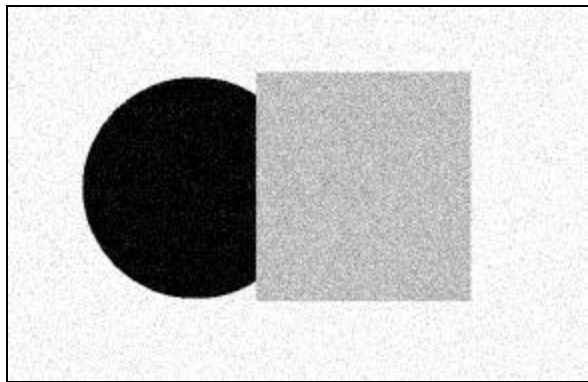
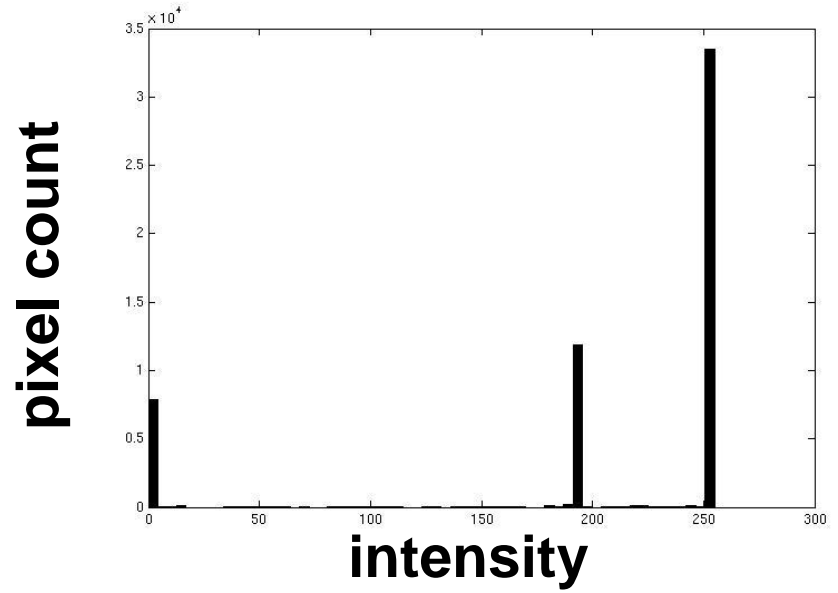
input image



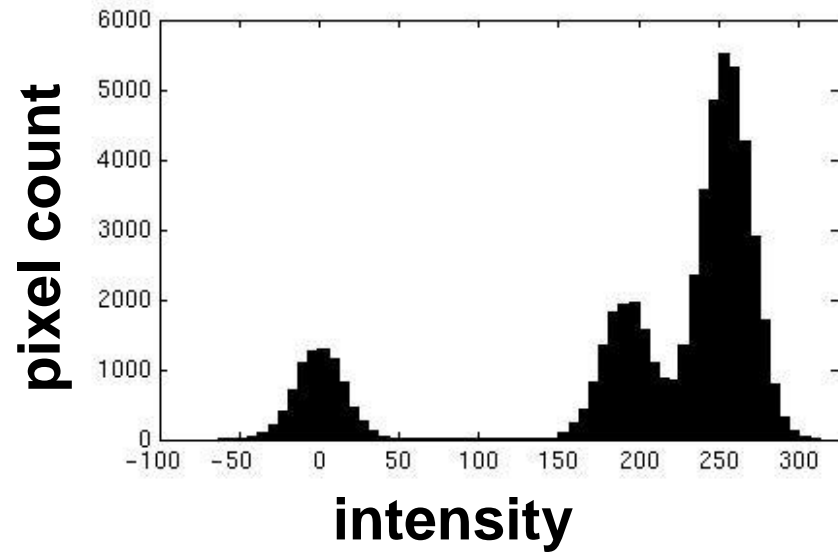
- These intensities define the three groups.
- We could label every pixel in the image according to which of these primary intensities it is.
 - i.e., *segment* the image based on the intensity feature.
- What if the image isn't quite so simple?

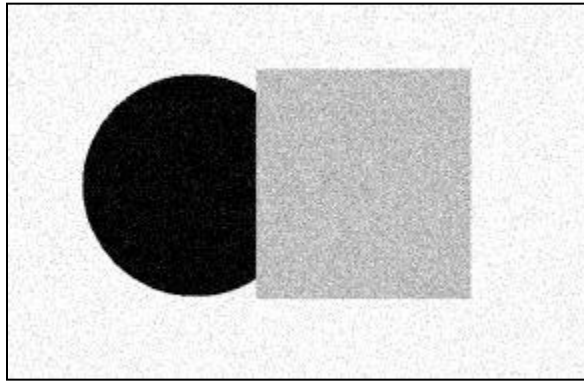


input image

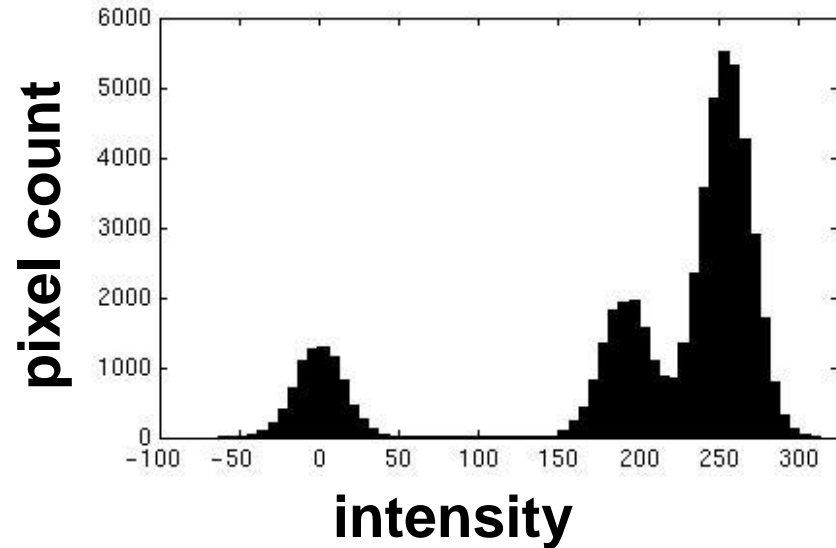


input image





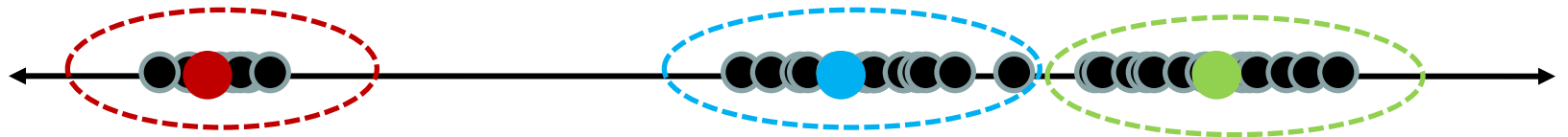
input image



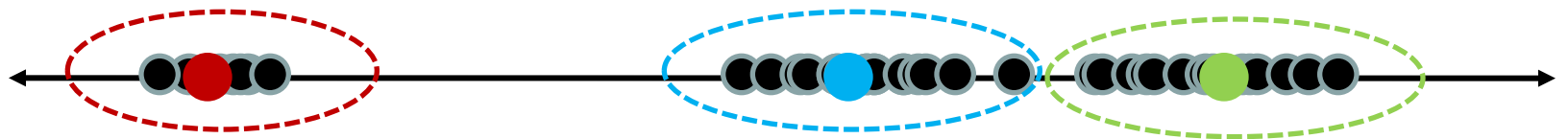
- Now how to determine the three main intensities that define our groups?
- We need to ***cluster***.

