

ELL 788  
Computational Perception & Cognition  
July – November 2015

**Module 3**

Cutaneous perception

*Which of the senses is the most important to you ?*

***Seeing ?***

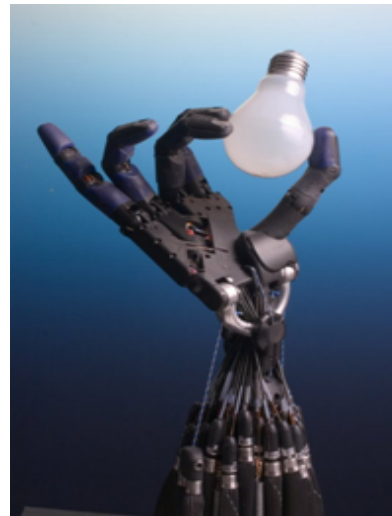
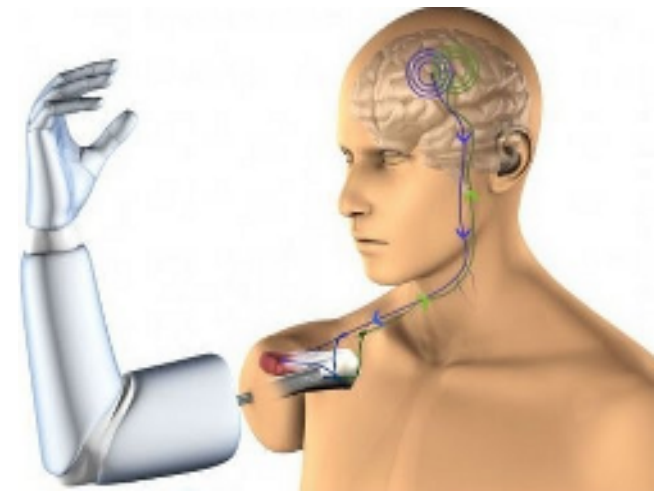
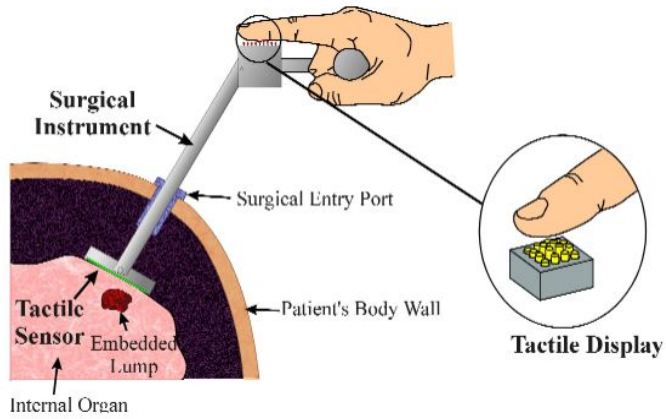
***Hearing ?***

***Touch ?***

***Which one is the least ?***

- A blind or a deaf man can live
- Have you ever seen a living man without a sense of touch ?

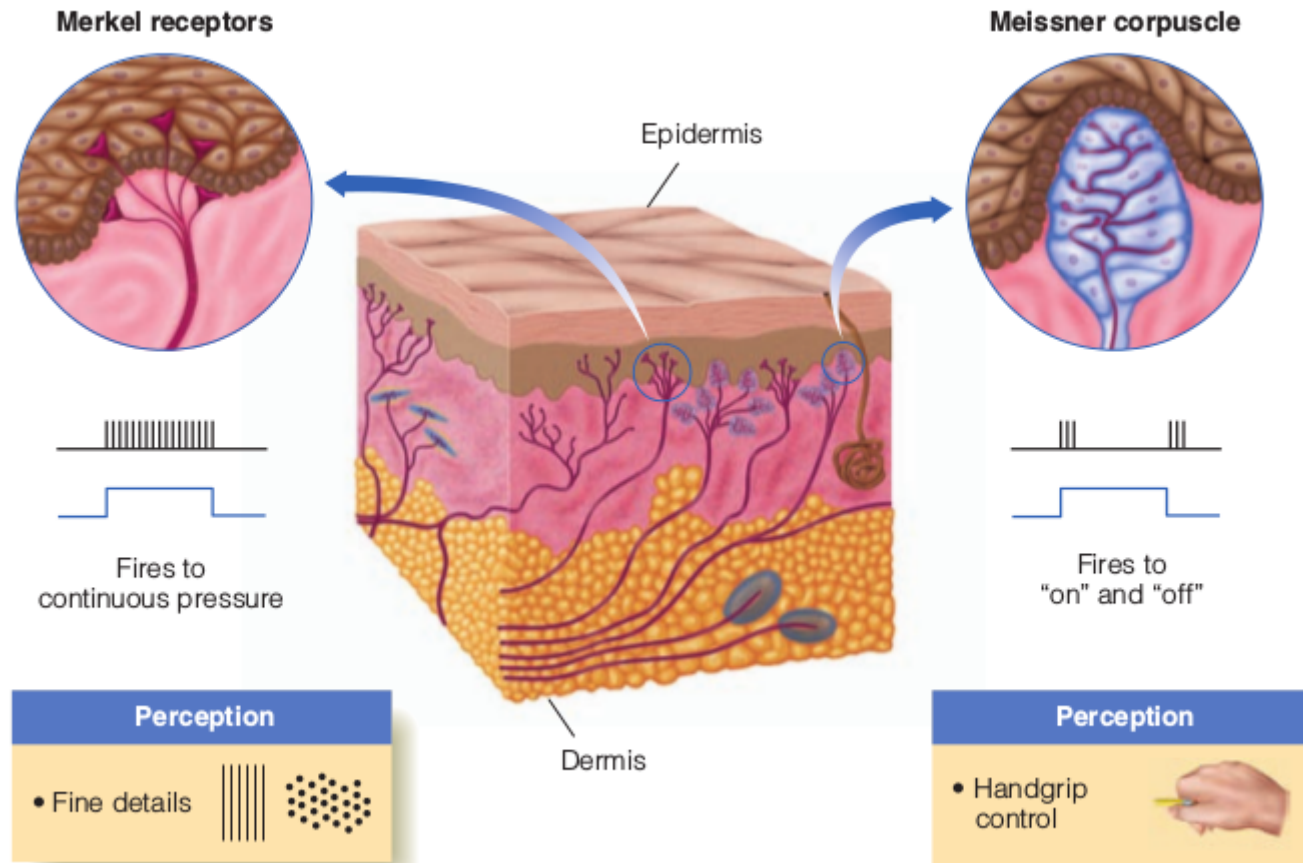
# Why study cutaneous perception ?



