

ELL 788  
Computational Perception & Cognition  
July – November 2015

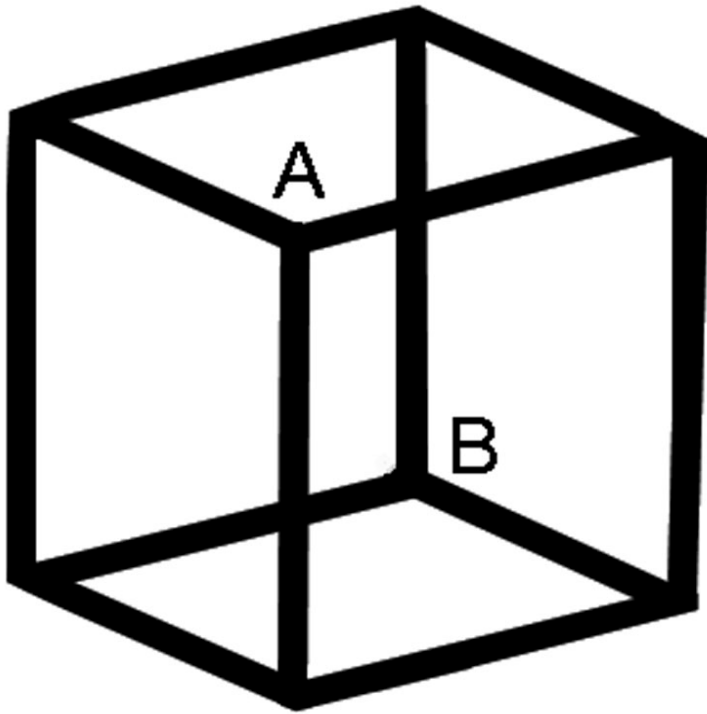
**Module 1-2**

Visual perception  
[Part 2]

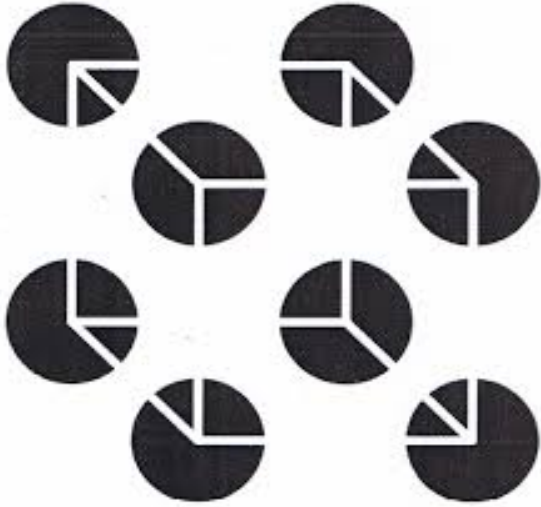
# Object and ground



# Multi-stability



# What occludes what?



cube cutout  
black disks  
white paper



paper with holes  
cube cutout





*Old couple or musician by Salvador Dali (1930)*

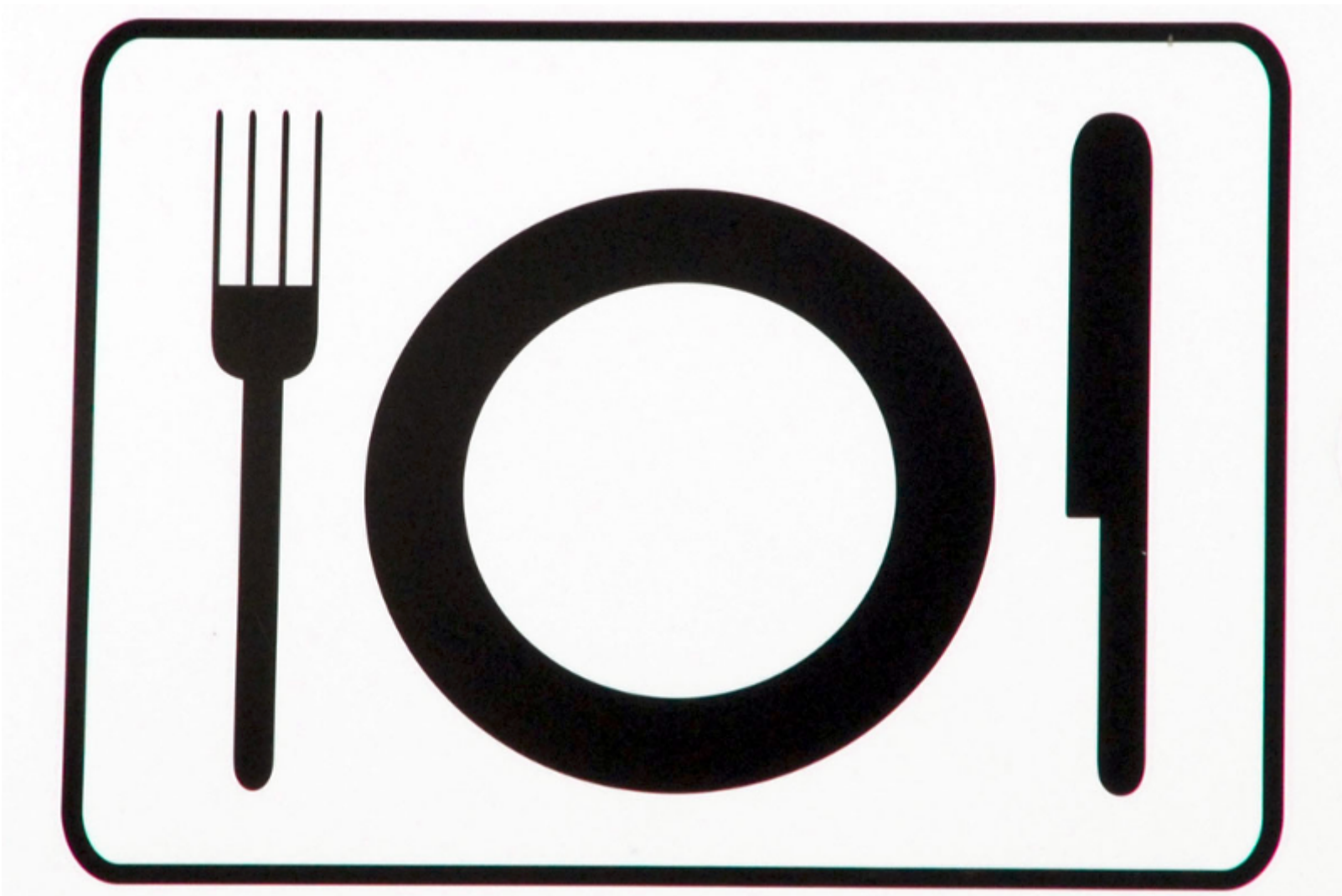
Spinning clockwise or anticlockwise ?



# Context and perception



# Context and perception





# Context and perception

A B C

*What is written above ?*

# Context and perception

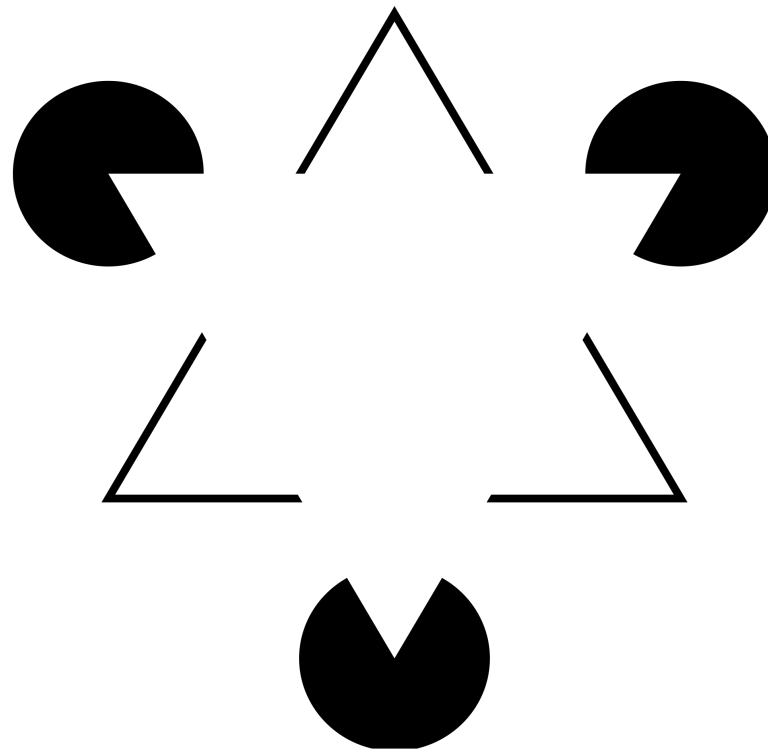
12 13 14

*What is written above ?*

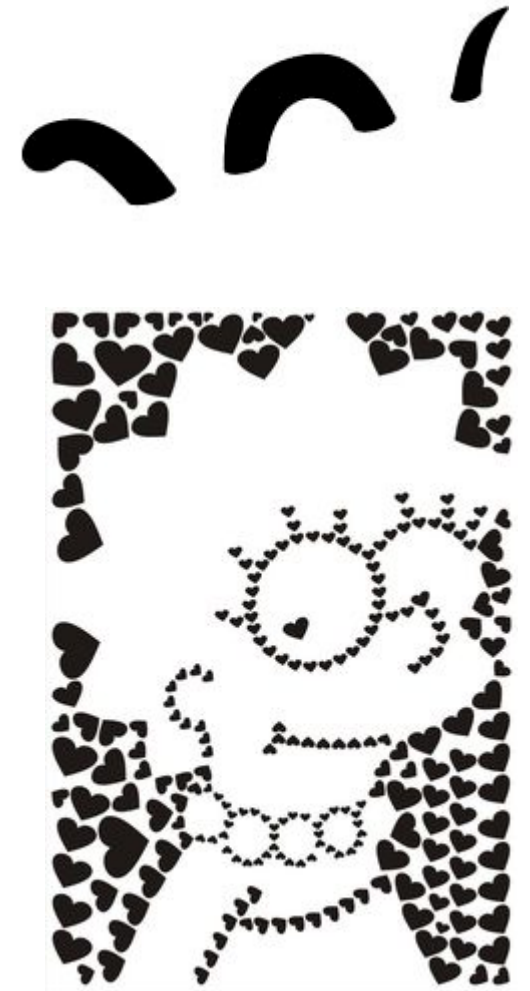
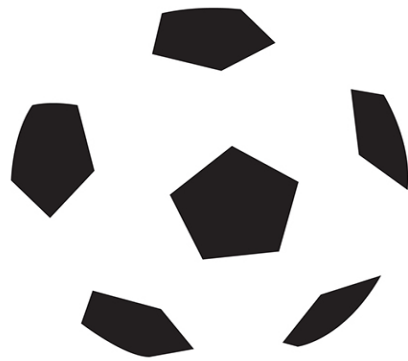
# Gestalt law of perceptual organization

*The whole is greater than the sum of the parts*

The fundamental principle of gestalt perception is the law of “prägnanz”, which says that we tend to order our experience in a manner that is regular, orderly, symmetrical, and simple.