Clustering

- With this objective, it is a “chicken and egg” problem:
 - If we knew the **cluster centers**, we could allocate points to groups by assigning each to its closest center.

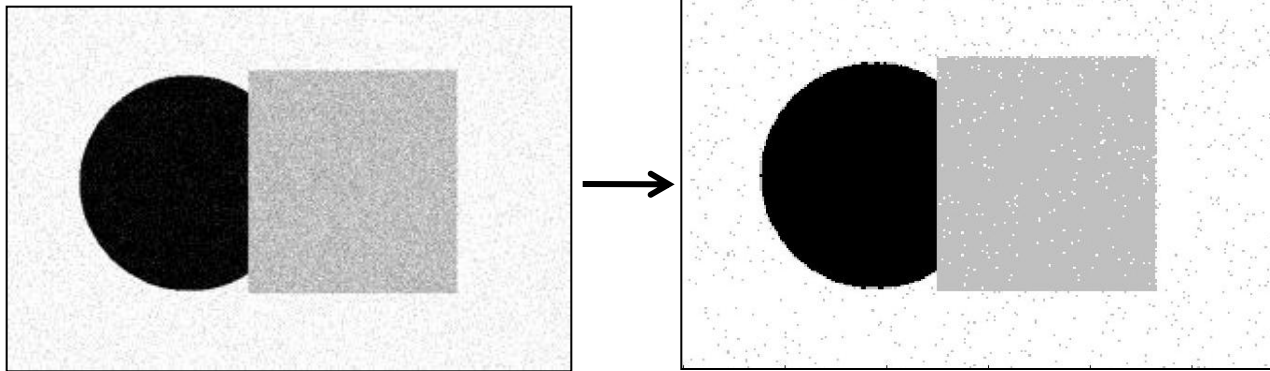


- If we knew the **group memberships**, we could get the centers by computing the mean per group.



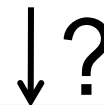
Smoothing out cluster assignments

- Assigning a cluster label per pixel may yield outliers:

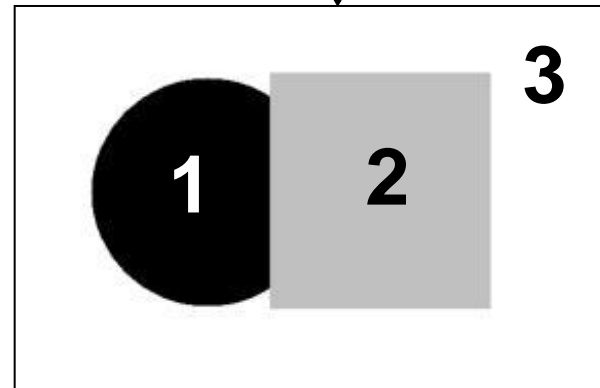


original

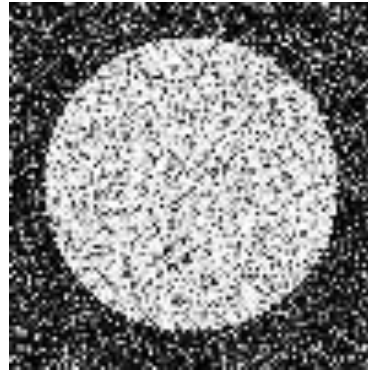
labeled by cluster center's
intensity



- How to ensure they are spatially smooth?



Solution



$P(\text{foreground} \mid \text{image})$

Encode dependencies between pixels

Normalizing constant

$$P(\mathbf{y}; \theta, data) = \frac{1}{Z} \prod_{i=1..N} f_1(y_i; \theta, data) \prod_{i,j \in \text{edges}} f_2(y_i, y_j; \theta, data)$$

Labels to be predicted

Individual predictions

Pairwise predictions

Writing Likelihood as an “Energy”

$$P(\mathbf{y}; \theta, data) = \frac{1}{Z} \prod_{i=1..N} p_1(y_i; \theta, data) \prod_{i,j \in edges} p_2(y_i, y_j; \theta, data)$$