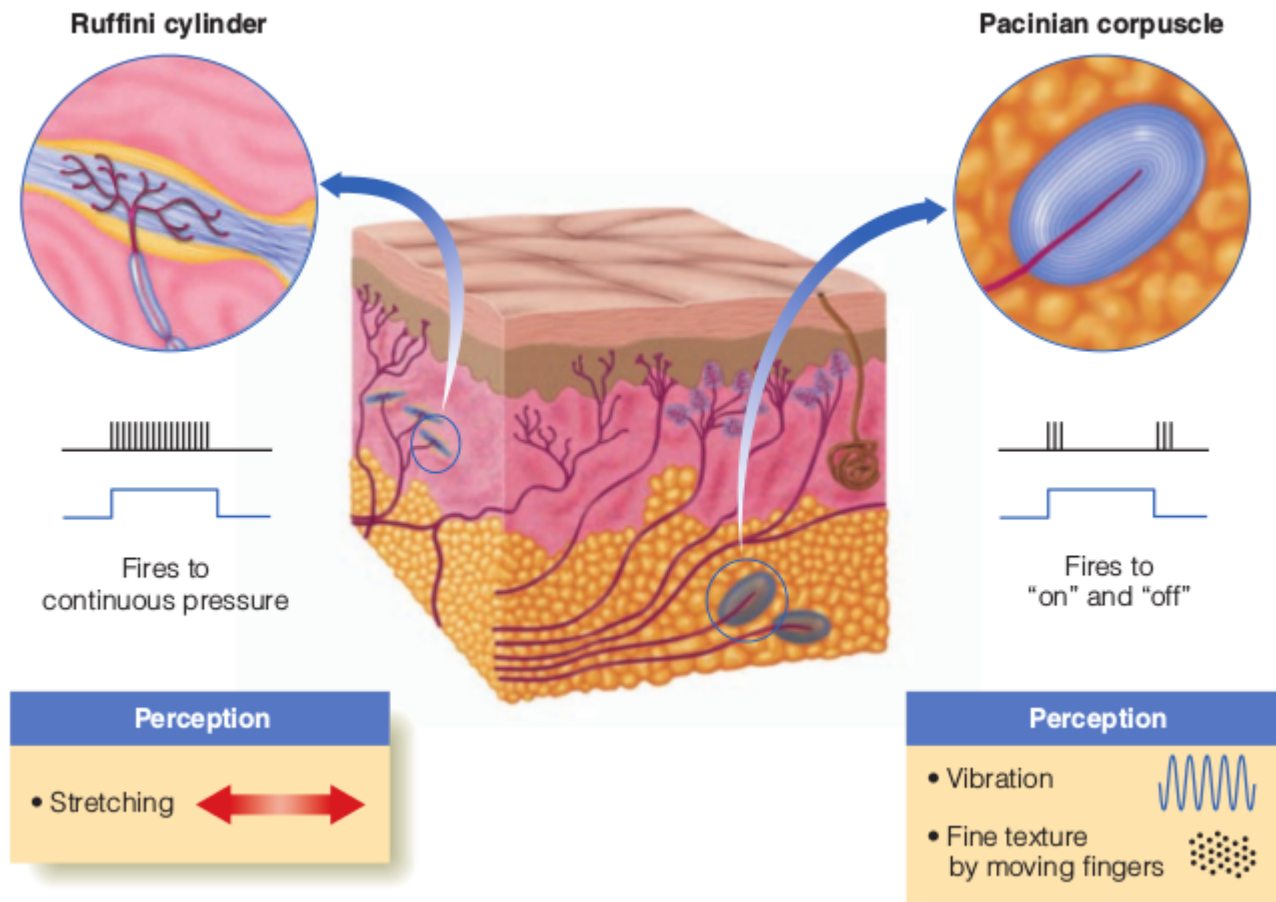
# Dimensions of cutaneous perception

- **What** (signal resolution)
  - Material properties (surface texture, softness)
  - Geometric properties (shape, size)
    - Depends on object sample
- **Where** (localization)
  - Where on the body
  - Where in the space
    - Exploring a dark room with hands and reconstructing the room geometry

