

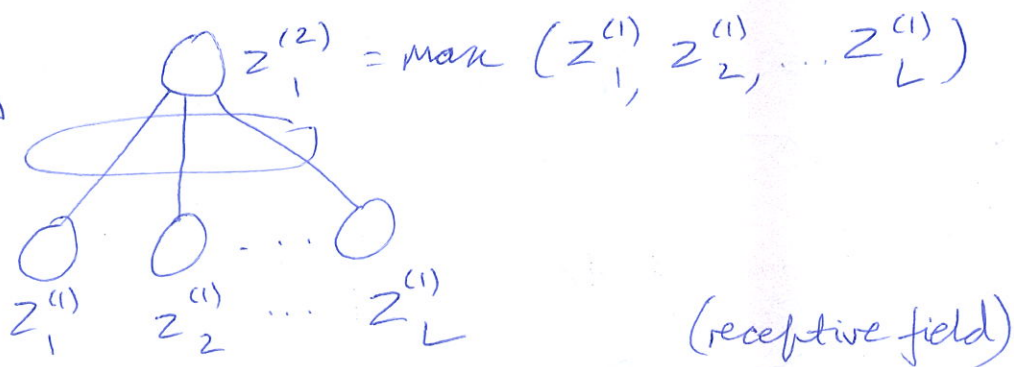
3.10.17.

Summit Aground

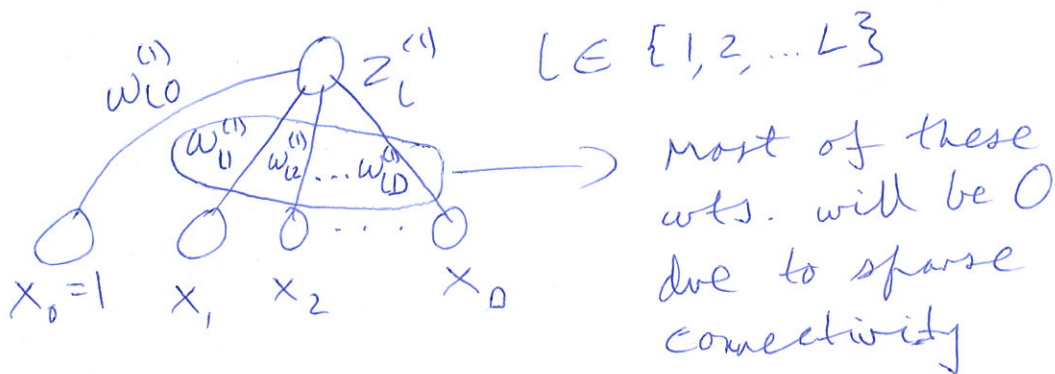
ELL784 : Notes on Backprop with Max Pooling

Consider a Max Pooling unit $z_1^{(2)}$, which is pooling over a bunch of feature map units denoted $z_1^{(1)}, z_2^{(1)}, \dots, z_L^{(1)}$

NB: These links don't have 'weights'



Note that each feature map unit z_l will in turn look like the below:



In this whole derivation $\sigma(\cdot)$ could be replaced by any activation fn. $h(\cdot)$

Formally, we have $z_l^{(1)} = \sigma(a_l^{(1)})$

$$\text{where } a_l^{(1)} = \sum_{i=0}^D w_{li}^{(1)} x_i = \sum_{i \in R_l} w_{li}^{(1)} x_i$$

Here R_l denotes the receptive field for $z_l^{(1)}$, i.e., the set of input units it is connected to.

(Assume all $z_l^{(1)}$ connect to $x_0=1$)

Now, suppose we wish to compute a partial derivative like

$$\frac{\partial E(w)}{\partial w_{li}^{(1)}} \quad \left[\begin{array}{l} \text{Assume } i \in R_L, \text{ otherwise} \\ w_{li}^{(1)} = 0 \text{ by defn.} \end{array} \right]$$

The usual chain rule process gives us:

$$\frac{\partial E(w)}{\partial w_{li}^{(1)}} = \frac{\partial E(w)}{\partial a_l^{(1)}} \cdot \frac{\partial a_l^{(1)}}{\partial w_{li}^{(1)}} = x_i$$

So we need to get $S_l^{(1)}$ to compute this. This needs to come via backpropagation, as for all 'hidden' units where there's no direct way to define 'error'.

$$S_l^{(1)} = \frac{\partial E(w)}{\partial a_l^{(1)}} = \frac{\partial E(w)}{\partial z_l^{(2)}} \cdot \frac{\partial z_l^{(2)}}{\partial z_l^{(1)}} \cdot \frac{\partial z_l^{(1)}}{\partial a_l^{(1)}} = \sigma'(a_l^{(1)})$$

(Here I am proceeding as if $z_l^{(2)}$ is the only pooling unit to which $z_l^{(1)}$ connects. If there are others, we would get a summation as before. But note that pooling IS normally applied to non-overlapping regions of a feature map.)