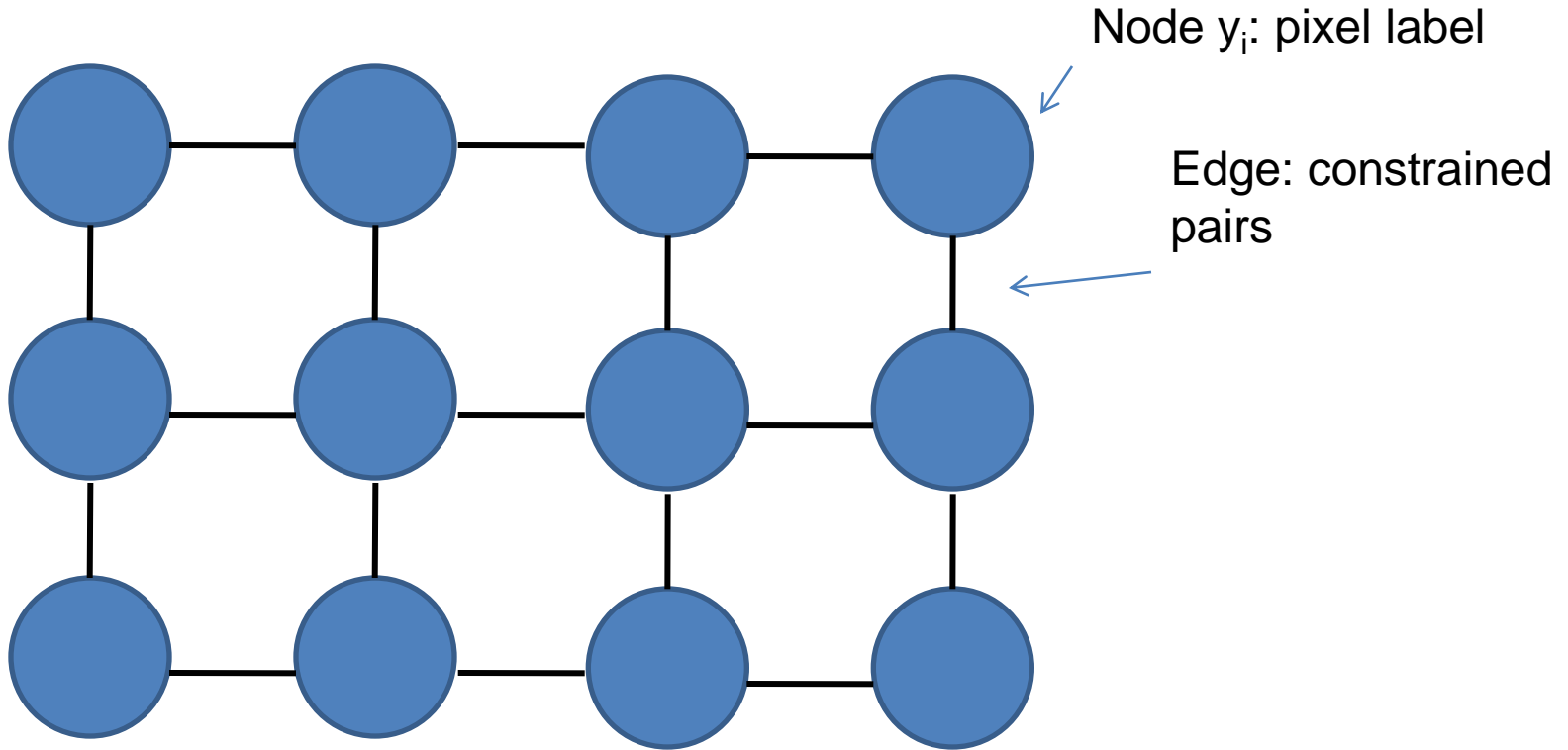


$$Energy(\mathbf{y}; \theta, data) = \sum_i \psi_1(y_i; \theta, data) + \sum_{i,j \in edges} \psi_2(y_i, y_j; \theta, data)$$

“Cost” of assignment y_i

“Cost” of pairwise assignment y_i, y_j

Markov Random Fields



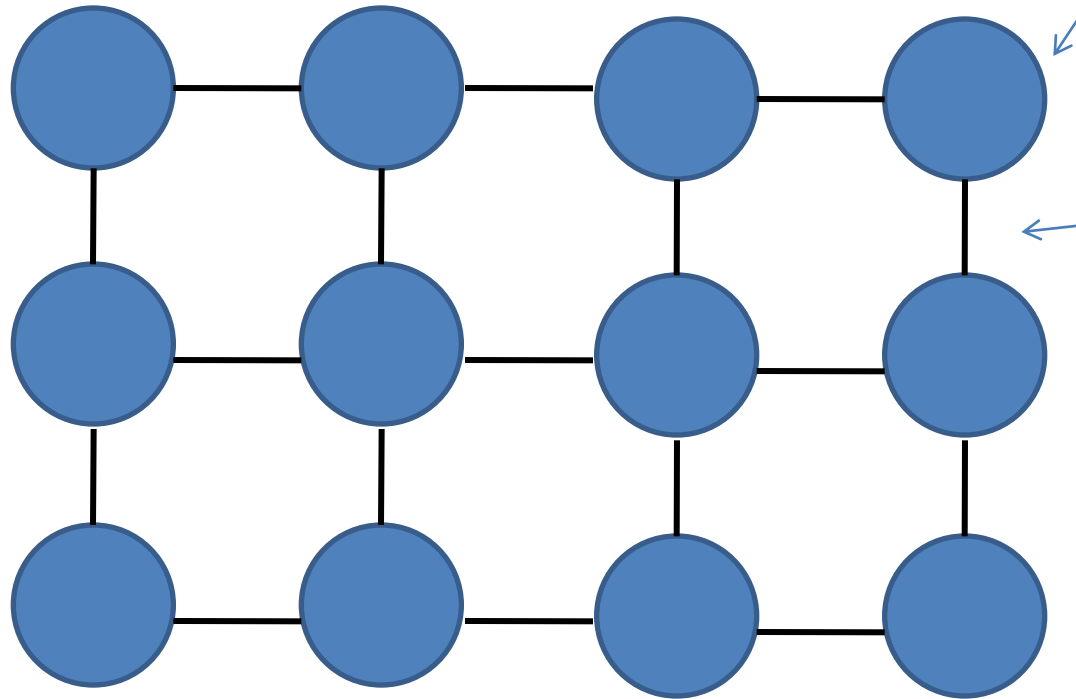
Cost to assign a label to each pixel

Cost to assign a pair of labels to connected pixels

$$Energy(\mathbf{y}; \theta, data) = \sum_i \psi_1(y_i; \theta, data) + \sum_{i,j \in edges} \psi_2(y_i, y_j; \theta, data)$$