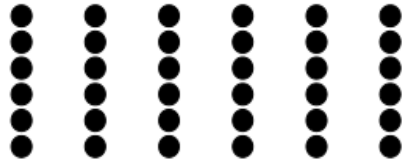


# Artworks based on Gestalt principle

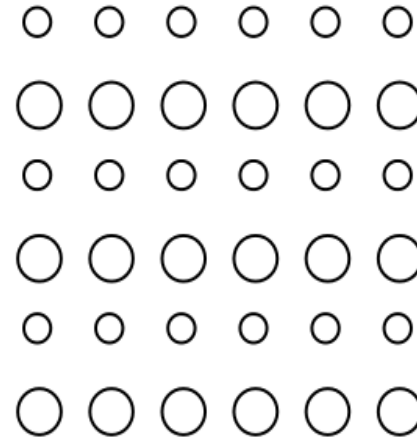


# Gestalt principles

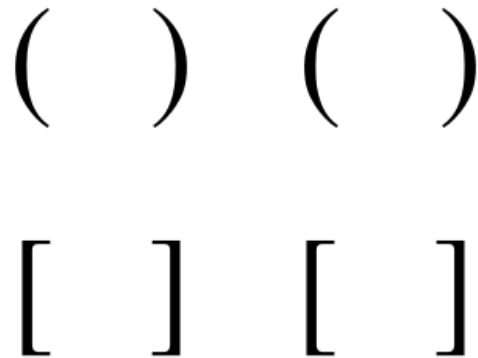
**Proximity**



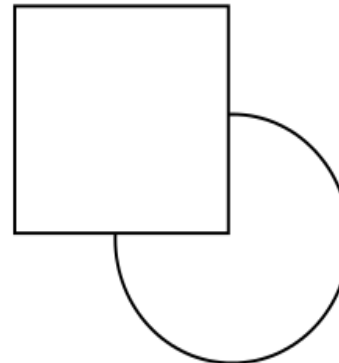
**Similarity**

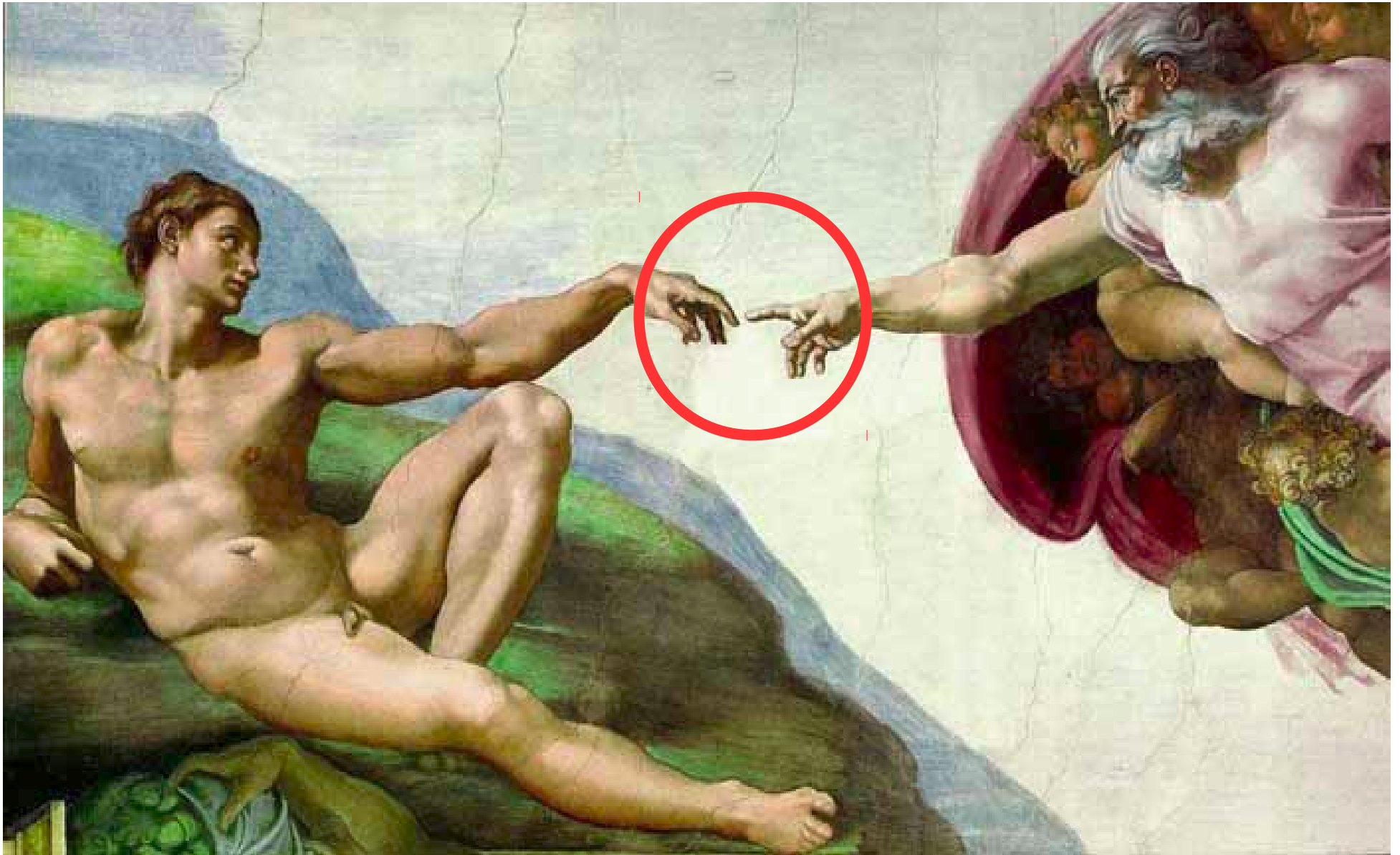


**Symmetry**



**Closure**

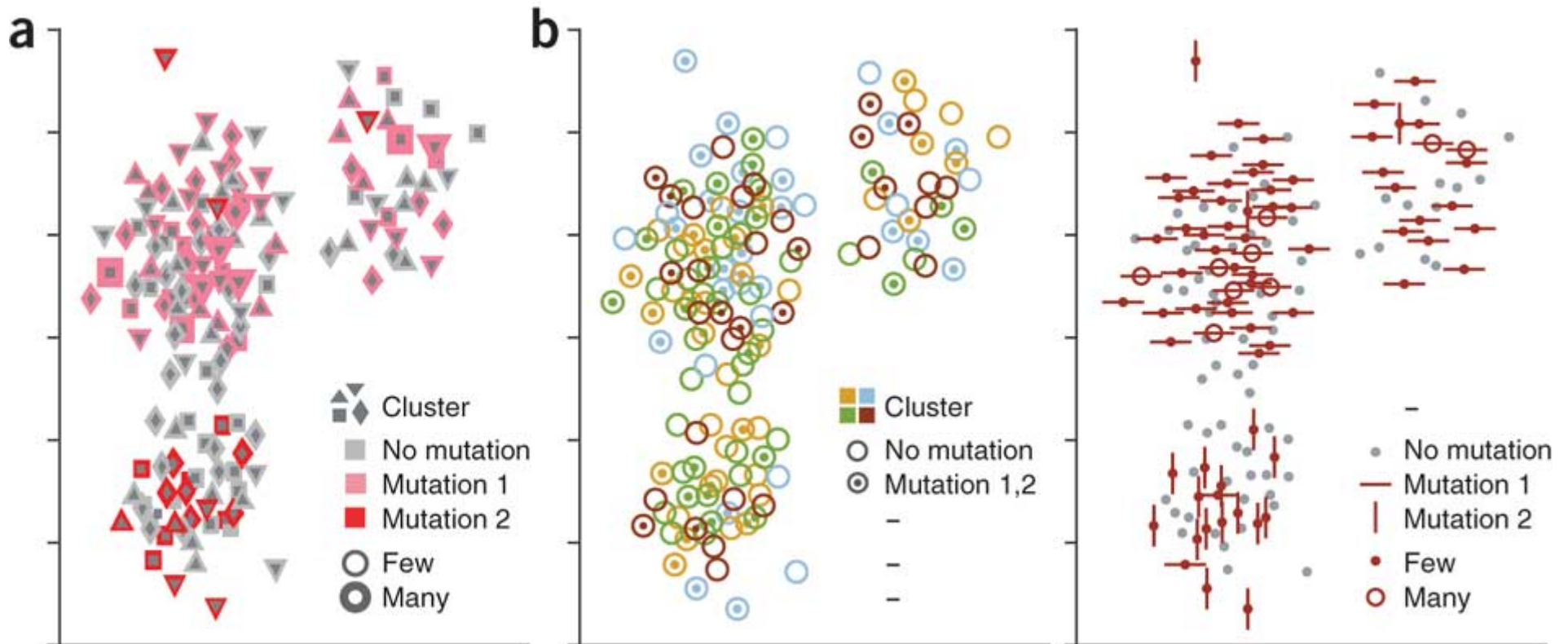




*Principle of proximity*

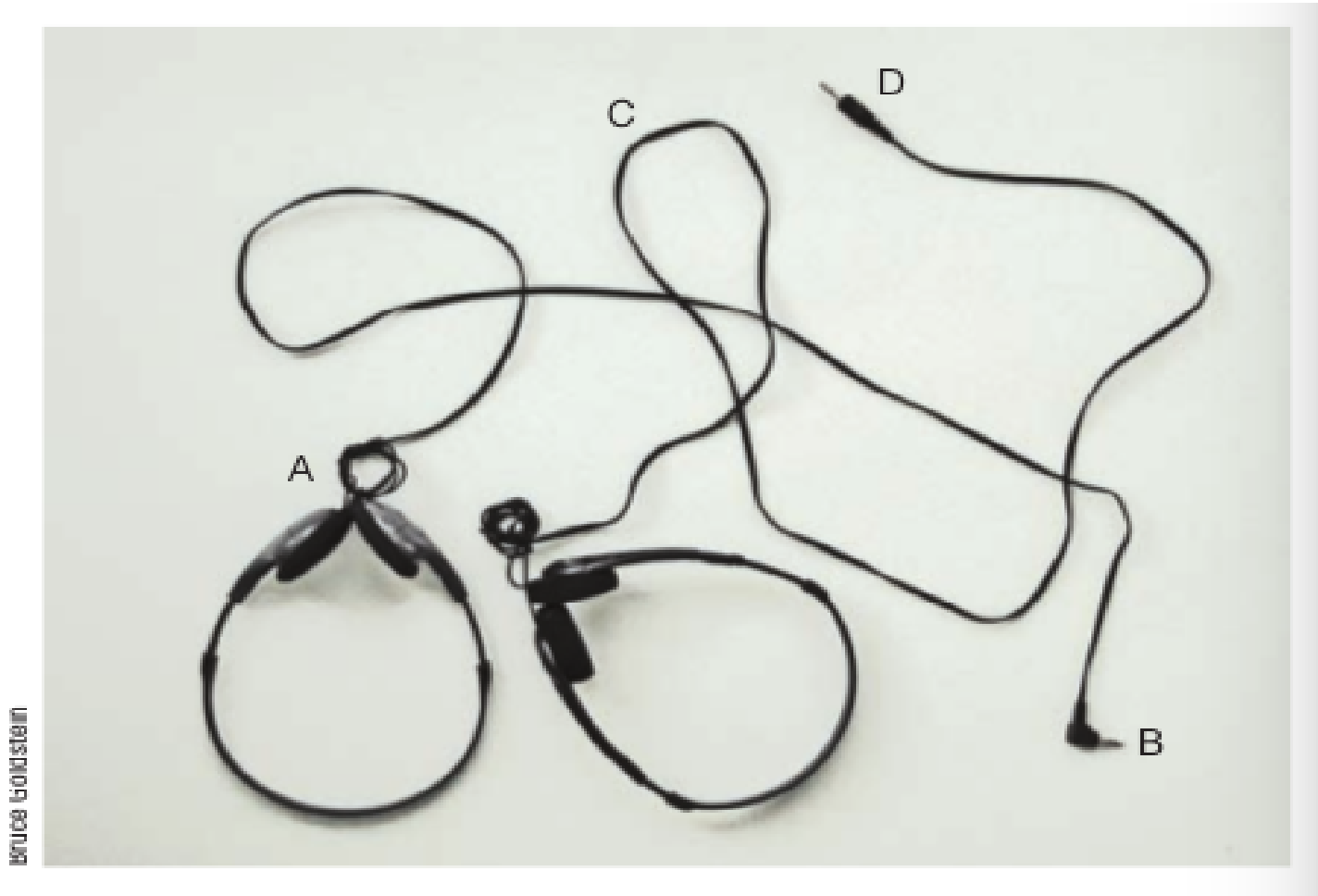
*Michelangelo, Creation of Adam, c. 1510.*