# The human skin



# The human skin ... more



# Summary

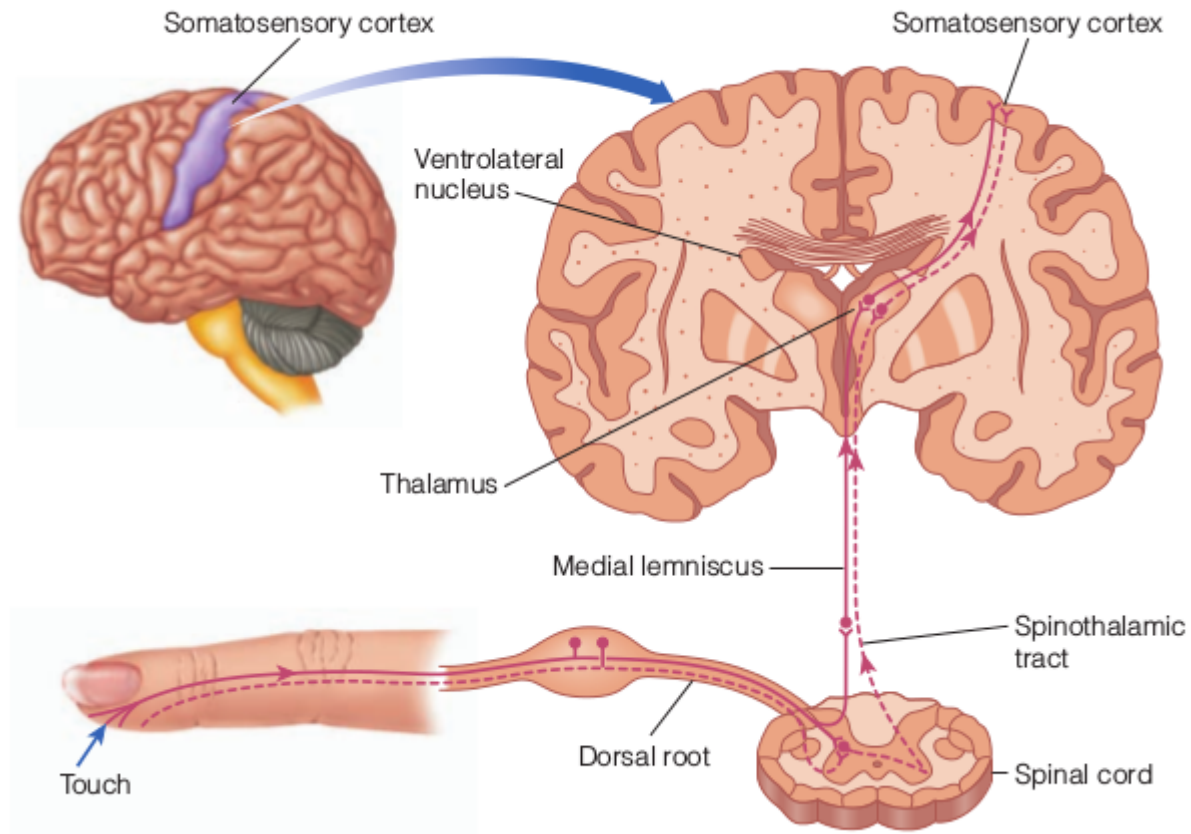
Neural Channel <sup>a</sup>	SA I (NP III)	RA (FA I, NP I)	SA II (NP II)	PC (FA II, P)
End Organ	Merkel Disk	Meissner Corpuscle	Ruffini Ending	Pacinian Corpuscle
Sensory Adaptation <sup>b</sup>	Slow	Fast	Slow	Fast
Receptive Field <sup>c</sup>	Small	Small	Large	Large
Frequency Range (Hz) <sup>d</sup>	< 5	3–100	15–400	10–500
Perceiving Property	Pressure, Fine Details	Flutter	Stretch	Vibration



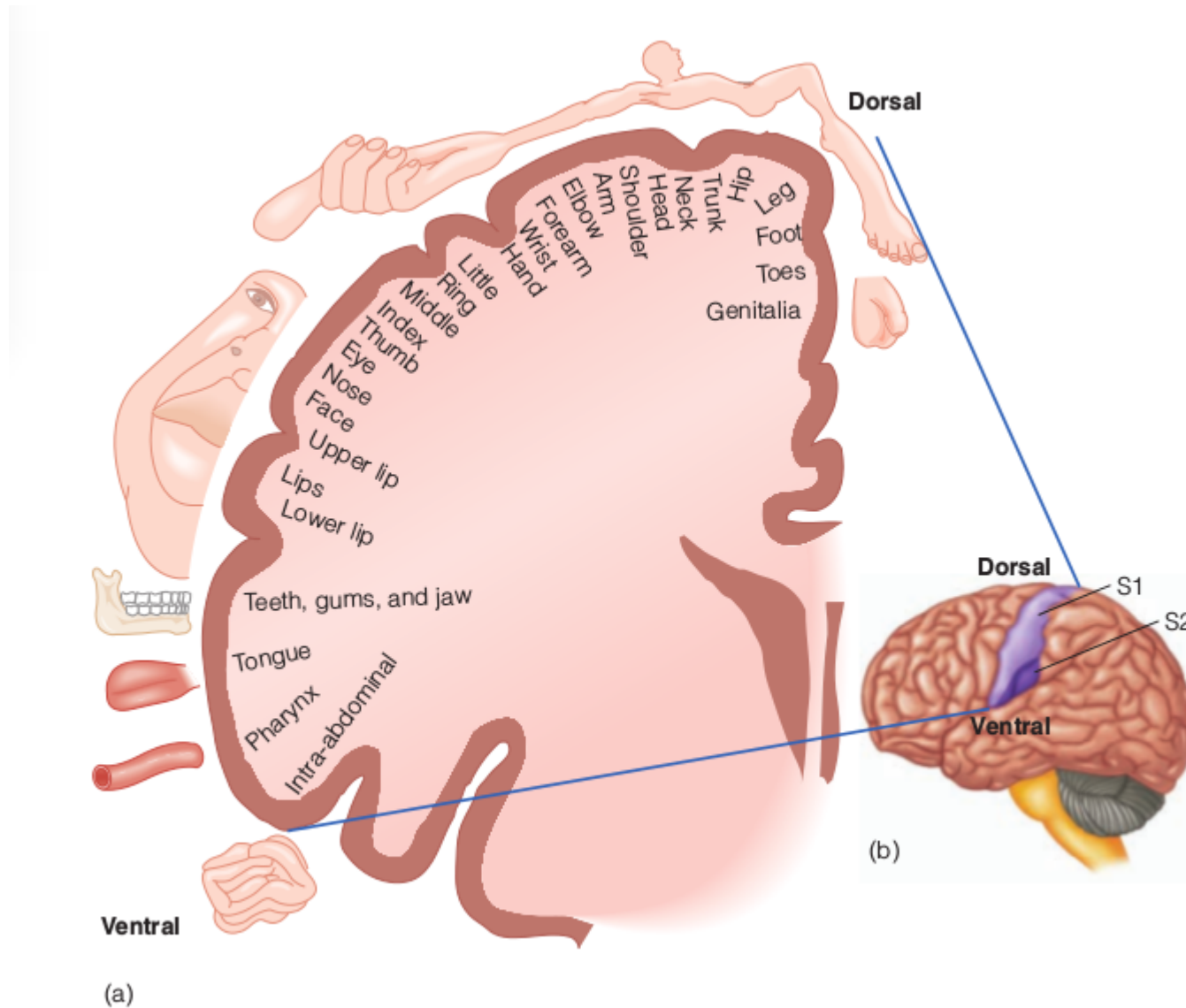
# Tactile and haptic perception

- Tactile (touch based)
  - Tactile feedback is when you outfit a robot with touch/force/torque sensors, and use those sensors to provide feedback to the human operator about real forces the robot experiences as it encounters its environment.
- Haptic (pressure based)
  - Haptic feedback imparts forces on the operator, for instance by using a mechanically actuated joystick or other hand controller.