Markov Random Fields

- Example: “label smoothing” grid



Unary potential

0: $-\log P(y_i = 0 ; \text{data})$

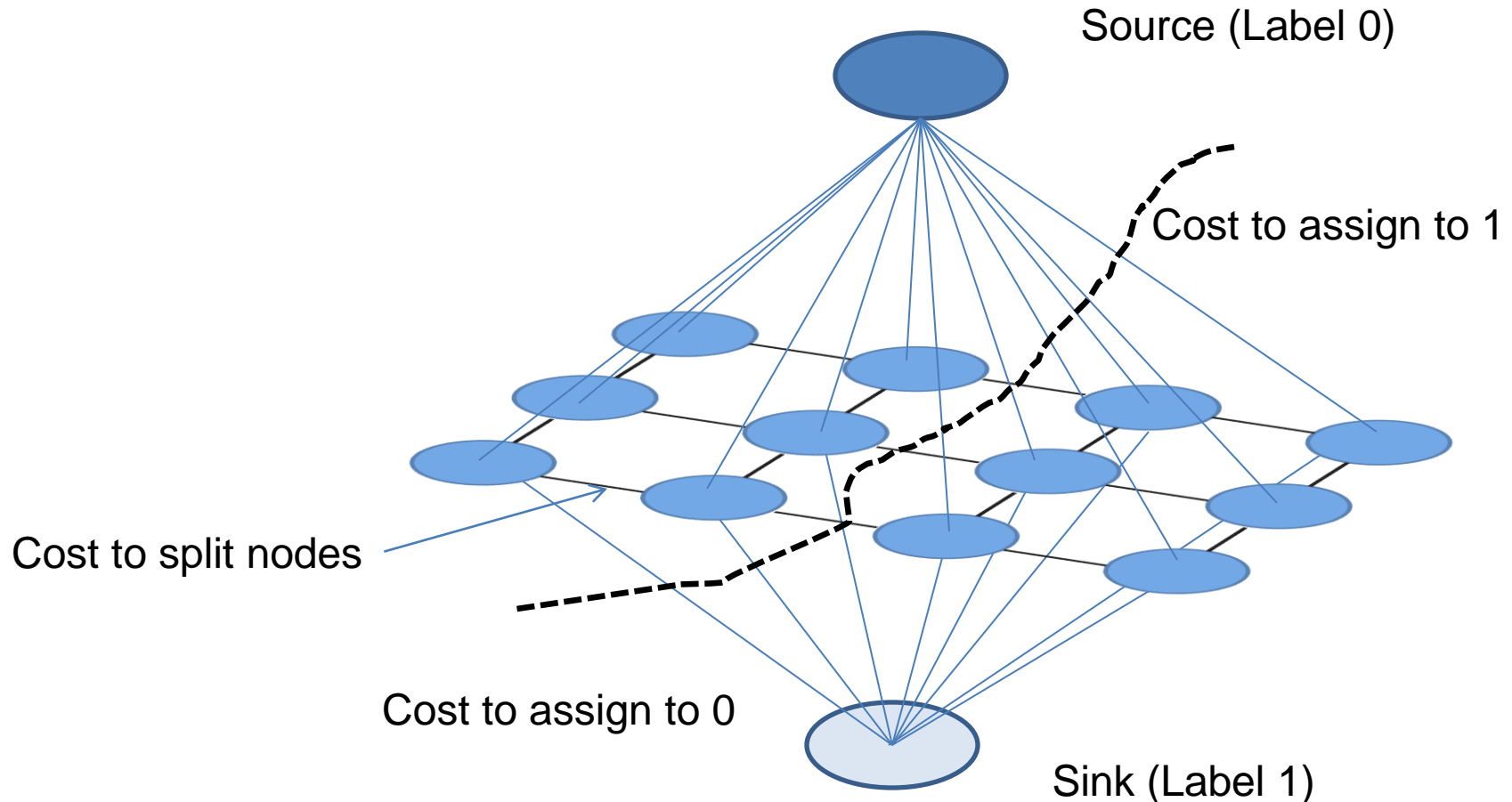
1: $-\log P(y_i = 1 ; \text{data})$

Pairwise Potential

	0	1
0	0	K
1	K	0

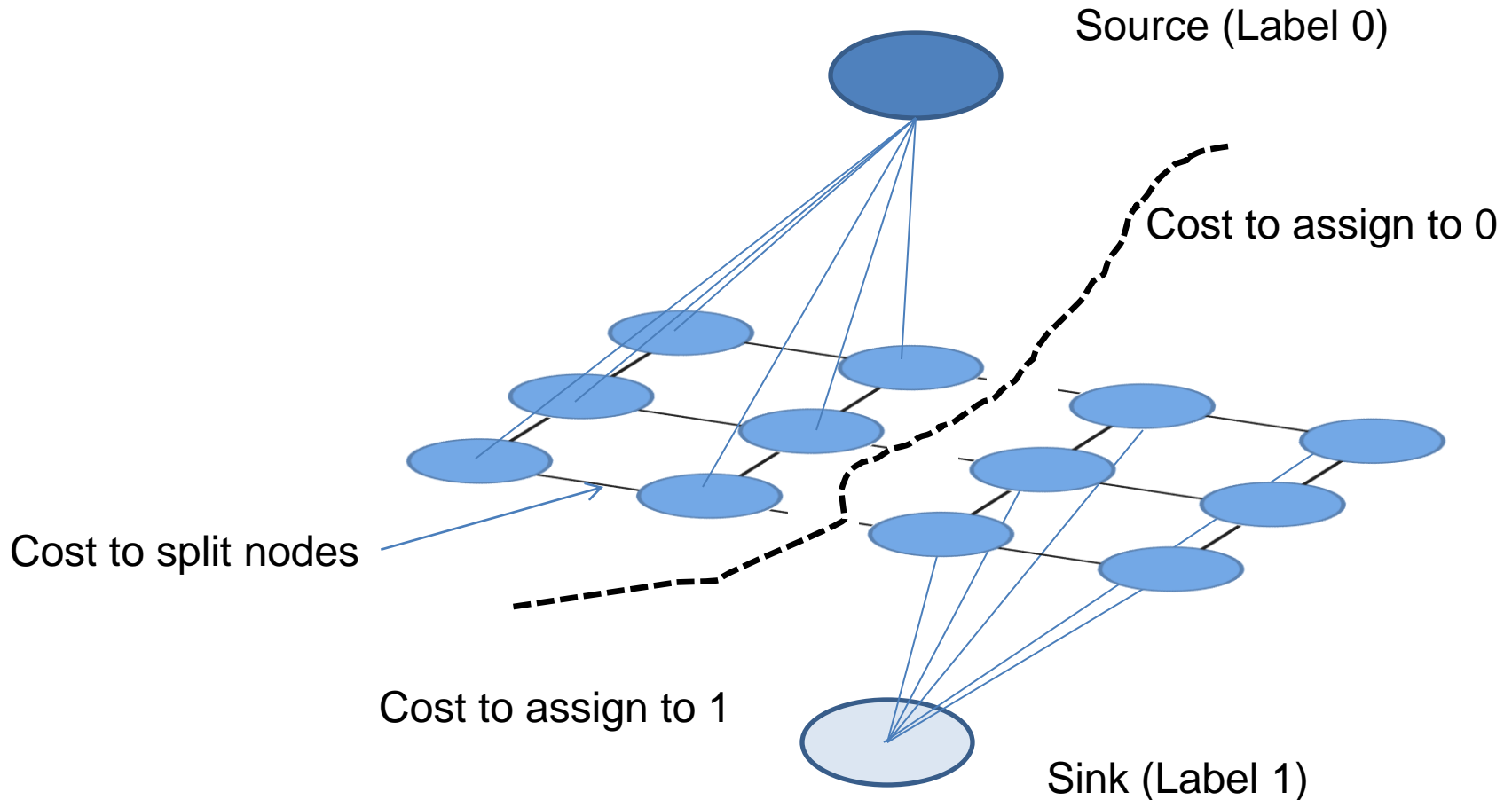
$$\text{Energy}(\mathbf{y}; \theta, \text{data}) = \sum_i \psi_1(y_i; \theta, \text{data}) + \sum_{i,j \in \text{edges}} \psi_2(y_i, y_j; \theta, \text{data})$$

Solving MRFs with graph cuts



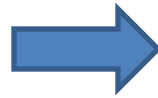
$$Energy(\mathbf{y}; \theta, data) = \sum_i \psi_1(y_i; \theta, data) + \sum_{i,j \in edges} \psi_2(y_i, y_j; \theta, data)$$

Solving MRFs with graph cuts



$$Energy(\mathbf{y}; \theta, data) = \sum_i \psi_1(y_i; \theta, data) + \sum_{i,j \in edges} \psi_2(y_i, y_j; \theta, data)$$

GrabCut segmentation

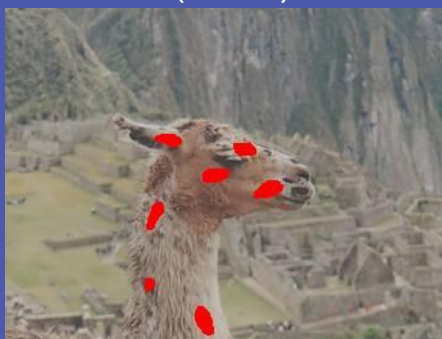


User provides rough indication of foreground region.

Goal: Automatically provide a pixel-level segmentation.

Grab cuts and graph cuts

Magic Wand
(198?)