# Application: Graphical Data Visualization



*Principle of similarity*

# Example



*Continuation*

*Source: Goldstein's e-book*



# Another example



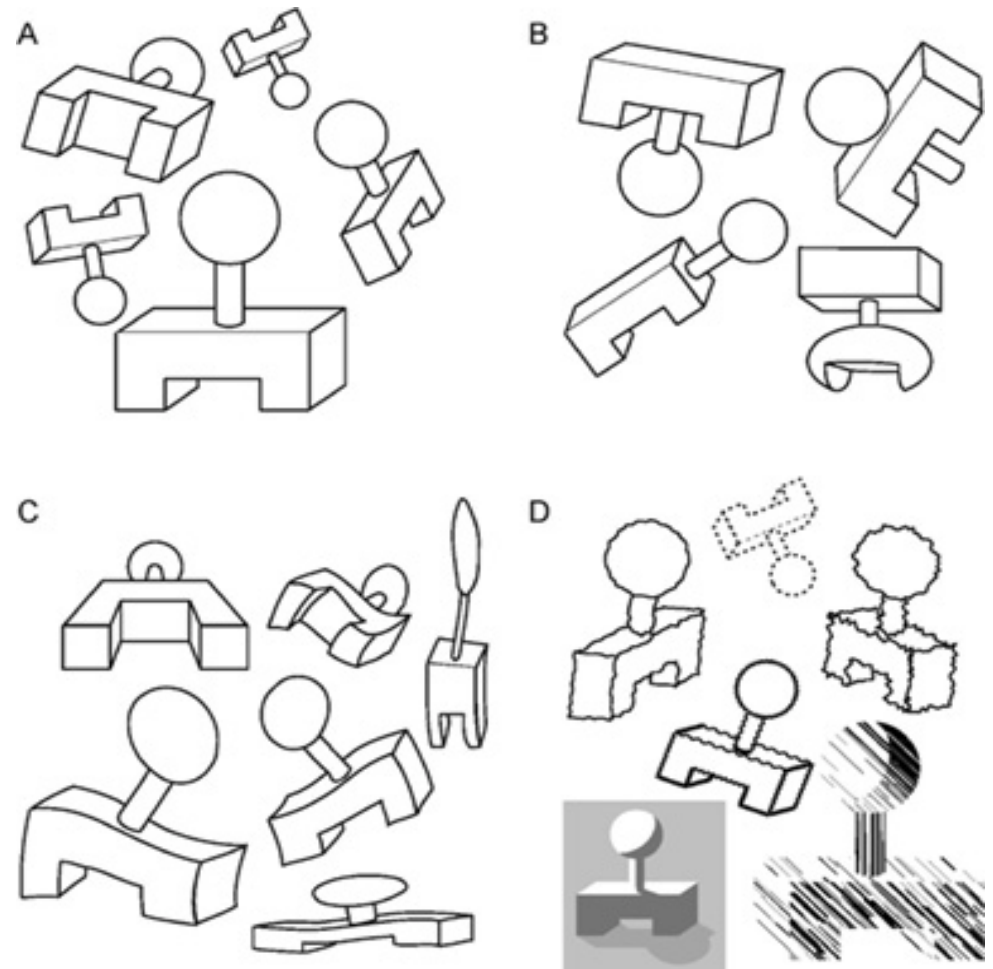
*What do you see in this image?*

*Source:* Perception and Imaging: Photography a Way of Seeing  
By Richard D. Zakia

# Perceptual invariance

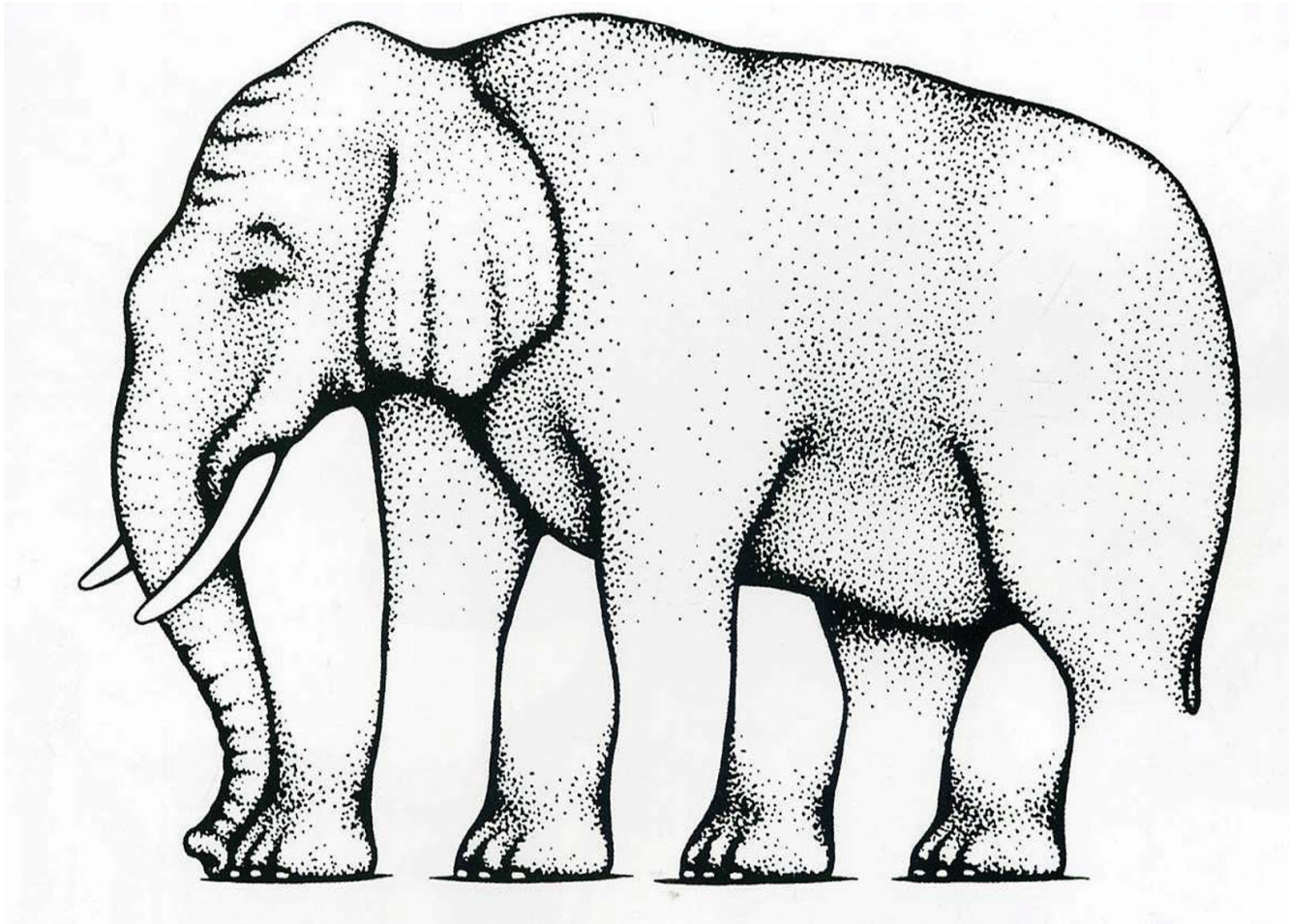
Invariance is the property of perception

- simple geometrical objects are recognized independent of rotation, translation, and scale;
- as well as several other variations such as elastic deformations, different lighting, and different component features.



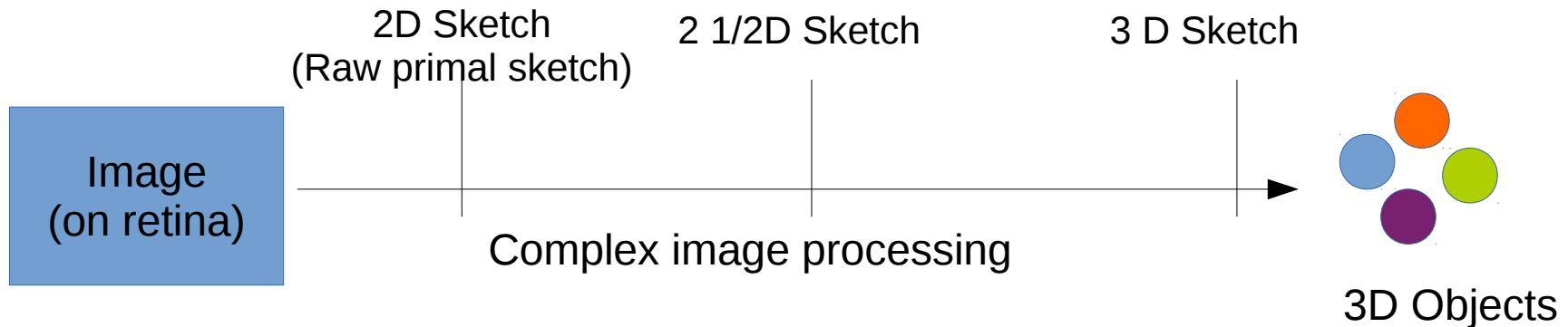
"Law of Symmetry" by Hsokolow  
via Wikipedia

# How many legs do the elephant has ?



*Exercise: Explain the phenomenon with Gestalt principles*

# Computational theory of vision [David Marr]



- Stage 1: (Raw Primal Sketch)