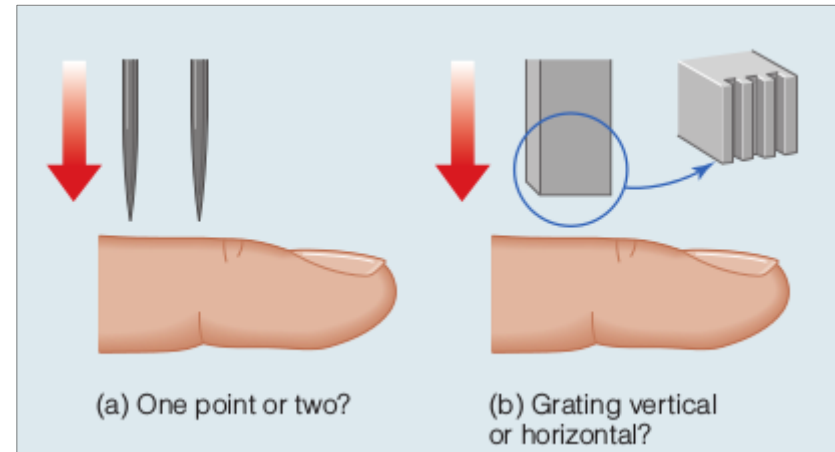
# Pathway to the brain



# Mapping of the body in brain

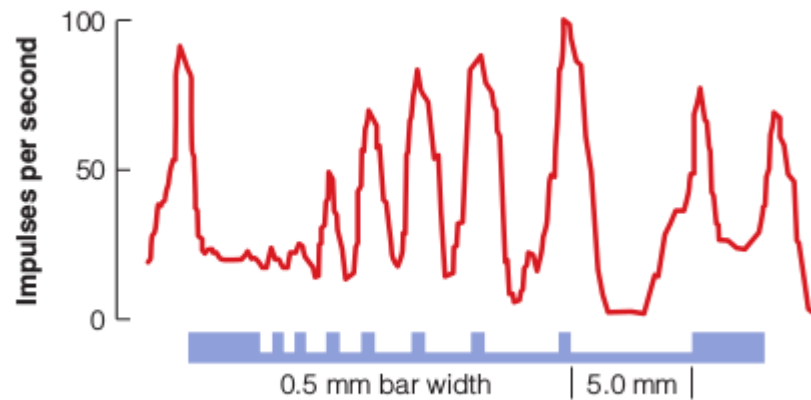


# Spatial resolution

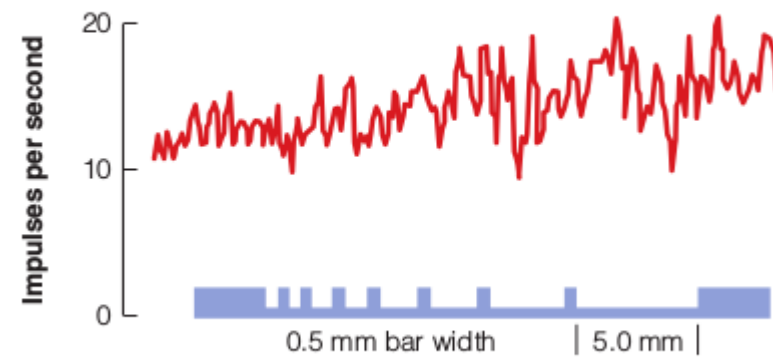


- Two point touch threshold
  - The smallest spatial separation between two stimuli applied to the skin that can be detected some arbitrary percentage of the time (e.g., 75%).
  - Whether a linear grating is applied horizontally or vertically
- Point localization threshold
  - A stimulus is presented to the skin, followed in time by a second stimulus that may or may not be applied to the same site.