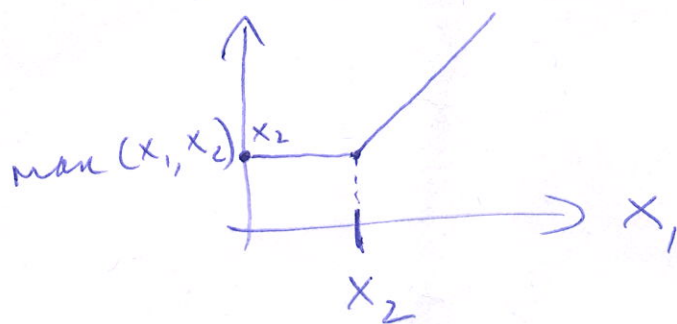
So we have

$$S_L^{(1)} = S_L^{(2)} \cdot \left(\frac{\partial z_1^{(2)}}{\partial z_L^{(1)}} \right) \cdot \sigma'(a_L^{(1)})$$

The first term is from backprop. above $z_1^{(2)}$.
So only the middle term needs to be obtained. This is:

$$\frac{\partial}{\partial z_L^{(1)}} \max(z_1^{(1)}, z_2^{(1)}, \dots, z_L^{(1)})$$

In general the $\max()$ fn. is not differentiable everywhere. But it is actually differentiable at most points. Consider the following:



(Here x_2 is taken fixed.)

$$\text{For } x_1 < x_2, \quad \frac{\partial \max(x_1, x_2)}{\partial x_1} = 0$$

$$\text{For } x_1 > x_2, \quad \frac{\partial \max(x_1, x_2)}{\partial x_1} = 1$$

The problem arises only at $x_1 = x_2$

So, coming back to $\max(z_1^{(1)}, z_2^{(1)}, \dots, z_L^{(1)})$,
 we can actually differentiate it, as
 long as we assume that no two _(or more) of
 its arguments have the same value which
 is also the maximum value. In this
 case, we have a unique maximum:

$$l_{\max} \triangleq \underset{L}{\operatorname{argmax}} z_l^{(1)}, \quad l \in \{1, \dots, L\}$$

And we thus have

$$\frac{\partial}{\partial z_l^{(1)}} \max(z_1^{(1)}, z_2^{(1)}, \dots, z_L^{(1)})$$

$$= \begin{cases} 1; & \text{if } l = l_{\max} \\ 0; & \text{otherwise} \end{cases}$$

This in turn gives us:

$$s_l^{(1)} = \begin{cases} s_1^{(2)} \cdot \sigma'(a_l^{(1)}); & l = l_{\max} \\ 0; & \text{otherwise} \end{cases}$$

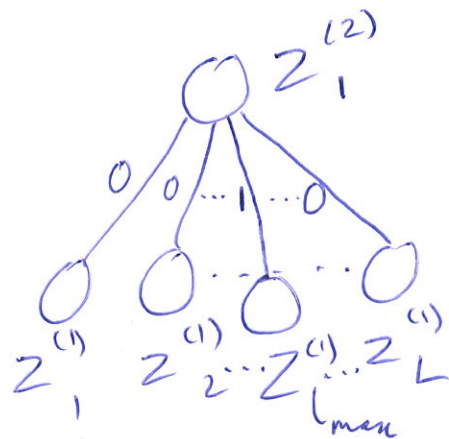
So we have all we need to compute any

$$\frac{\partial E(w)}{\partial w_{li}^{(1)}}$$

Notice that the entire error at $z_1^{(2)}$ is being propagated back to just a single unit in the layer below: $z_{L_{max}}^{(1)}$.

This is intuitively reasonable: For the current setting of the weights, $z_{L_{max}}^{(1)}$ is the controlling unit for $z_1^{(2)}$, and no other unit has an effect on it.

There is another way to think of this. Although we said that a MaxPooling unit has no 'weights', supposing we were to write it out as if it did, we can do that as follows:



i.e., all wts. are 0 except for $z_{L_{max}}^{(1)}$

If we imagine these 'weights' and apply the normal backprop principle (propagate the error back along each link, multiplying by its weight), we get the same thing as above!