- Perceptual grouping of pixels (brightness, color, contrast)
- Contours and edges

- Stage 2: (2 1/2D Sketch)

- Feature grouping (Gestalt principles)
- Surfaces and layouts

- Stage 3: (3D Sketch)

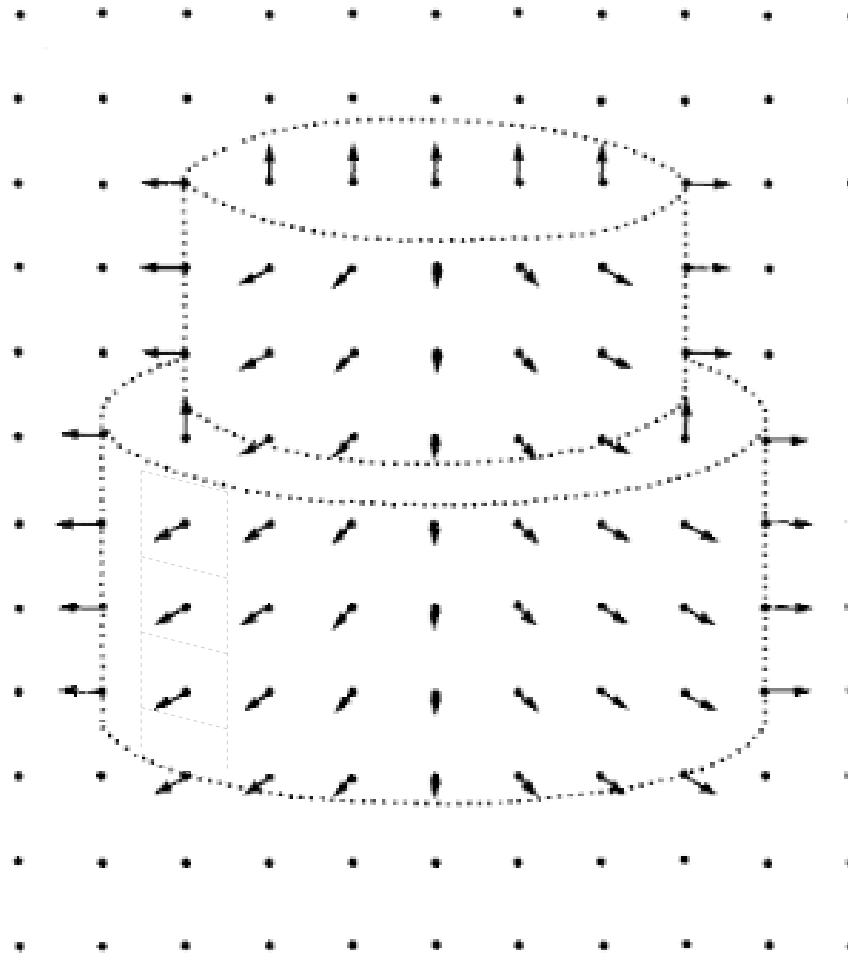
- Parts linked, axis of symmetry determined
- 3D image completed (*incl.* occluded areas)

**Viewer centric description**

**Object centric description**

*Objects recognized despite disparate points of view*

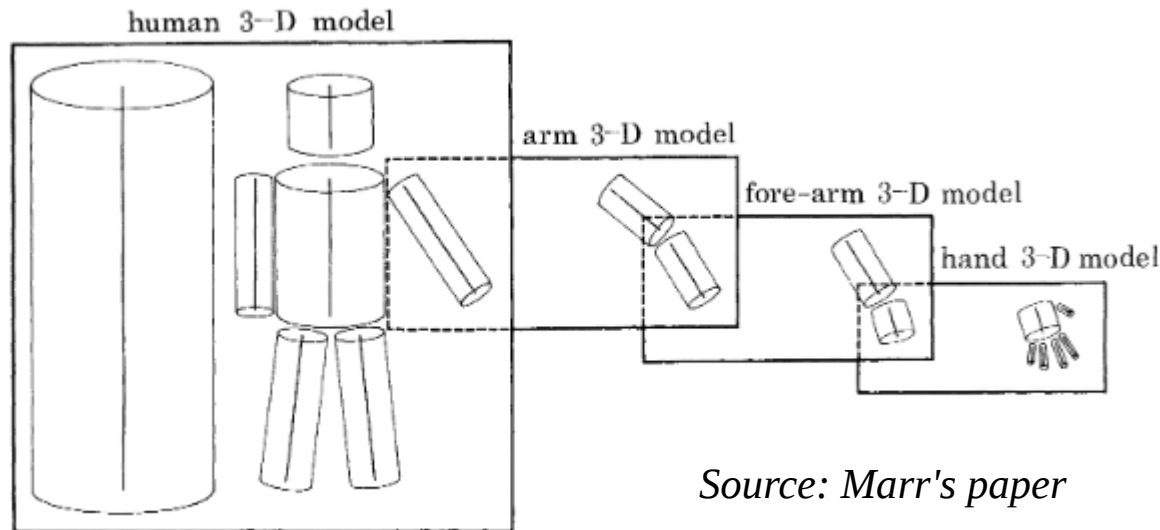
# Shape representation (2 1/2D)



- Models the surfaces
- Viewer centric

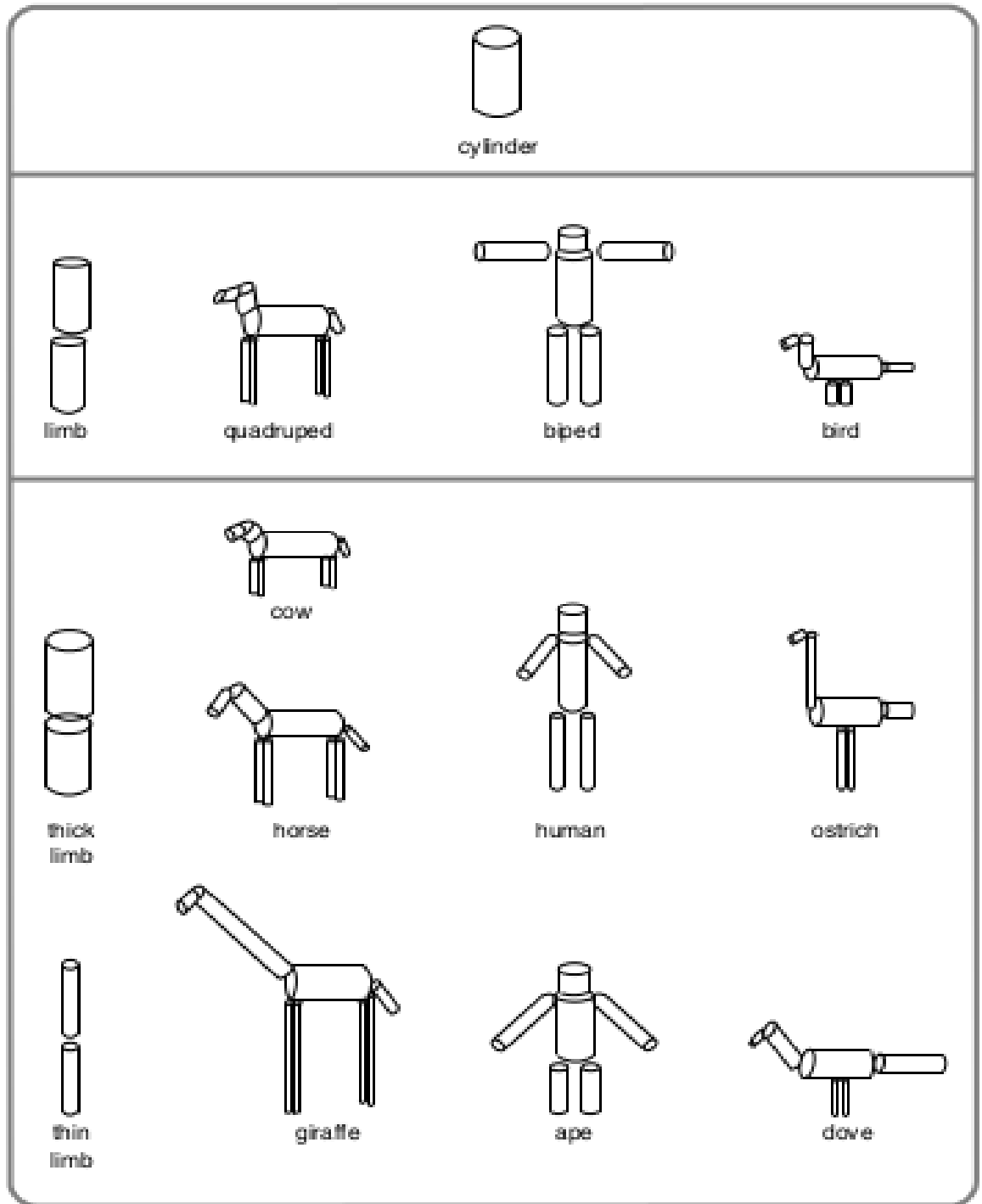
Source: Marr's paper

# Shape representation (3D)



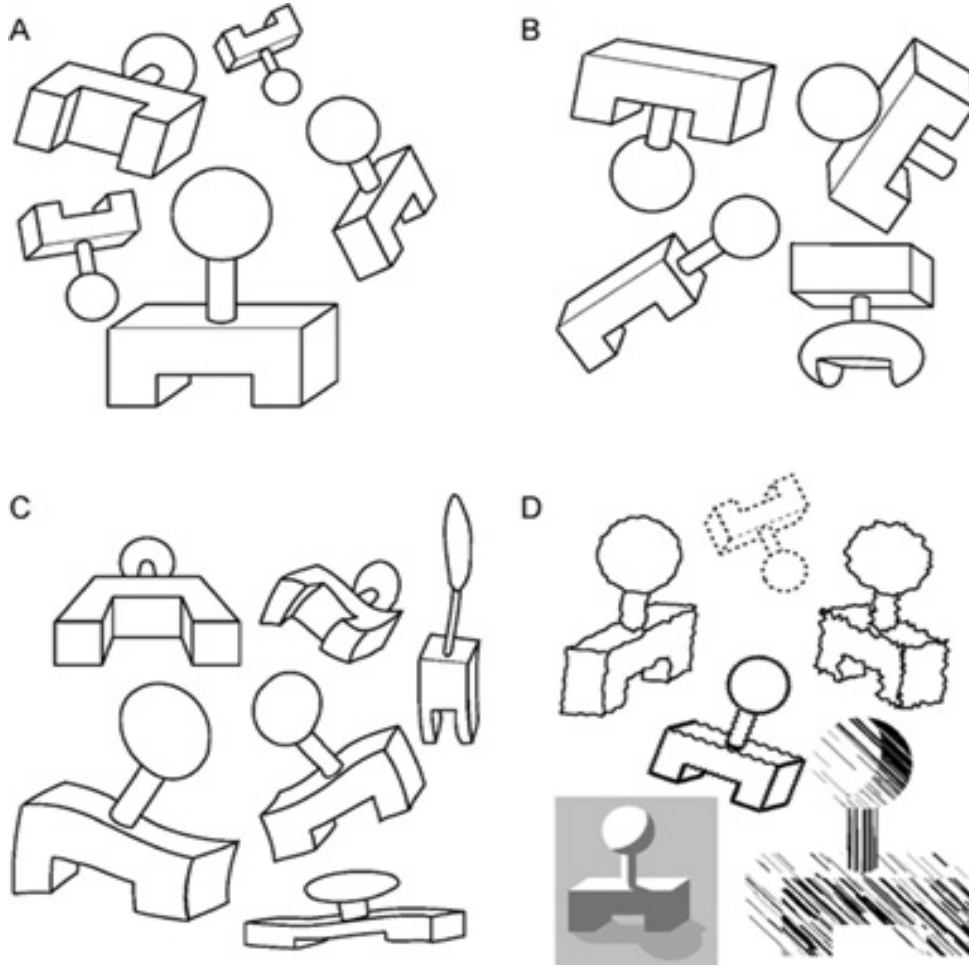
- Hierarchical model (Modular decomposition) -- different levels of details
- Model axis: Natural axis -- represents orientation
- Coordinate system: canonical coordinate system at each level of decomposition
- Object centric – neutral to viewer perspective