# Resolution by mechanoreceptors

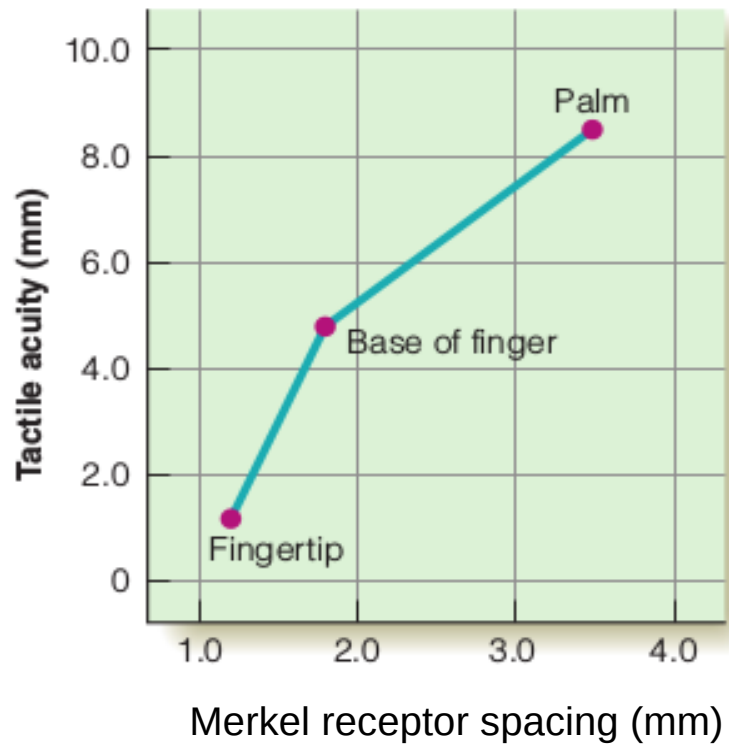


(a) Merkel/SA1



(b) Pacinian/RA2

# Tactile acuity: Mechanoreceptor density

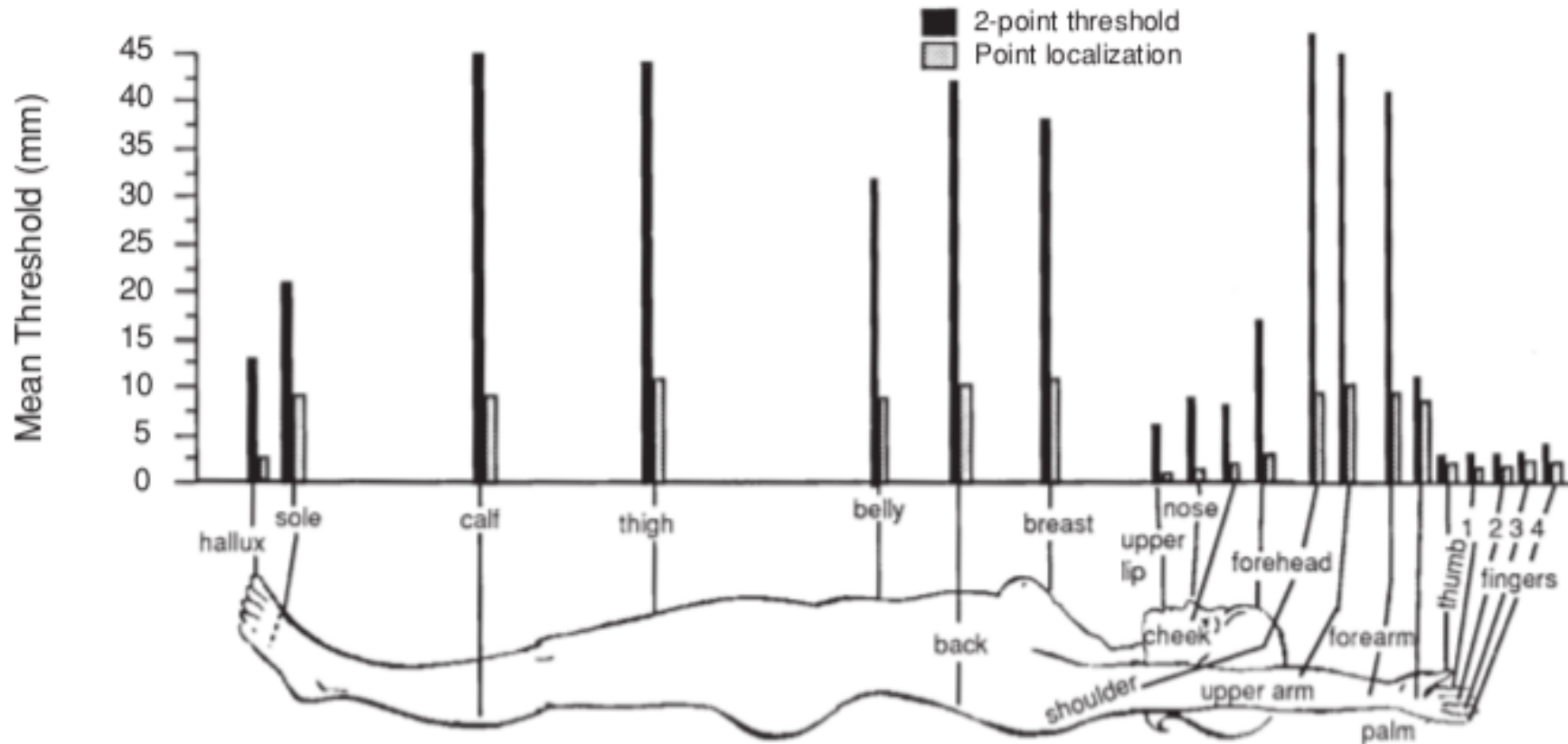


Cortical magnification also plays a role

# Observations

- Two point thresholds are  $\sim 4 - 45$  mm
  - With grating experiments, they are lower
- Localization thresholds are  $\sim 2 - 12$  mm
  - Much smaller than two point thresholds
- Thresholds varies with part of the body
  - Lower on fingertips, nose, lips ...
  - Higher on back, chest, belly, forearm, thigh ...
  - Shows consistent pattern on male and female bodies
- The spatial resolving power of the skin is poorer than the eye's but better than the ear's.

# Resolution at different parts of human body



Source: *L ederman and Klatzky*

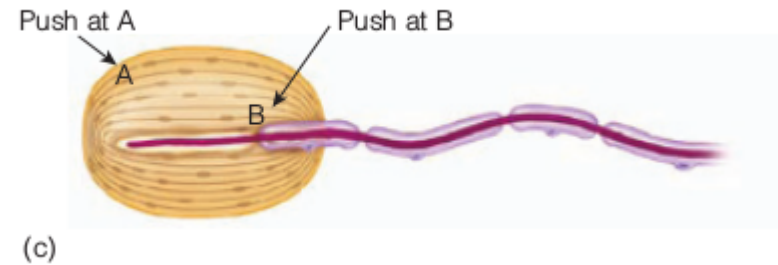
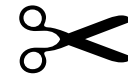
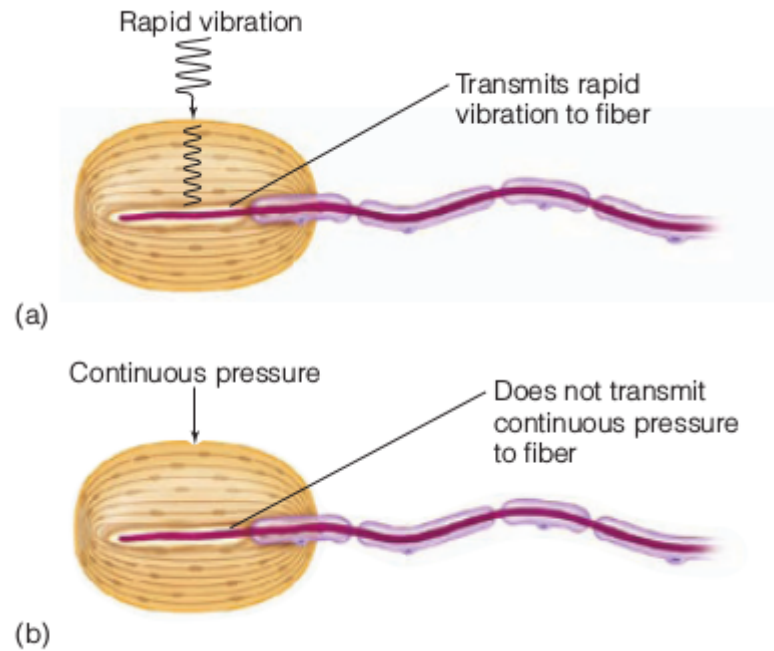
- Shows consistent pattern on male and female bodies



# Temporal resolution

- People can resolve a temporal gap of 5 msec between successive taps on the skin
- The temporal resolving power of the skin is better than that of vision, but worse than that of audition