User
Input



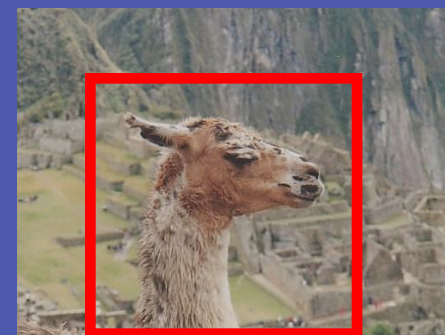
Regions

Intelligent Scissors
Mortensen and Barrett (1995)



Boundary

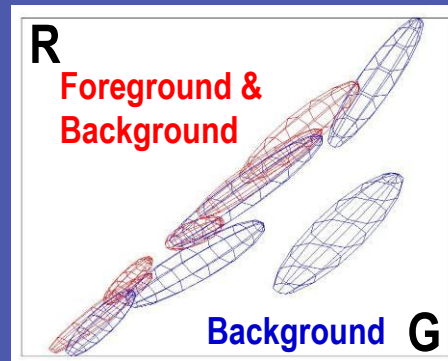
GrabCut



Regions & Boundary

Result

Colour Model

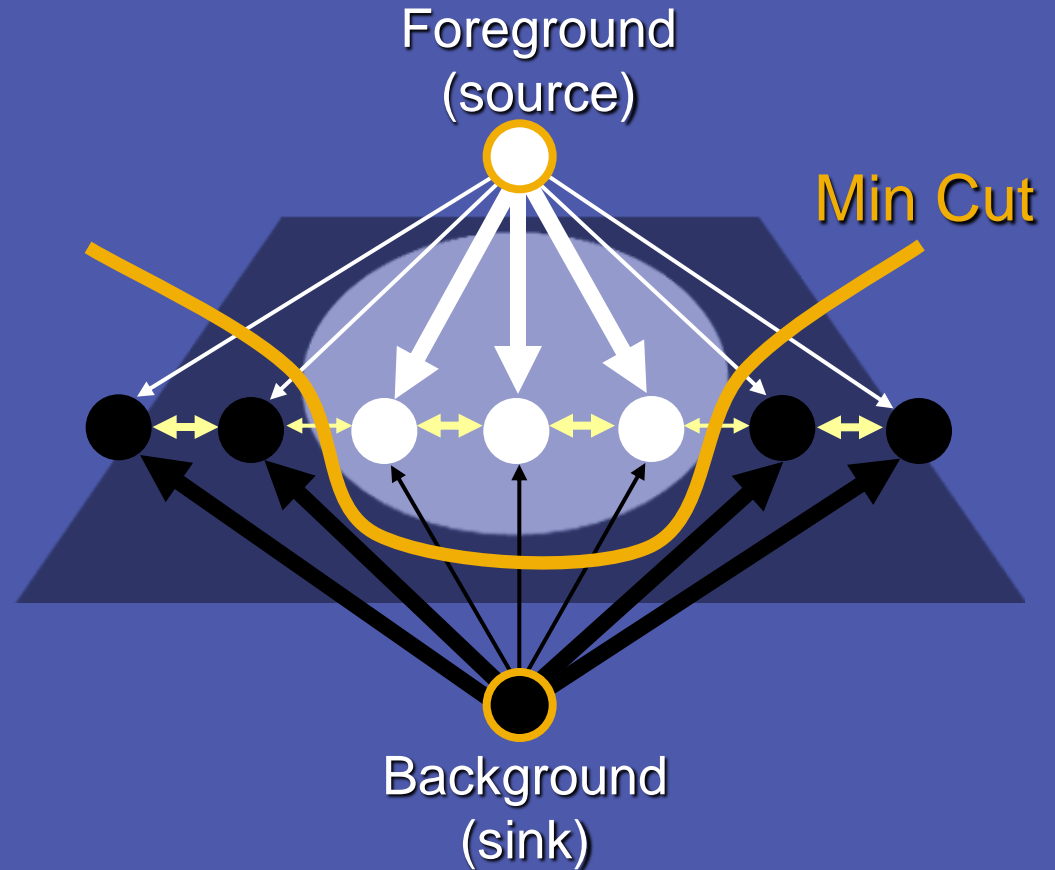
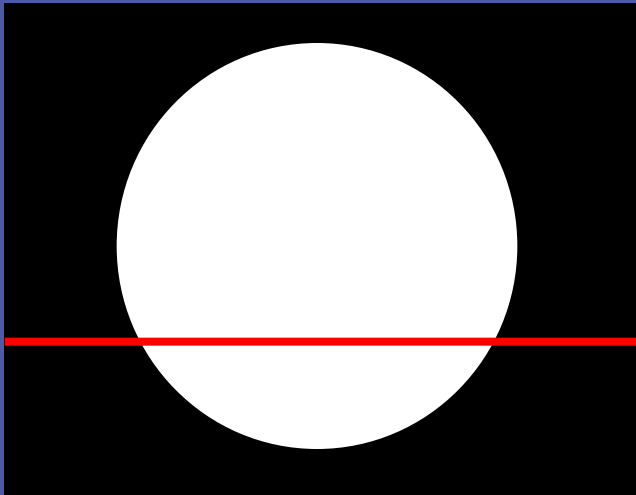


Gaussian Mixture Model (typically 5-8 components)

Graph cuts

Boykov and Jolly (2001)

Image



Cut: separating source and sink; Energy: collection of edges

Min Cut: Global minimal energy in polynomial time

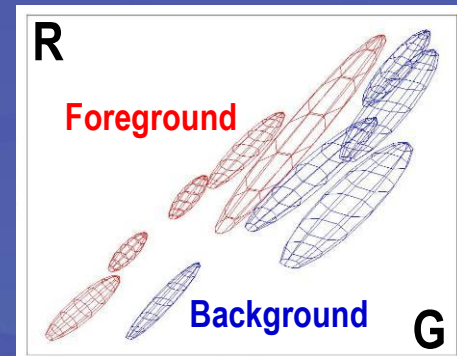
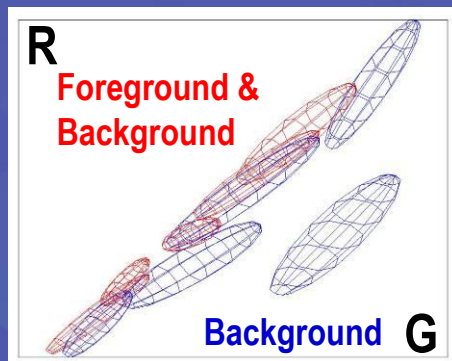
Colour Model



SIGGRAPH2004



Iterated
graph cut



Gaussian Mixture Model (typically 5-8 components)

GrabCut segmentation

1. Define graph

- usually 4-connected or 8-connected

2. Define unary potentials

- Color histogram or mixture of Gaussians for background and foreground

$$\text{unary_potential}(x) = -\log\left(\frac{P(c(x); \theta_{\text{foreground}})}{P(c(x); \theta_{\text{background}})}\right)$$