# Hierarchical organization and indexing



Source: Marr's paper

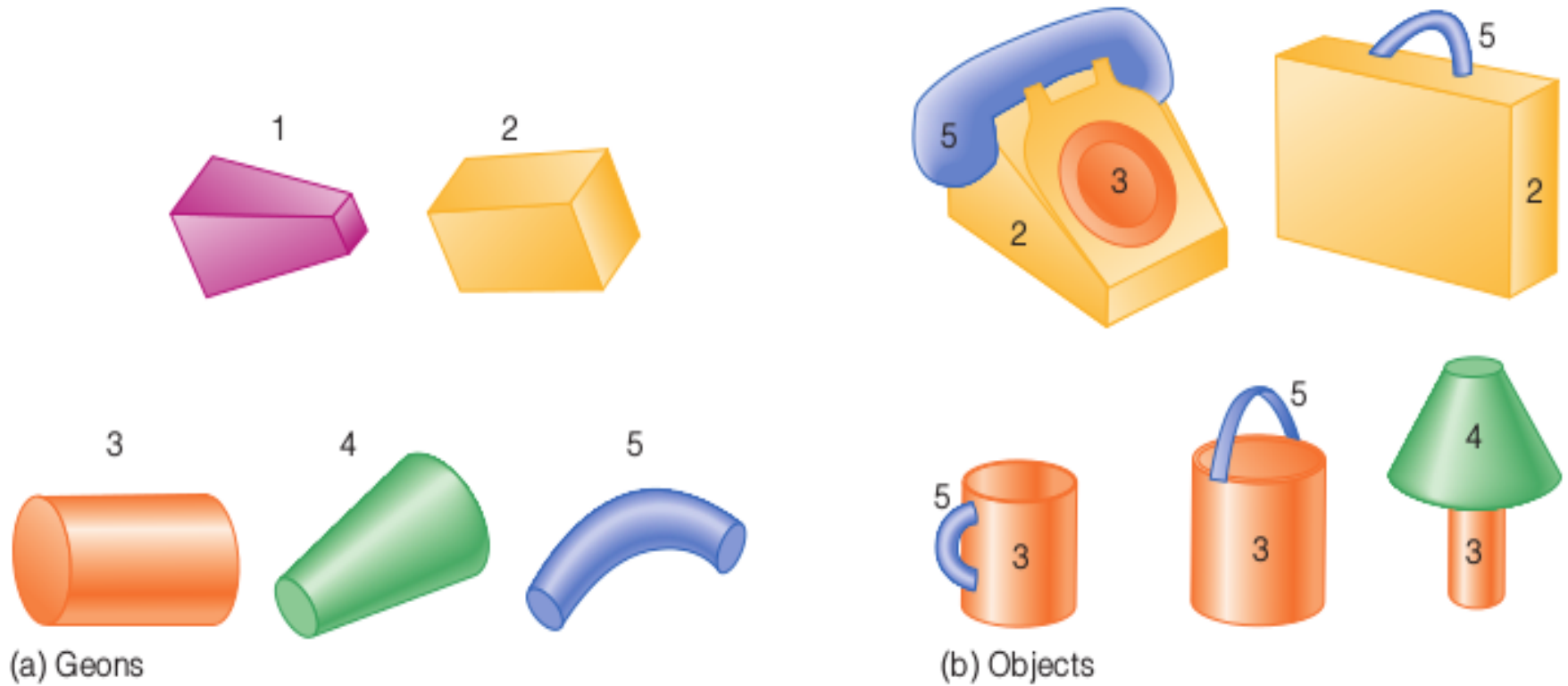
# Another way to interpret “law of symmetry”



Figures in A, B and D share the same 3D model



# Parts-based model (Biedman)



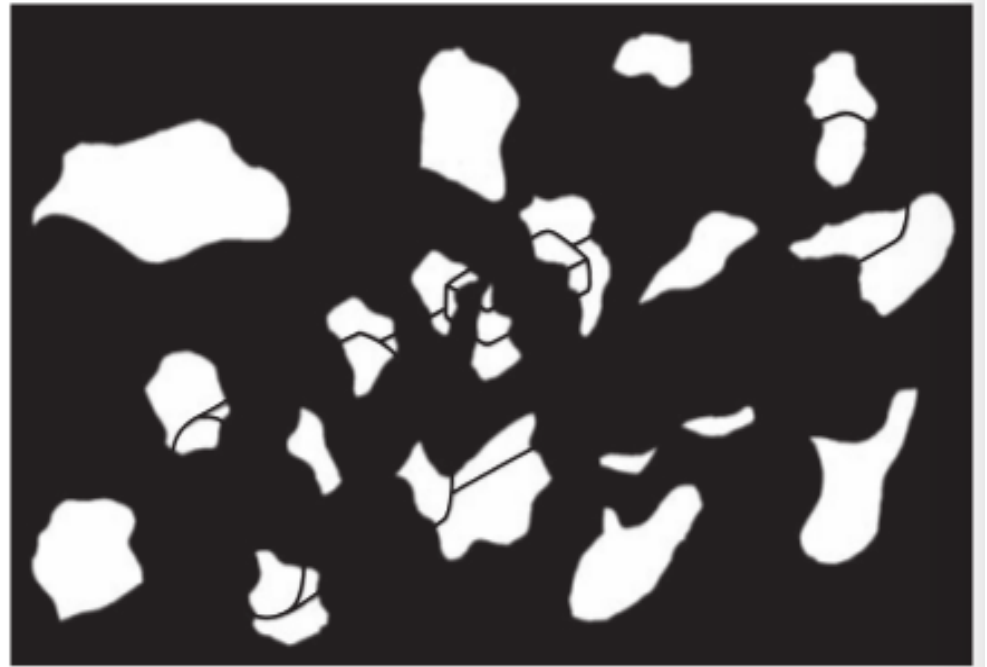
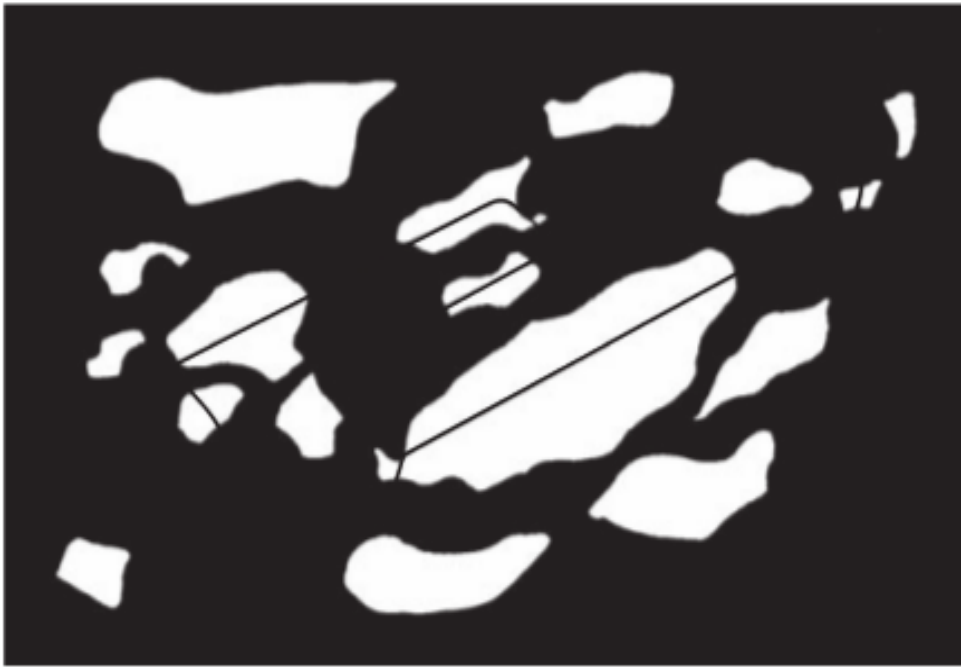
Source: Goldstein's e-book