# Perceiving vibration



Pacinian corpuscles

# Perceiving texture coarseness of surface

- Perception of texture depends on

*Katz 1925*

- Spatial cues

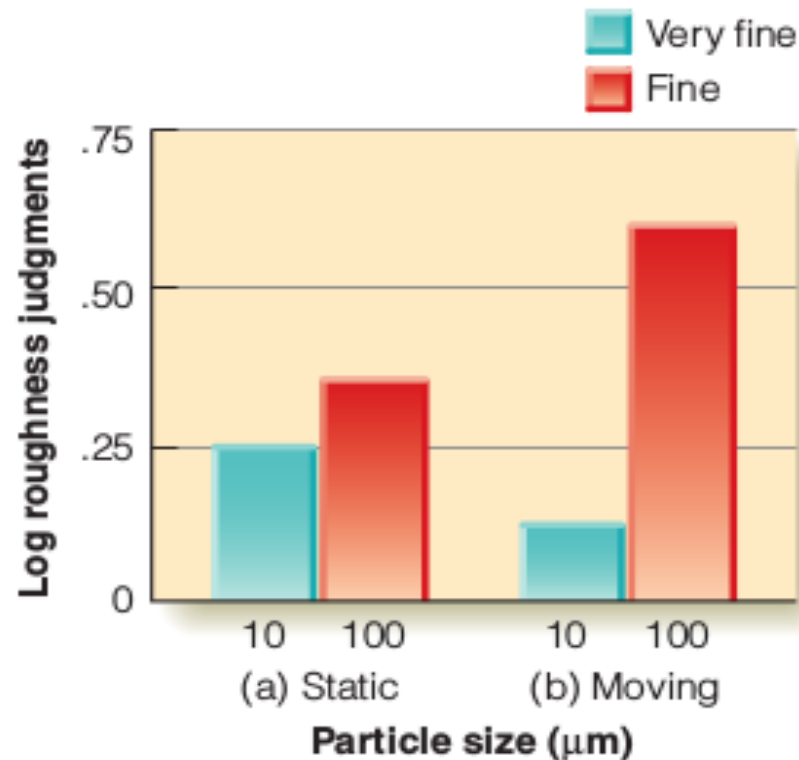
- Large surface elements, e.g. a protrusion / a groove
- Useful for perceiving shape / size, Braille dots
- When skin presses against the surface (pressure)

- Temporal cues

- Coarse surface, e.g. sandpaper, fabric
- When skin moves over the surface (vibration)

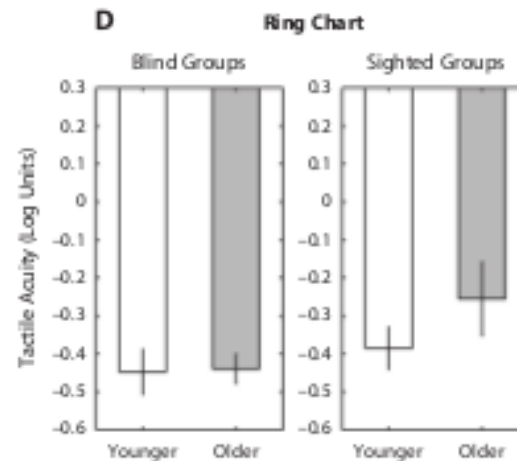
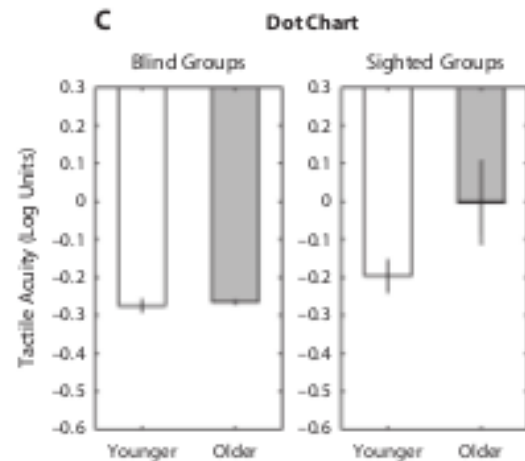
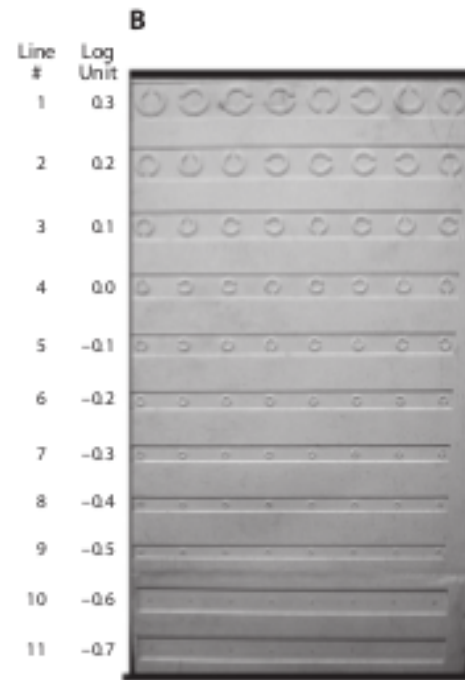
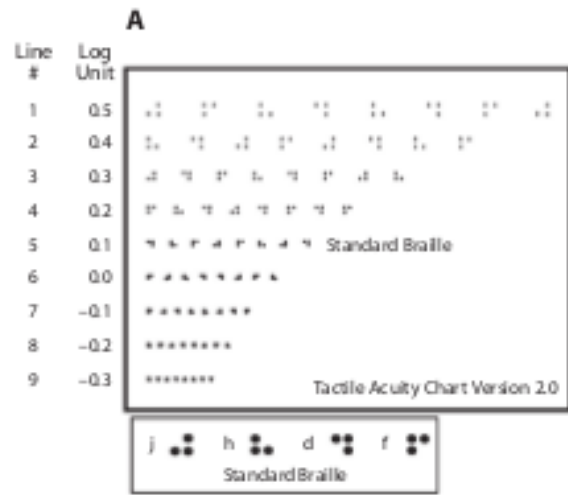
# Perceiving texture ... more