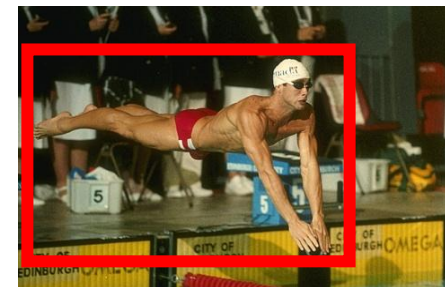
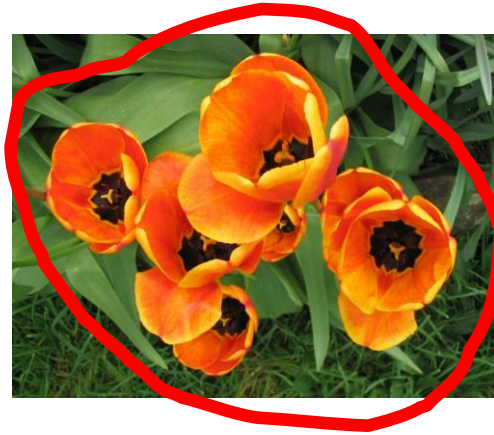
3. Define pairwise potentials

$$\text{edge_potential}(x, y) = k_1 + k_2 \exp\left\{\frac{-\|c(x) - c(y)\|^2}{2\sigma^2}\right\}$$

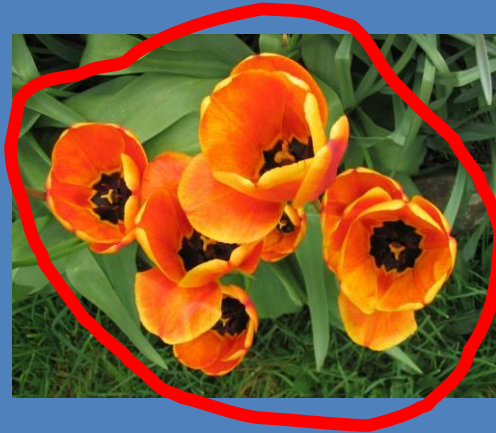
4. Apply graph cuts

5. Return to 2, using current labels to compute foreground, background models

What is easy or hard about these cases for graphcut-based segmentation?



Easier examples



More difficult Examples

Camouflage &
Low Contrast



Initial
Rectangle



Initial
Result

Fine structure



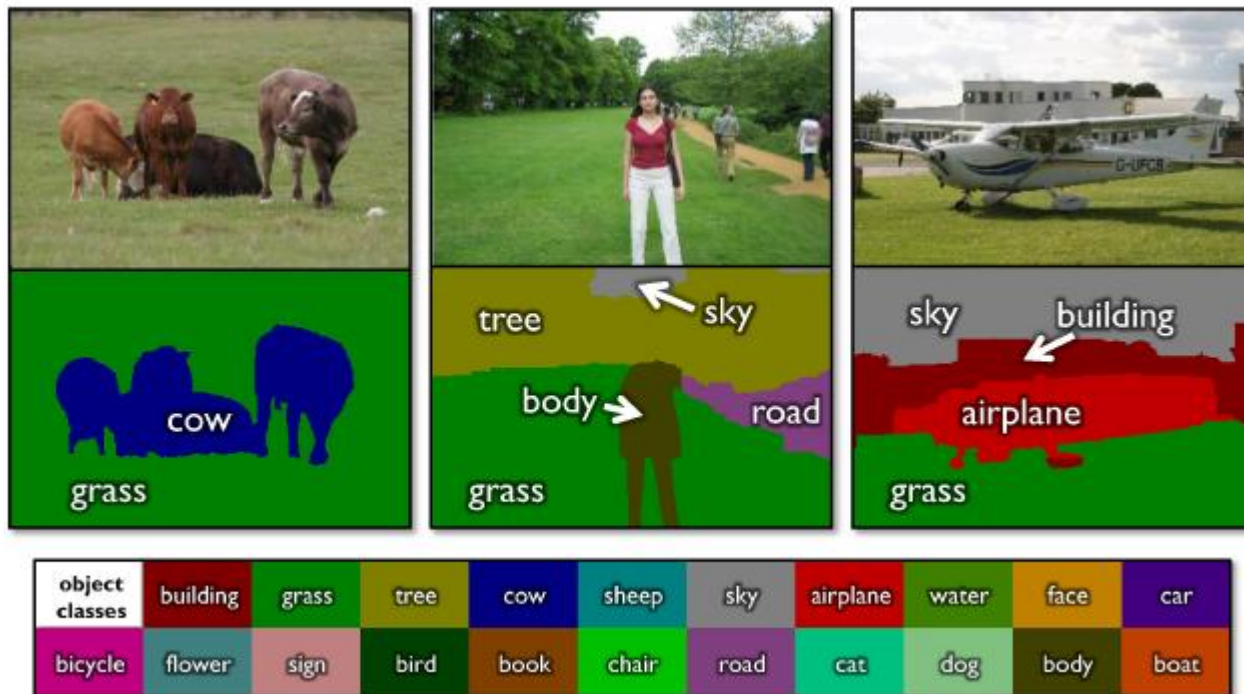
Harder Case



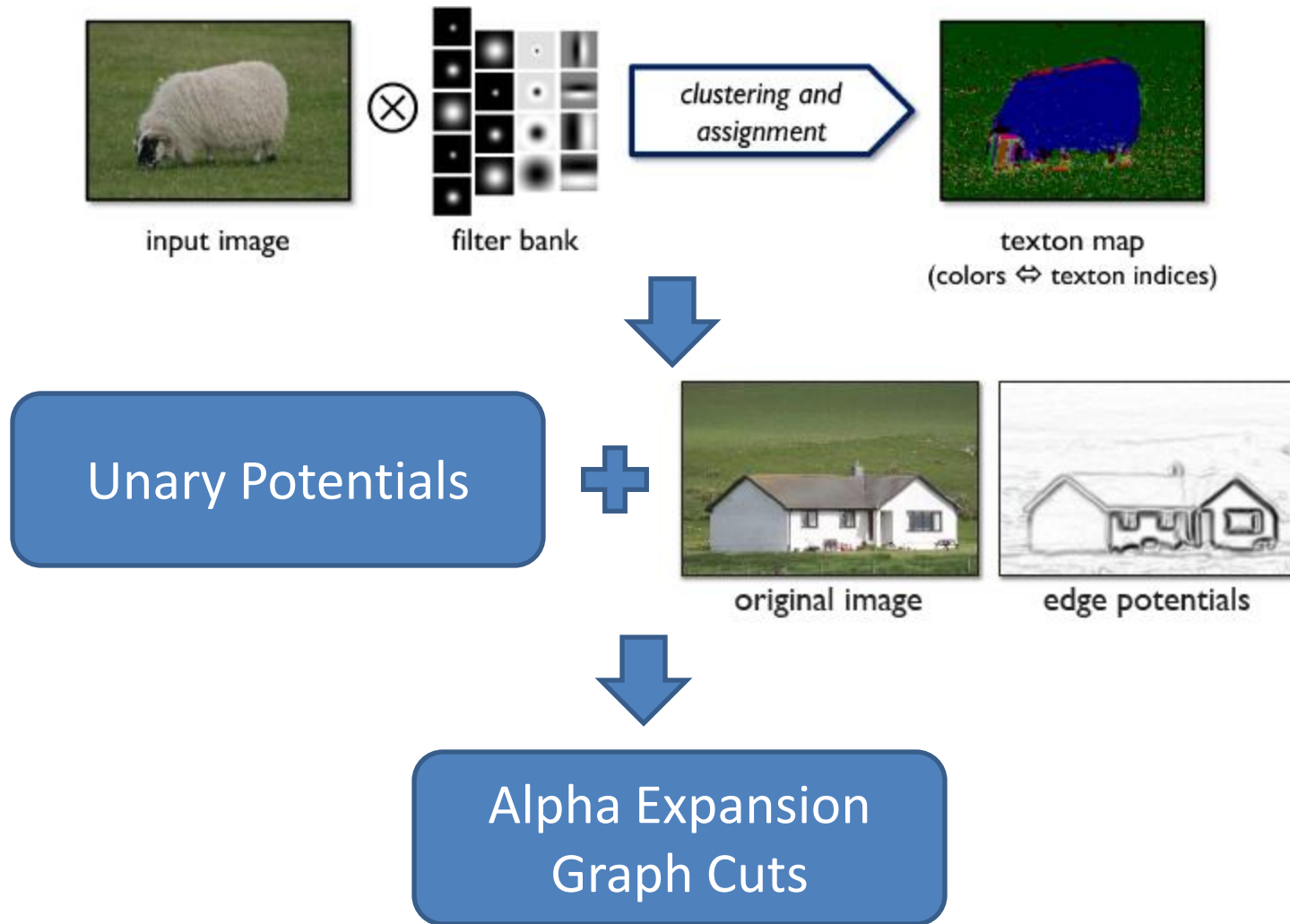
Lazy Snapping (Li et al. SG 2004)