# A real example

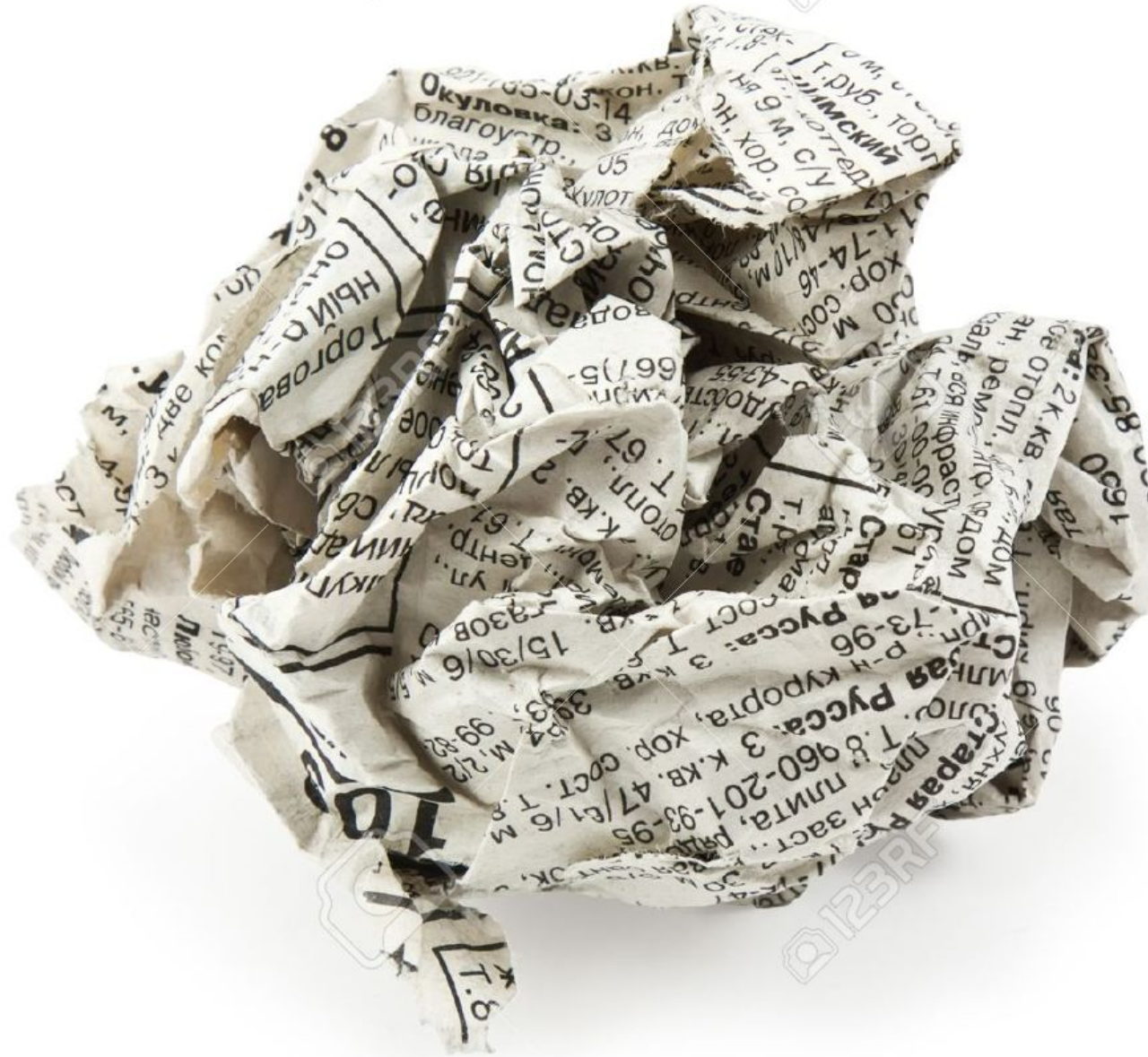


*Source: Goldstein's e-book*

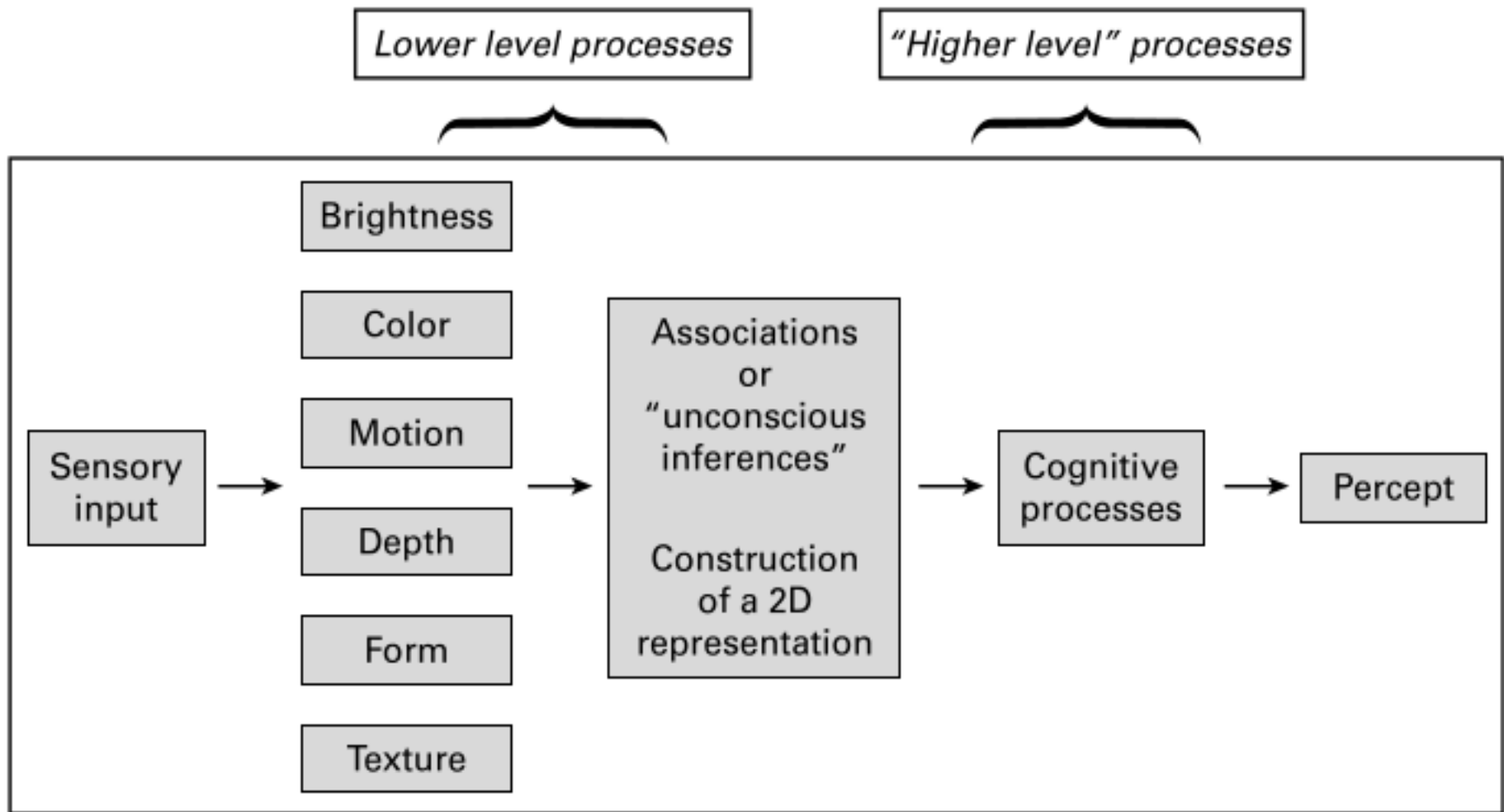
# A final example



# Counter-example

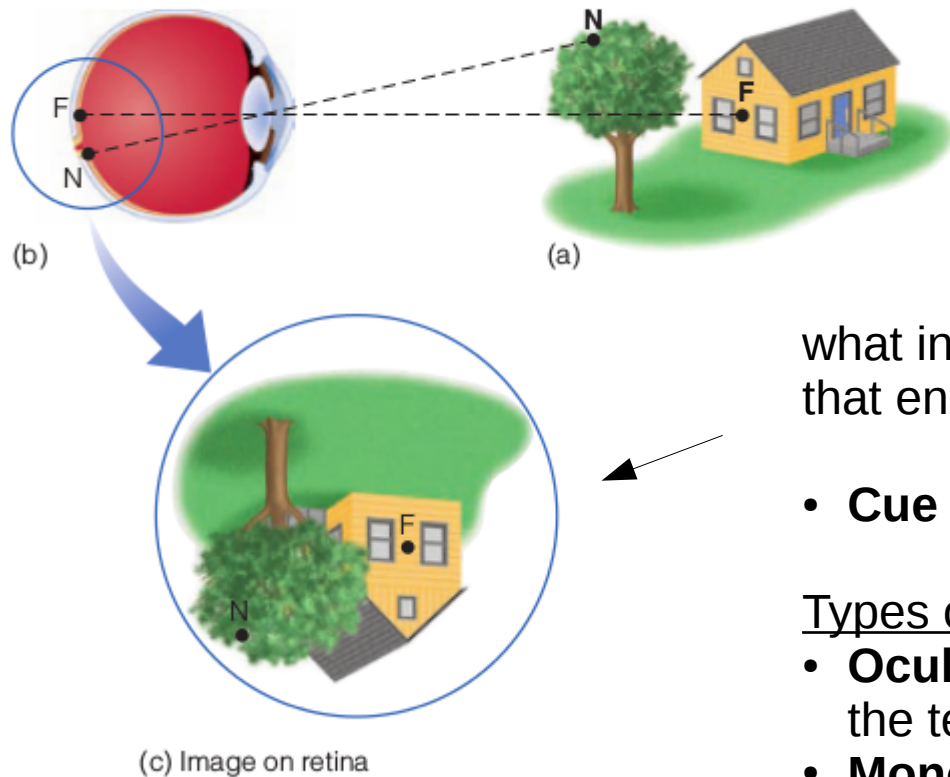


# Standard model of (visual) preception



Source: *Albertazzi, Tonder & Viswanath (Ed). Perception beyond inference*

# Perception of depth



what information is contained in this 2D image that enables us to perceive depth ?

- **Cue approach**

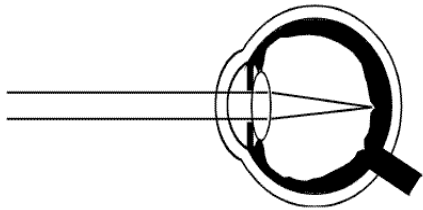
Types of cues:

- **Oculomotor.** The position of our eyes and the tension in our eye muscles.
- **Monocular.** Cues that work with one eye
- **Binocular.** Cues that depend on two eyes

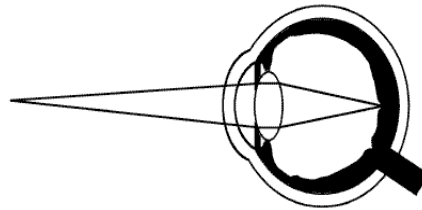
# Oculomotor cues



## Accommodation



Accommodation to the infinity



Accommodation to a short distance

## Convergence

Far away object



← IPD →

parallel  
optical axis



convergent  
optical axis

# Monocular cues

## Pictorial cues

- Occlusion
- Relative height
- Relative size
- Familiar size
- Perspective convergence



Bruce Goldstein



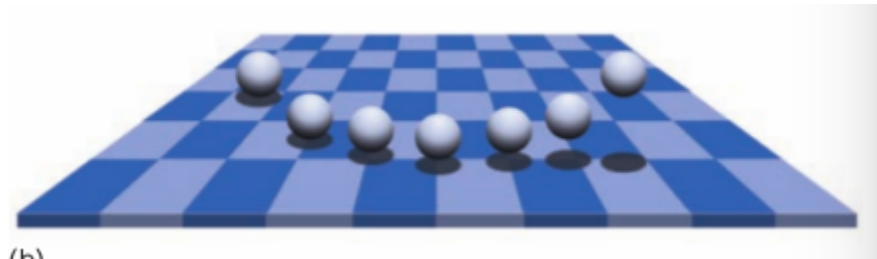
# Monocular cues ... more

## Pictorial cues

- Texture gradient
- Atmospheric perspective (sharpness)