- Experimentation on temporal cues



*Hollins and Reisner 2000*

# Surface Texture: age, disability and perception



Source:  
Lederman and Klatzky

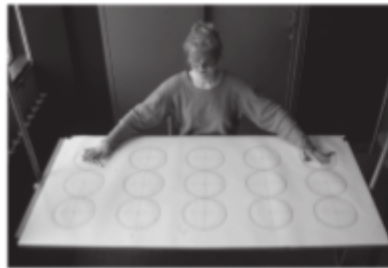
# Perceiving orientation

- Horizontal / Vertical orientations are easier to compare (perceptually) than oblique ones
  - Two frames of reference (body and space) – more computation
  - Depends on position with respect to the body

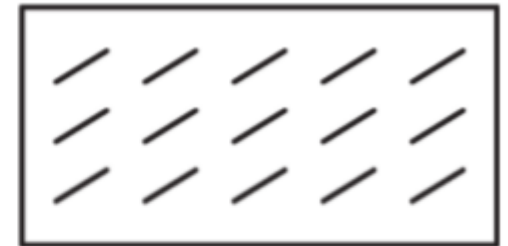
Source:  
*Lederman and Klatzky*

- Vertical lengths are assessed longer than vertical ones
- Distances away from the body are assessed longer than the tangential direction

A



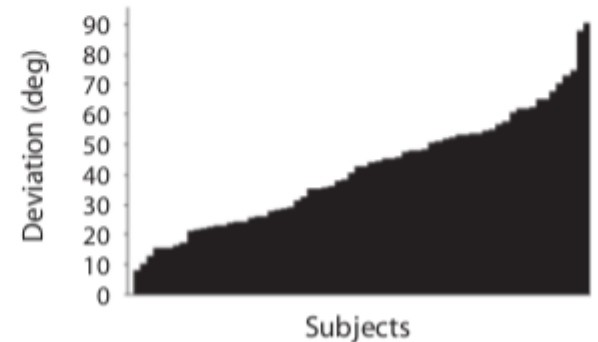
B



C



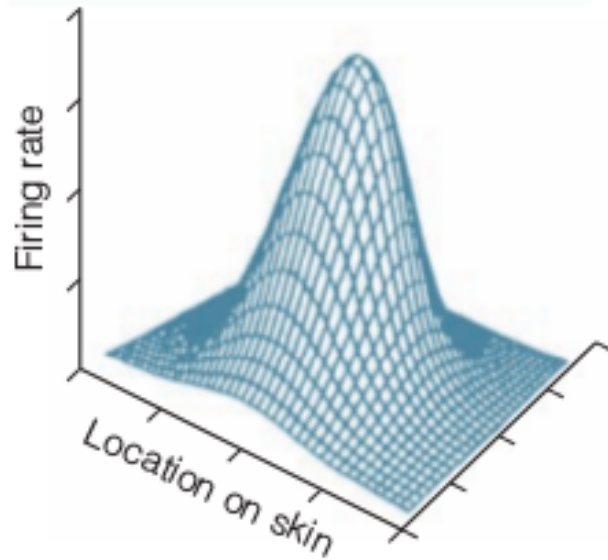
D



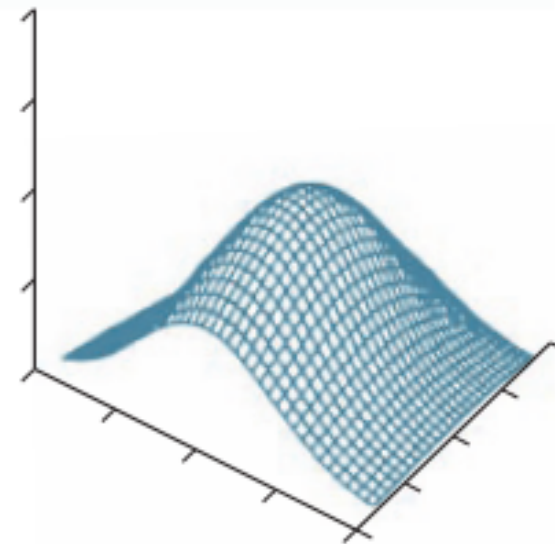
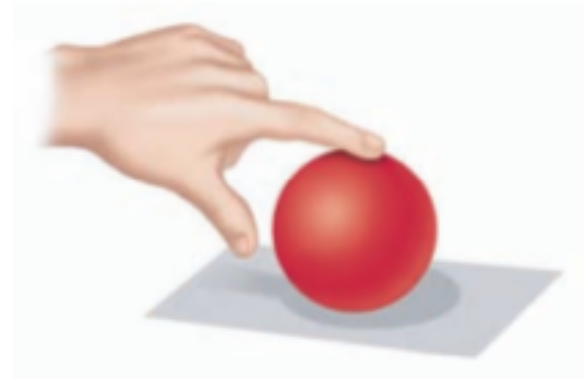
# Geometric properties (size and shape)

- Small objects (Fits on a finger-tip)
  - Local indentation on skin reveals shape
- Bigger objects
  - Both cutaneous and kinesthetic inputs (mechanoreceptors)
  - Varying local pressure on skin → curvature
- Perception depends on
  - Convex or concave
  - Position of stimulus on hand
  - Movement of hand over the surface ...

# Perception of curvature



(a)



(b)



# Perceiving objects

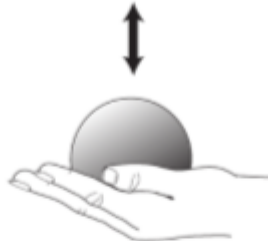
- Most of the everyday use objects can be identified with touch
  - The great grand-mother who has lost her eyesight can do a 'face recognition' with her fingers.
- Most of the research so far has centered around passive touch
  - Not active exploration

# Exploratory processes

**Lateral Motion  
(Texture)**



**Unsupported Holding  
(Weight)**



**Pressure  
(Hardness)**



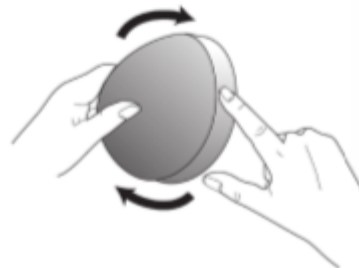
**Enclosure  
(Global Shape)  
(Volume)**