Using graph cuts for recognition



Using graph cuts for recognition



Limitations of graph cuts

- Associative: edge potentials penalize different labels

Must satisfy

$$E^{i,j}(0,0) + E^{i,j}(1,1) \leq E^{i,j}(0,1) + E^{i,j}(1,0)$$

- If not associative, can sometimes clip potentials
- Approximate for multilabel
 - Alpha-expansion or alpha-beta swaps

Graph cuts: Pros and Cons

- Pros
 - Very fast inference
 - Can incorporate data likelihoods and priors
 - Applies to a wide range of problems (stereo, image labeling, recognition)
- Cons
 - Not always applicable (associative only)
 - Need unary terms (not used for generic segmentation)
- Use whenever applicable

More about MRFs/CRFs

- Other common uses
 - Graph structure on regions
 - Encoding relations between multiple scene elements
- Inference methods
 - Loopy BP or BP-TRW: approximate, slower, but works for more general graphs

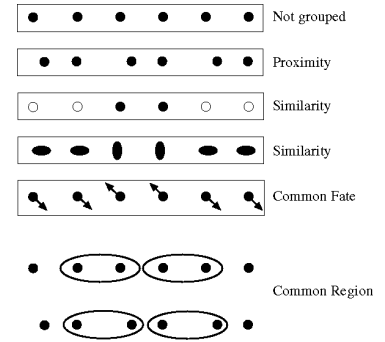
Further reading and resources

- Graph cuts
 - <http://www.cs.cornell.edu/~rdz/graphcuts.html>
 - Classic paper: [What Energy Functions can be Minimized via Graph Cuts?](#) (Kolmogorov and Zabih, ECCV '02/PAMI '04)
- Belief propagation

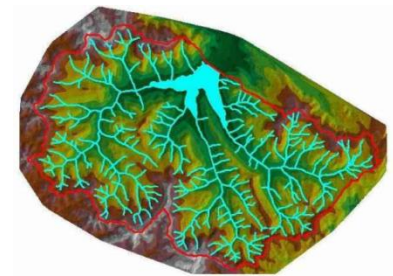
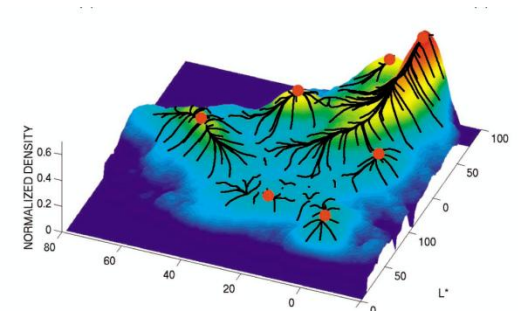
Yedidia, J.S.; Freeman, W.T.; Weiss, Y., "Understanding Belief Propagation and Its Generalizations", Technical Report, 2001:
<http://www.merl.com/publications/TR2001-022/>
- Normalized cuts and image segmentation (Shi and Malik)
<http://www.cs.berkeley.edu/~malik/papers/SM-ncut.pdf>
- N-cut implementation
<http://www.seas.upenn.edu/~timothee/software/ncut/ncut.html>

Next Class

- Gestalt grouping



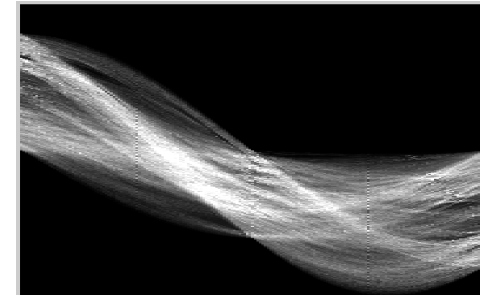
- More segmentation methods



Recap of Grouping and Fitting

Edge and line detection

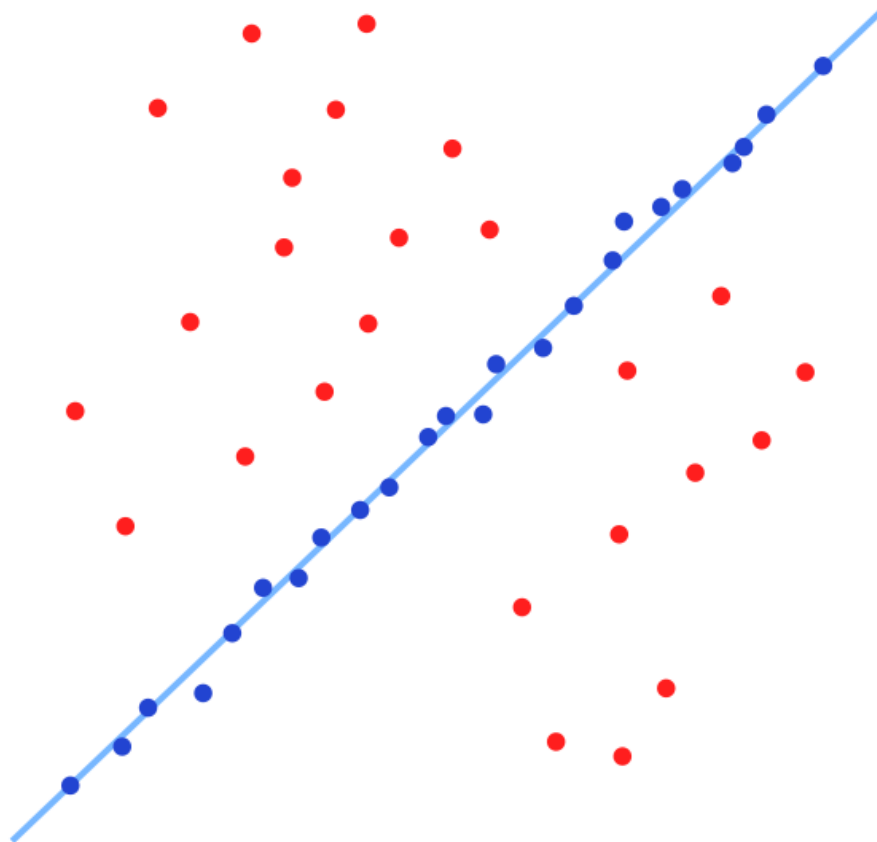
- Canny edge detector =
smooth \rightarrow derivative \rightarrow thin \rightarrow
threshold \rightarrow link
- Generalized Hough transform =
points vote for shape parameters
- Straight line detector =
canny + gradient orientations \rightarrow
orientation binning \rightarrow linking \rightarrow
check for straightness