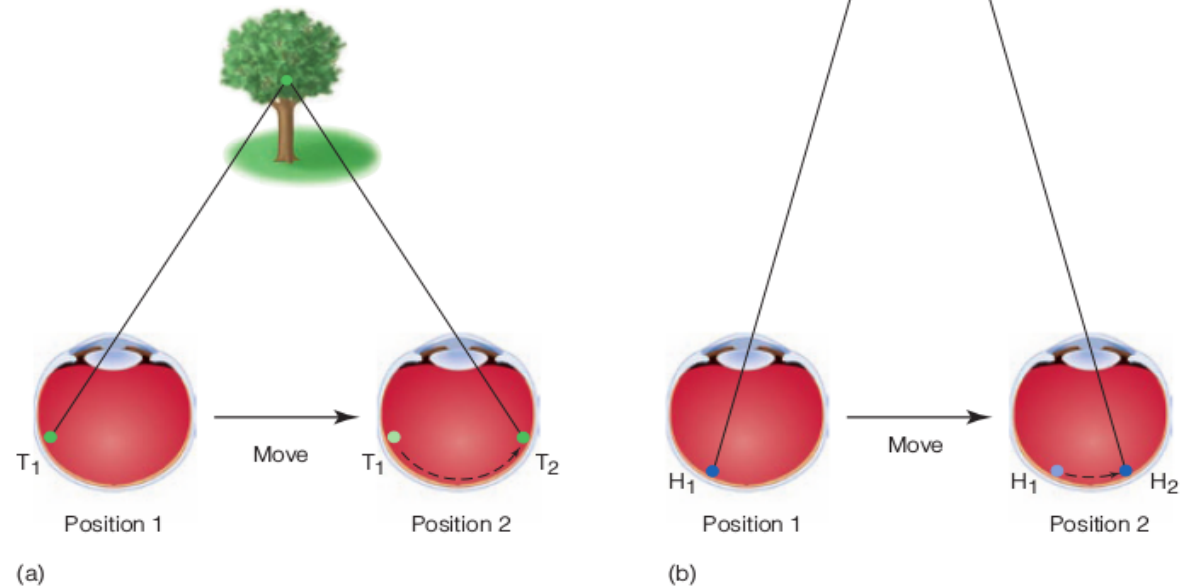
- Shadows



# Monocular cues ... more

## Motion cues

- Parallax



# Monocular cues ... more

## Motion cues

- Deletion and accretion

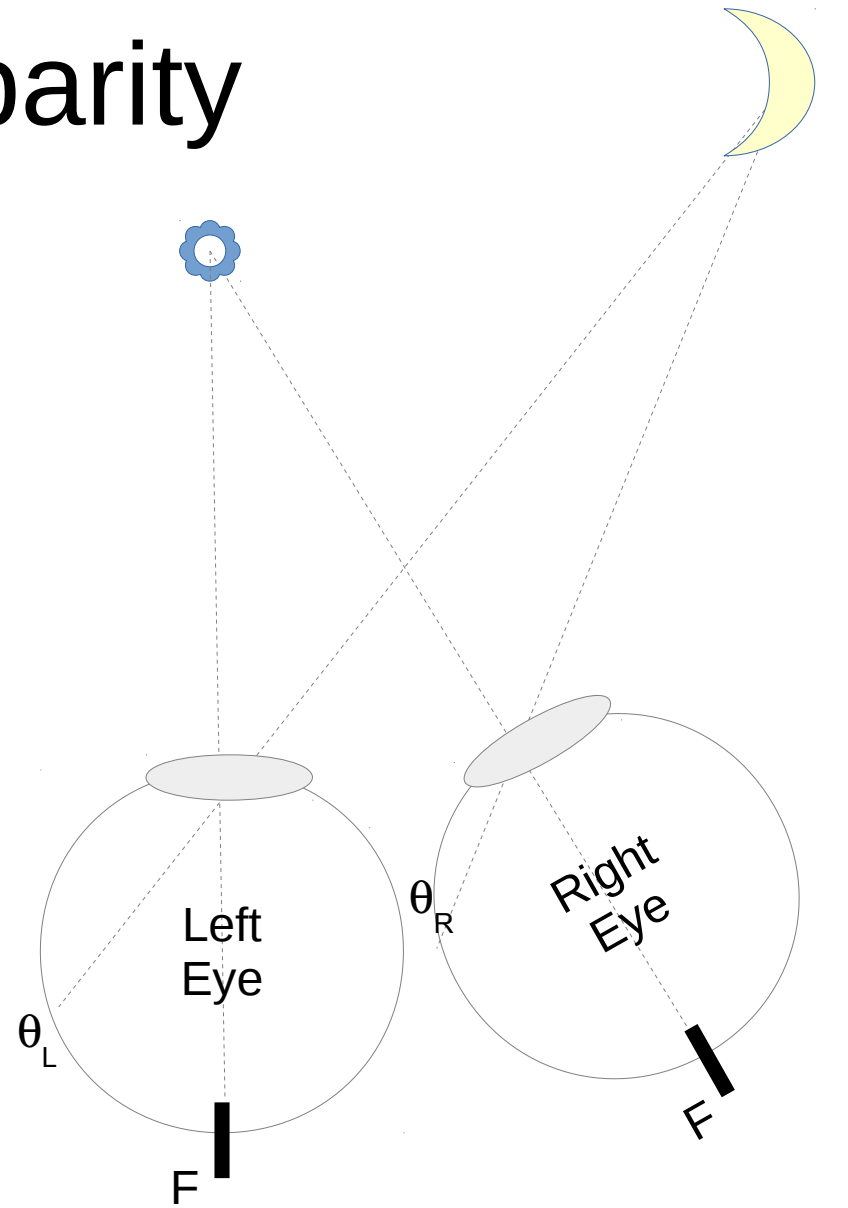
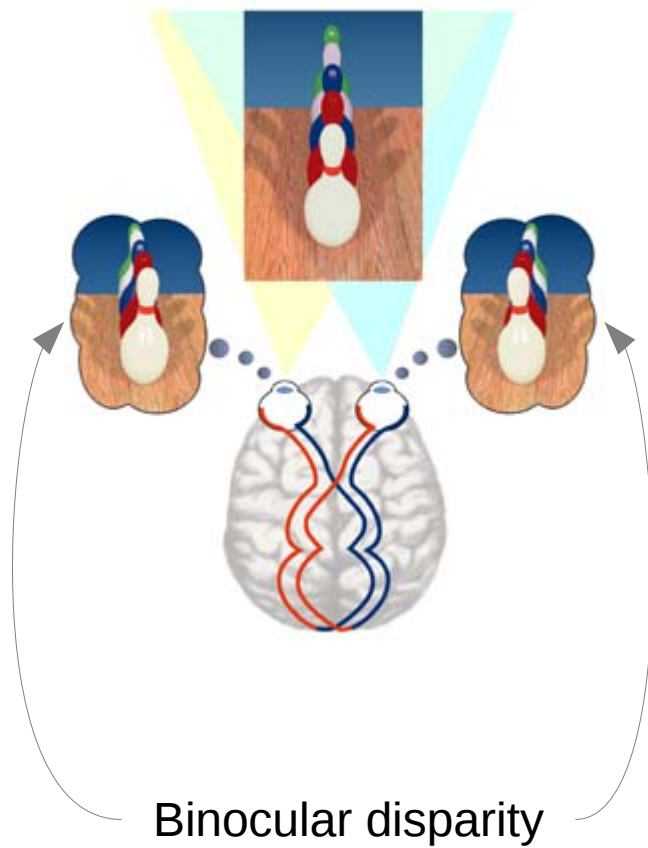


# Range effectiveness of different cues

DEPTH INFORMATION	0-2 METERS	2-20 METERS	ABOVE 30 METERS
Occlusion	✓	✓	✓
Relative size	✓	✓	✓
Accommodation and convergence	✓		
Motion parallax	✓	✓	
Relative height		✓	✓
Atmospheric perspective			✓

Source: Based on Cutting & Vishton, 1995.

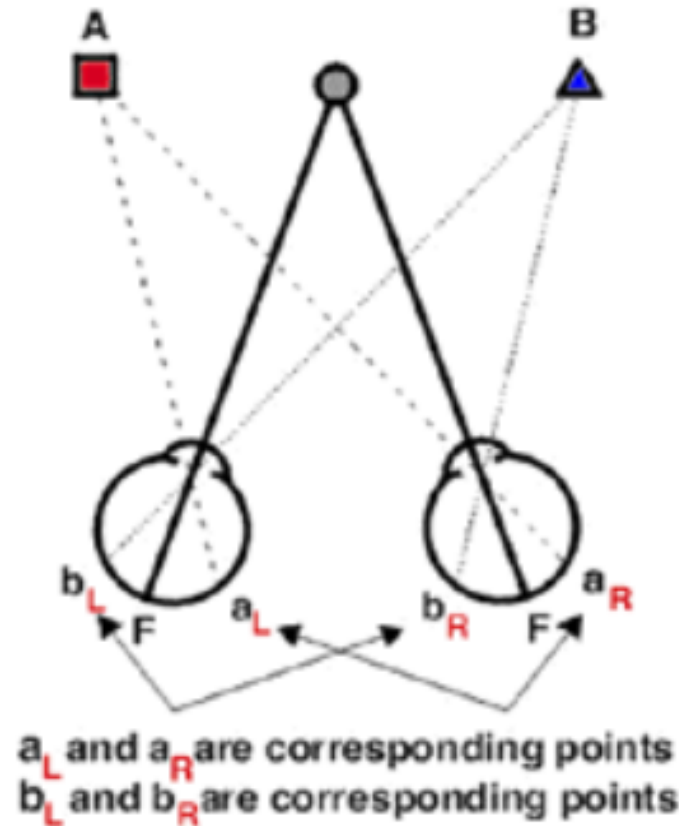
# Binocular cues: disparity



$$\text{Absolute (angular) disparity} = \theta_L - \theta_R$$

Closer distance  $\rightarrow$  Greater disparity

# Absolute and relative disparities



Absolute disparity of A =  $\theta_A = a_L - a_R$

Absolute disparity of B =  $\theta_B = b_L - b_R$

**Relative disparity** between A and B =  $\theta_A - \theta_B$

does not depend on where the eyes are looking at

**Invariant so long the objects do not move**

# Stereopsis and perception of depth



View Master



Bruce Goldstein

(a) Left eye image



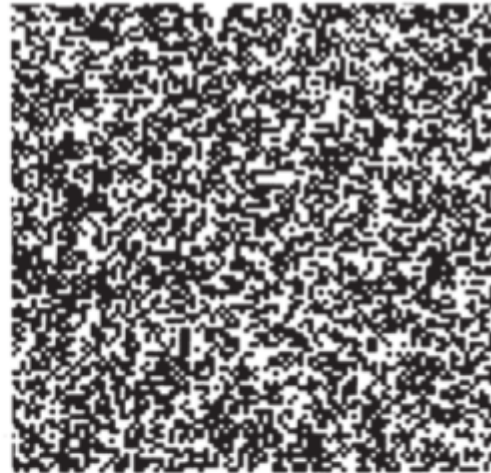
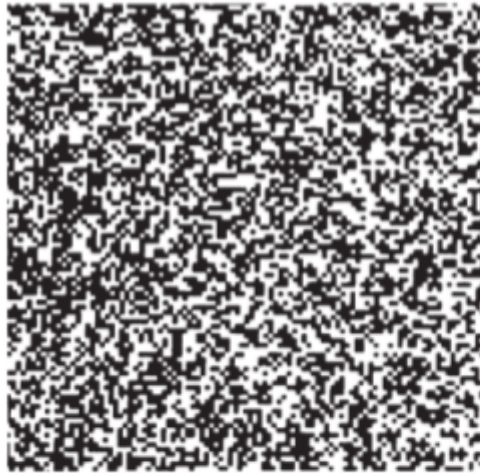
(b) Right eye image