**Static Contact  
(Temperature)**



**Contour Following  
(Global Shape)  
(Exact Shape)**

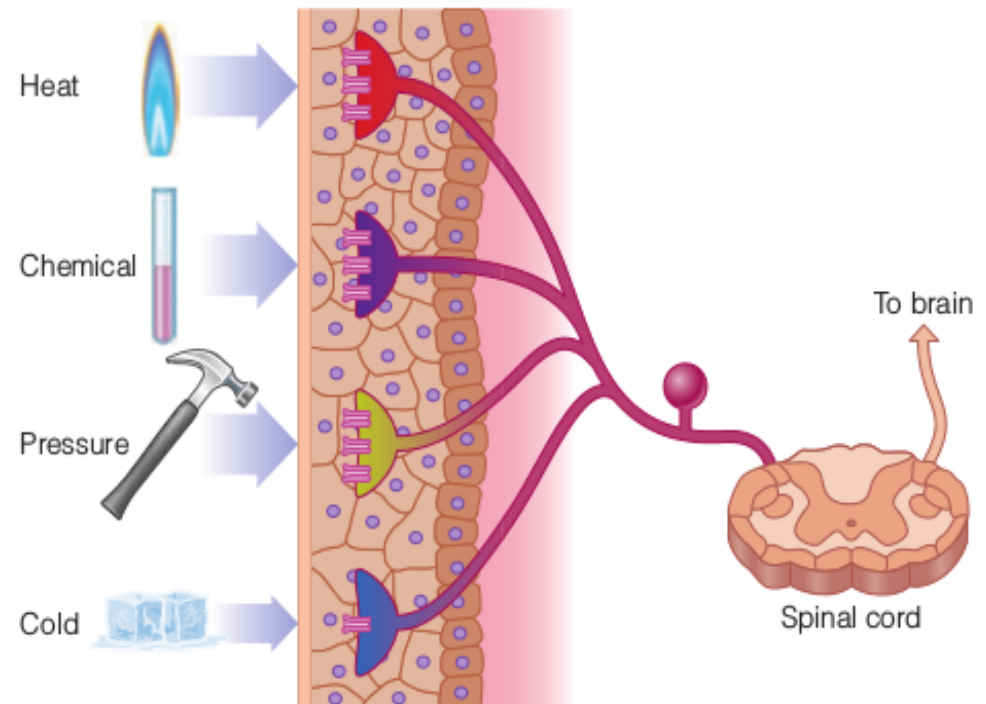


- Time to execute
- Capability
- Accuracy

Source:  
*Lederman and Klatzky*

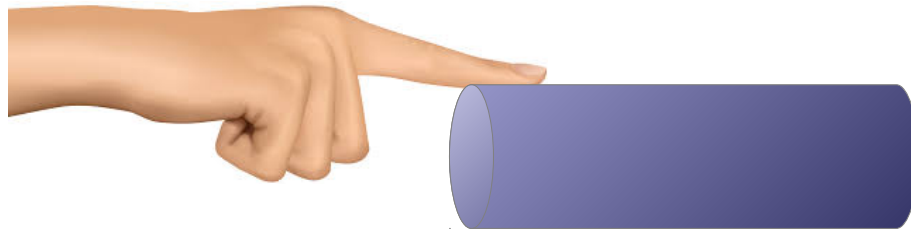
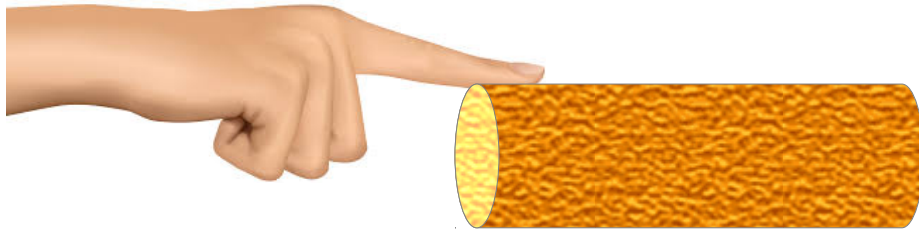
# Feeling the pain

- **Nociceptive pain**
  - Caused by activation of receptors in the skin called nociceptors.
- **Inflammatory pain**
  - Caused by damage to tissues and inflammations to joints or by tumor cells.
- **Neuropathic pain**
  - Caused by lesions or other damage to the nervous system.



*Perception of pain depends on mental state of a person.*

# Perceiving material



*Thermal cue: The rate of heat dissipation*

# ***WEBER LAW / WEBER-FECHNER LAW: A Computational Model of perception***

*Can the user distinguish between the different vibrotactile cues being displayed?*

Relationship between the physical magnitude of a stimulus and its (subjectively) perceived intensity

- The minimum change in a stimulus that can be detected is proportional to the current value of the stimulus

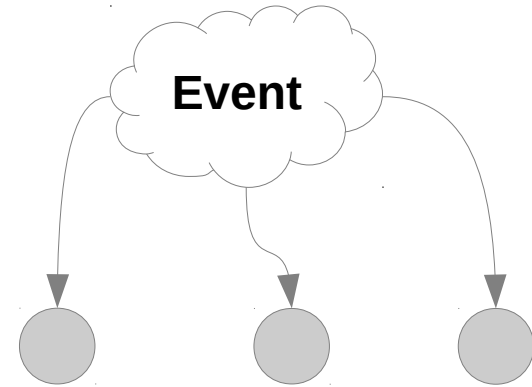
$$\Delta p = k \frac{\Delta S}{S} \quad \frac{dp}{dS} = k \frac{1}{S} \quad p = k \log S + C \quad k = \text{Weber fraction}$$

- To solve for C

$$0 = k \log S_0 + C \quad [\text{Threshold stimulus}] \quad p = k \log \frac{S}{S_0}$$

- Subjective sensation is proportional to the logarithm of the stimulus intensity, measured in proportion to threshold stimulus
- **Holds for all modalities – visual, audio, haptics (approximately)**

# Multimodal perception



- Supportive / contradictory signals
- Combining
  - Weighted sum
  - Expectation maximization

# Higher level interactions



# References

- Goldstein (e-book)
- MacLean. Haptic Interaction Design for Everyday Interfaces (chapter)  
<http://web.stanford.edu/class/me327/readings/1-MacLean08-RHFE-Design.pdf>
- Lederman and Klatzky: Haptic perception: A tutorial.  
<http://www.queensu.ca/psychology/lederman/Publications/175.pdf>