Robust fitting and registration

Key algorithms

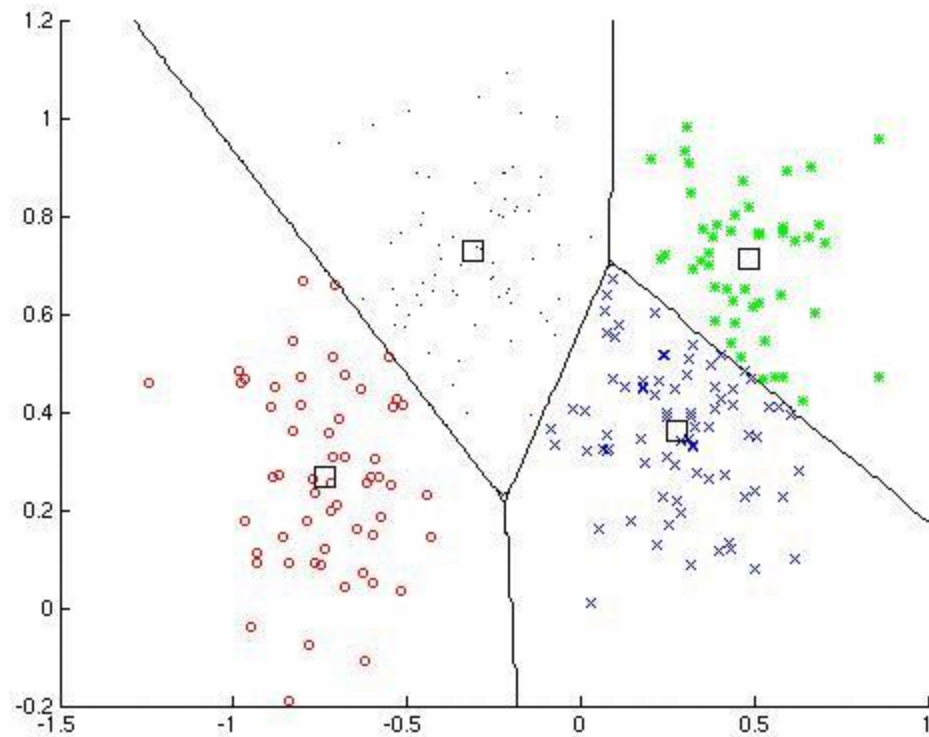
- RANSAC, Hough Transform



Clustering

Key algorithm

- K-means

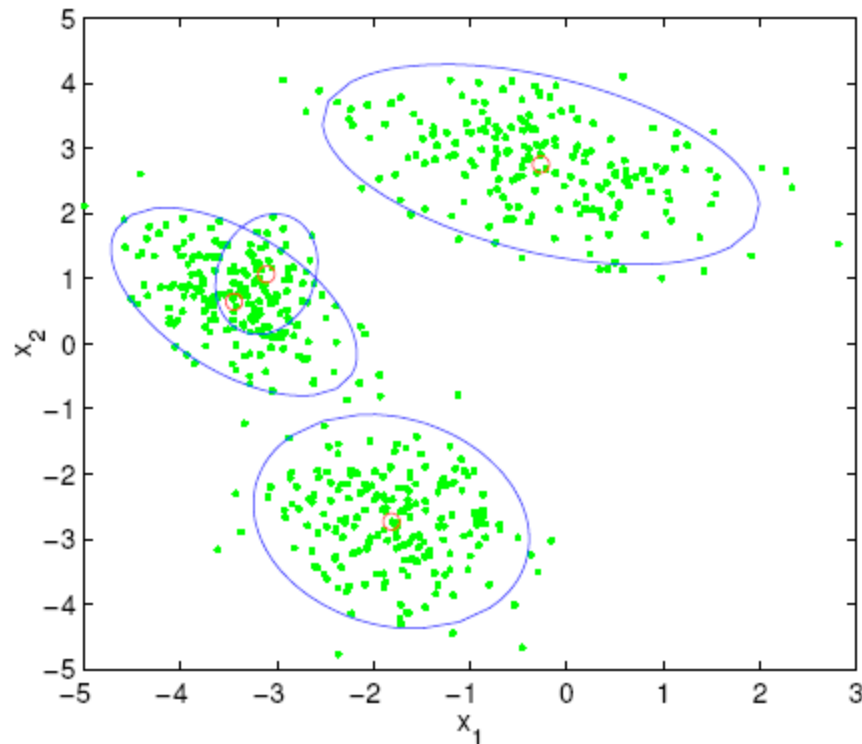


EM and Mixture of Gaussians

Tutorials:

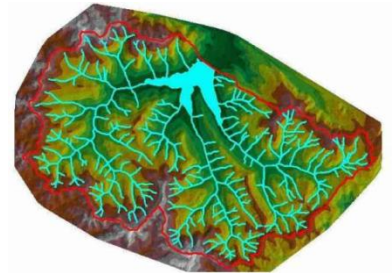
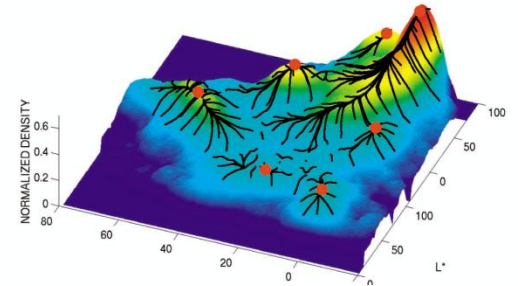
<http://www.cs.duke.edu/courses/spring04/cps196.1/.../EM/tomasiEM.pdf>

http://www-clmc.usc.edu/~adsouza/notes/mix_gauss.pdf



Segmentation

- Mean-shift segmentation
 - Flexible clustering method, good segmentation
- Watershed segmentation
 - Hierarchical segmentation from soft boundaries
- Normalized cuts
 - Produces regular regions
 - Slow but good for oversegmentation
- MRFs with Graph Cut
 - Incorporates foreground/background/object model and prefers to cut at image boundaries
 - Good for interactive segmentation or recognition



Next section: Recognition

- How to recognize
 - Specific object instances
 - Faces
 - Scenes
 - Object categories