# 3D Movies





# Random dot stereograms



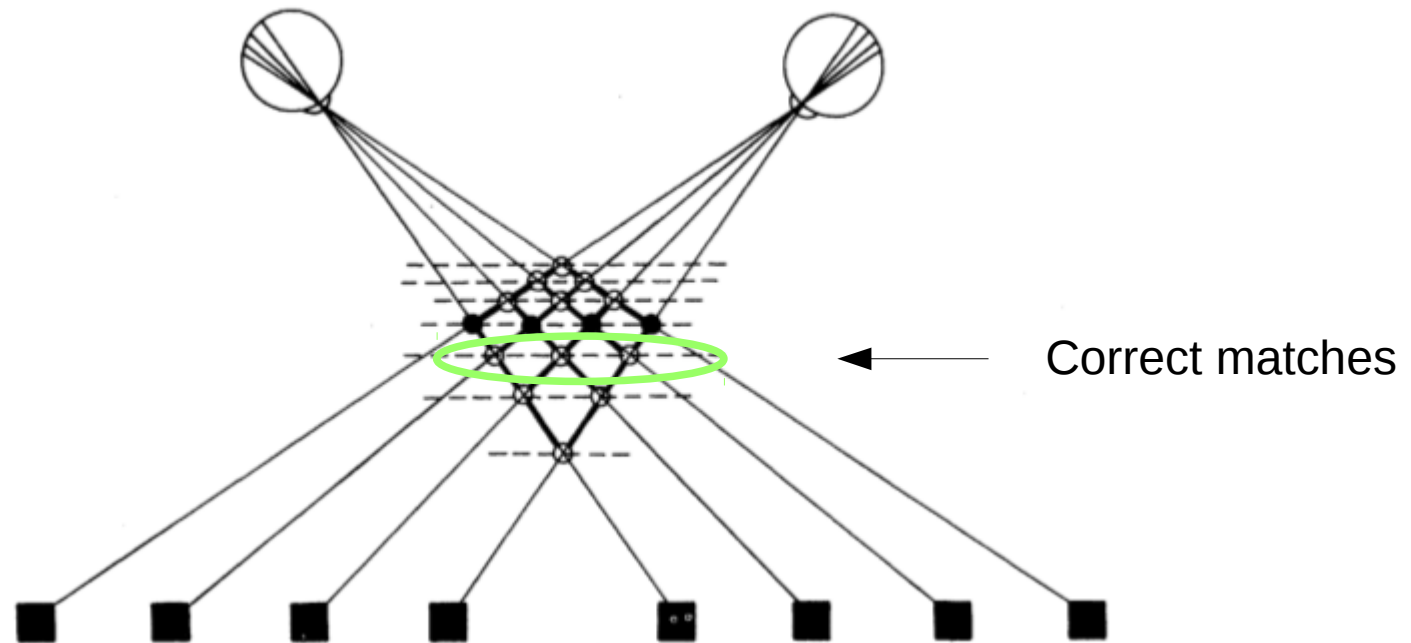
(a)

1	0	1	0	1	0	0	1	0	1
1	0	0	1	0	1	0	1	0	0
0	0	1	1	0	1	1	0	1	0
0	1	0	A	A	B	B	1	0	1
1	1	1	B	A	B	A	0	0	1
0	0	1	A	A	B	A	0	1	0
1	1	1	B	B	A	B	1	0	1
1	0	0	1	1	0	1	1	0	1
1	1	0	0	1	1	0	1	1	1
0	1	0	0	0	1	1	1	1	0

1	0	1	0	1	0	0	1	0	1
1	0	0	1	0	1	0	1	0	0
0	0	1	1	0	1	1	0	1	0
0	1	0	Y	A	A	B	B	0	1
1	1	1	X	B	A	B	A	0	1
0	0	1	X	A	A	B	A	1	0
1	1	1	Y	B	B	A	B	0	1
1	0	0	1	1	0	1	1	0	1
1	1	0	0	1	1	0	1	1	1
0	1	0	0	0	1	1	1	1	0

(b)

# The correspondence problem



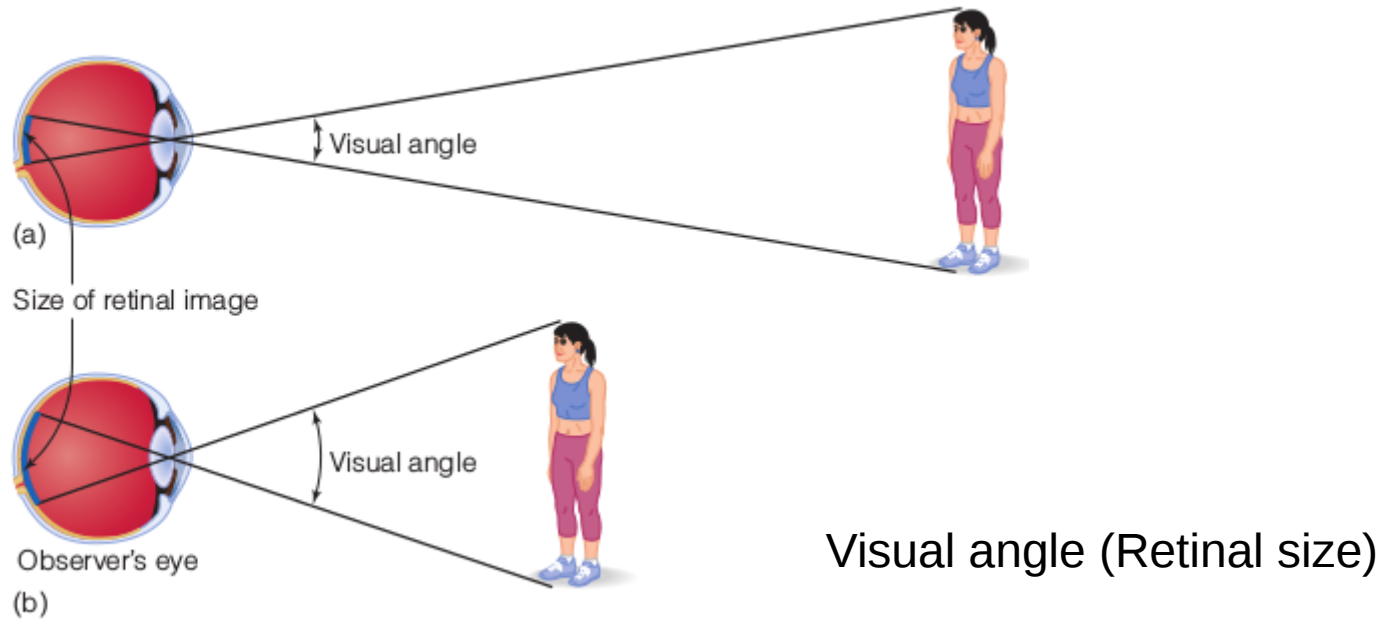
## *How to resolve ?*

- **Uniqueness:** Each image point represents a unique point in the real world
- **Continuity:** Cohesiveness of matter. Depth has discontinuity only at few places in an image

# More on uniqueness

- Cannot be established with gray levels alone
  - ➔ Intensity gradients
  - ➔ At multiple spatial resolution
  - ➔ Peaks of the first derivatives  $\equiv$  Zero crossings of the second derivatives

# Perception of size



Perceived size  $S \propto R * D$

R = Retinal size,  
D = Perceived distance

# Reference (close by objects)

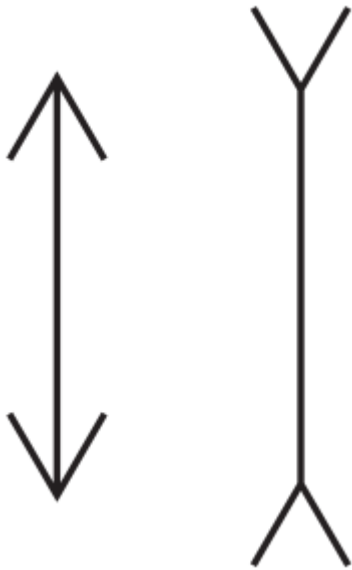


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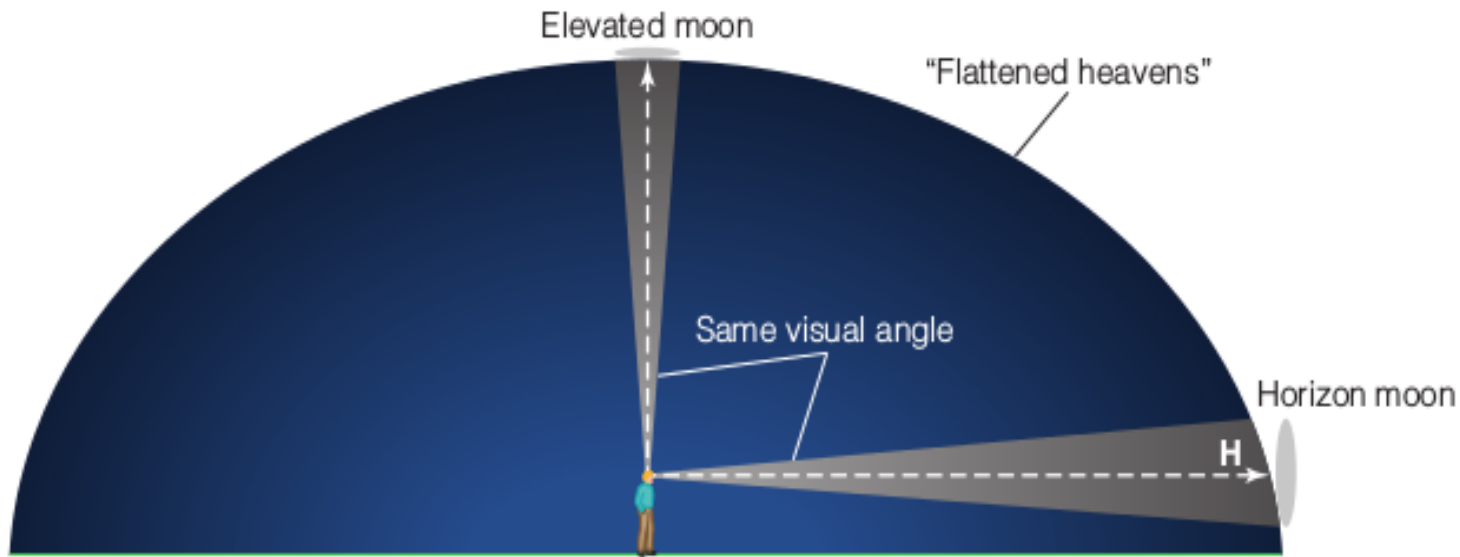
Bruce Goldstein

# Muller-Lyer illusion



Misapplied size constancy scaling

# Why the moon looks bigger near the horizon than when it is up in the sky?



*Flattened heaven theory*

## *Angular size contrast theory*

An object appears smaller when surrounded by larger objects

# References

1. Goldstein. Sensation and perception (e-book)  
<http://cartesians.biz/ctfile/sensation-and-perception-goldstein-9th-edition.pdf>

Perception of color, contrast, motion ...